

LV 706.046 Summer Term 2019
Monday, March, 11

Introduction and Overview From measuring Usability to measuring Causability

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<https://hci-kdd.org/intelligent-user-interfaces-2019>



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Image by Randall Munroe <https://xkcd.com>

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- 01 The HCI-KDD approach: integrative ML
- 02 Application Area: Health
- 03 Probabilistic Learning
- 04 aML
- 05 iML
- 06 Causality and Causability
- 07 Measuring Causality?
- Our Goal for this semester: design develop & test a System Causability Scale

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01 What is the HCI-KDD approach?

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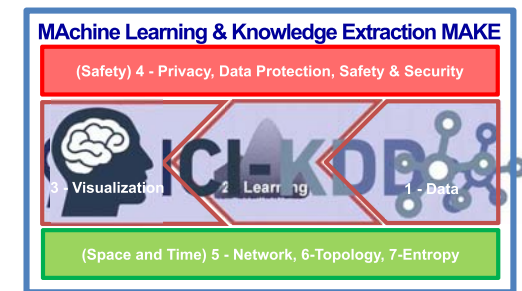
- ML is a very practical field – algorithm development is at the core – however, successful ML needs a concerted effort of various topics ...



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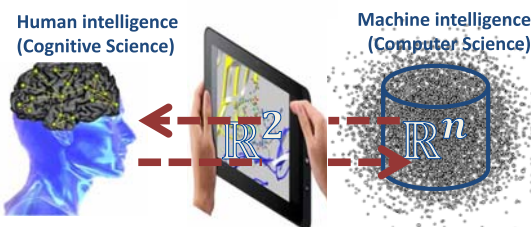


Andreas Holzinger 2017. Introduction to Machine Learning and Knowledge Extraction (MAKE). *Machine Learning and Knowledge Extraction*, 1, (1), 1-20, doi:10.3390/make1010001.

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Holzinger, A. (2013). Human-Computer Interaction & Knowledge Discovery (HCI-KDD): What is the benefit of bringing those two fields to work together? In: Lecture Notes in Computer Science 8127 (pp. 319-328)

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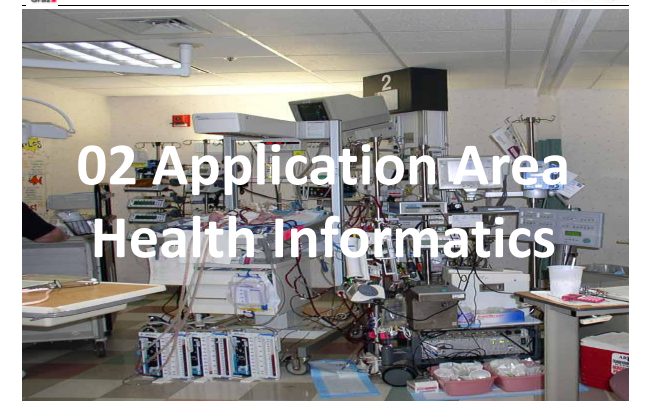
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- 1) **learn** from prior data
- 2) **extract** knowledge
- 2) **generalize**, i.e. guessing where a probability mass function concentrates
- 4) fight the curse of **dimensionality**
- 5) **disentangle** underlying explanatory factors of data, i.e.
- 6) **understand** the data in the **context** of an application domain

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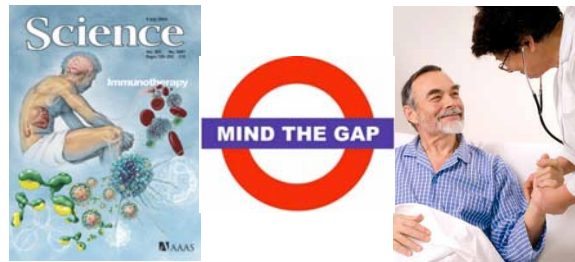
02 Application Area Health Informatics

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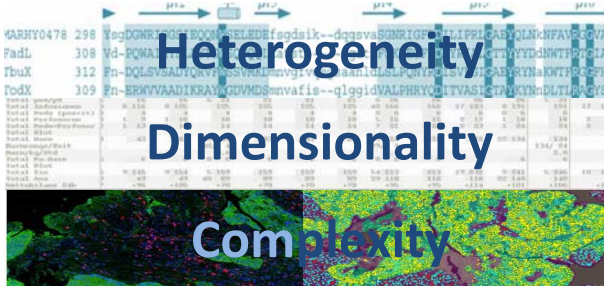
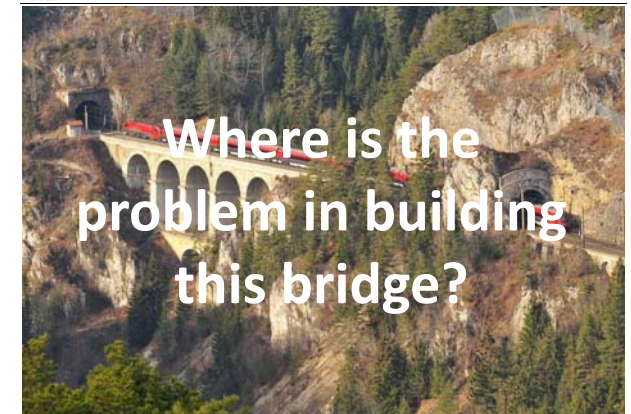
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Why is this application area complex ?



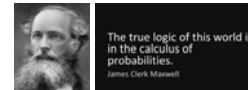
Our central hypothesis: Information may bridge this gap

Holzinger, A. & Simon, K.-M. (eds.) 2011. *Information Quality in e-Health. Lecture Notes in Computer Science LNCS 7058, Heidelberg, Berlin, New York: Springer.*

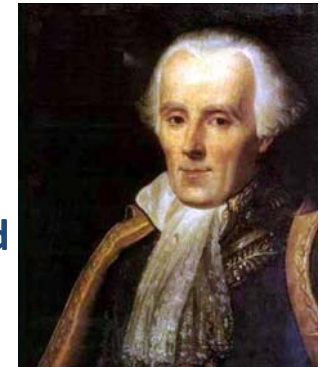


Holzinger, A., Dehmer, M. & Jurisica, I. 2014. Knowledge Discovery and interactive Data Mining in Bioinformatics - State-of-the-Art, future challenges and research directions. *BMC Bioinformatics*, 15, (S6), 11.

03 Probabilistic Learning



Probability theory is nothing but common sense reduced to calculation ...



Pierre Simon de Laplace (1749-1827)



- Newton, Leibniz, ... developed calculus – mathematical language for describing and dealing with rates of change
- Bayes, Laplace, ... developed probability theory - the mathematical language for describing and dealing with uncertainty
- Gauss generalized those ideas

What is the simplest mathematical operation for us?

$$p(x) = \sum_y p(x, y) \quad (1)$$

How do we call repeated adding?

$$p(x, y) = p(y|x) * p(x) \quad (2)$$

Laplace (1773) showed that we can write:

$$p(x, y) * p(y) = p(y|x) * p(x) \quad (3)$$

Now we introduce a third, more complicated operation:

$$\frac{p(x, y) * p(y)}{p(y)} = \frac{p(y|x) * p(x)}{p(y)} \quad (4)$$

We can reduce this fraction by $p(y)$ and we receive what is called Bayes rule:

$$p(x, y) = \frac{p(y|x) * p(x)}{p(y)} \quad p(h|d) = \frac{p(d|h)p(h)}{p(d)} \quad (5)$$

$$p(x_i) = \sum P(x_i, y_j)$$

$$p(x_i, y_j) = p(y_j|x_i)P(x_i)$$

Bayes, T. (1763). An Essay towards solving a Problem in the Doctrine of Chances (Postum communicated by Richard Price). *Philosophical Transactions*, 53, 370-418.

Bayes' Rule is a corollary of the Sum Rule and Product Rule:

$$p(x_i|y_j) = \frac{p(y_j|x_i)p(x_i)}{\sum p(x_i, y_j)p(x_i)}$$

$$P(\text{hypothesis}|\text{data}) = \frac{P(\text{hypothesis})P(\text{data}|\text{hypothesis})}{\sum_h P(h)P(\text{data}|h)}$$

$$P(\theta|\mathcal{D}, m) = \frac{P(\mathcal{D}|\theta, m)P(\theta|m)}{P(\mathcal{D}|m)}$$

Barnard, G. A., & Bayes, T. (1958). Studies in the history of probability and statistics: IX. Thomas Bayes's essay towards solving a problem in the doctrine of chances. *Biometrika*, 45(3/4), 293-315.

We need ...

$P(\mathcal{D}|\theta, m)$ likelihood of parameters θ in model m
 $P(\theta|m)$ prior probability of θ
 $P(\theta|\mathcal{D}, m)$ posterior of θ given data $\mathcal{D}$

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Bayesian Learning from data

$$\mathcal{D} = x_{1:n} = \{x_1, x_2, \dots, x_n\}$$

$$p(\mathcal{D}|\theta)$$

$$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta) * p(\theta)}{p(\mathcal{D})}$$

posterior = $\frac{\text{likelihood} * \text{prior}}{\text{evidence}}$

The inverse probability allows to learn from data, infer unknowns, and make predictions

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Learning and Inference

$d \dots \text{data}$
 $h \dots \text{hypotheses}$
 $\mathcal{H} \dots \{H_1, H_2, \dots, H_n\} \quad \forall h, d \dots$

Likelihood: $p(d|h)$
 Prior Probability: $p(h)$
 Posterior Probability: $p(h|d) = \frac{p(d|h) * p(h)}{\sum_{h \in \mathcal{H}} p(d|h) p(h)}$

Problem in $\mathbb{R}^n \rightarrow$ complex

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Connection to Cognitive Science: Decision Making

$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta) * p(\theta)}{p(\mathcal{D})}$

Wickens, C. D. (1984) Engineering psychology and human performance. Columbus (OH), Charles Merrill, modified by Holzinger, A.

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Scaling to high-dimensions is the holy grail in ML

Wang, Z., Hutter, F., Zoghi, M., Matheson, D. & De Freitas, N. 2016. Bayesian optimization in a billion dimensions via random embeddings. Journal of Artificial Intelligence Research, 55, 361-387, doi:10.1613/jair.4806.

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GP = distribution, observations occur in a cont. domain, e.g. t or space

$p(f(x)|\mathcal{D}) \propto p(\mathcal{D}|f(x)) p(f(x))$

GP posterior, Likelihood, GP prior

Brochu, E., Cora, V. M. & De Freitas, N. 2010. A tutorial on Bayesian optimization of expensive cost functions, with application to active user modeling and hierarchical reinforcement learning. arXiv:1012.2599.

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Goal: Reduce uncertainty by learning representations

$\mathbb{E}[f] = \int p(x) f(x) dx$
 $\mathbb{E}[f] \simeq \frac{1}{N} \sum_{n=1}^N f(x_n)$

Holzinger, A. 2017. Introduction to Machine Learning and Knowledge Extraction (MAKE). Machine Learning and Knowledge Extraction, 1, (1), 1-20, doi:10.3390/make1010001.

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Bayesian Optimization 1

pred var, pred mean, truth, evaluations

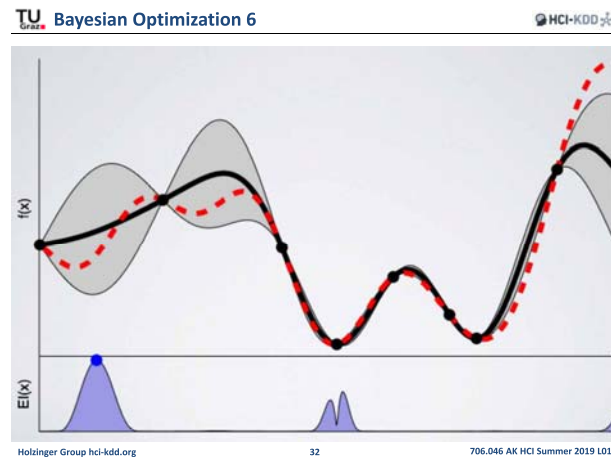
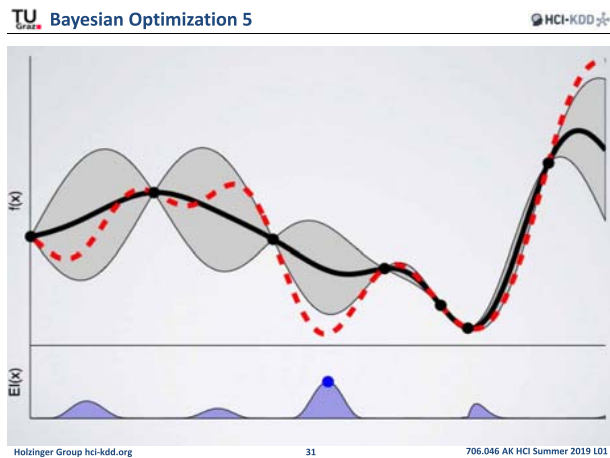
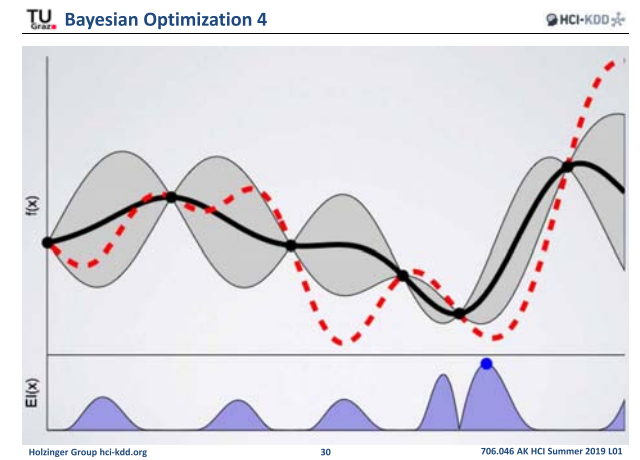
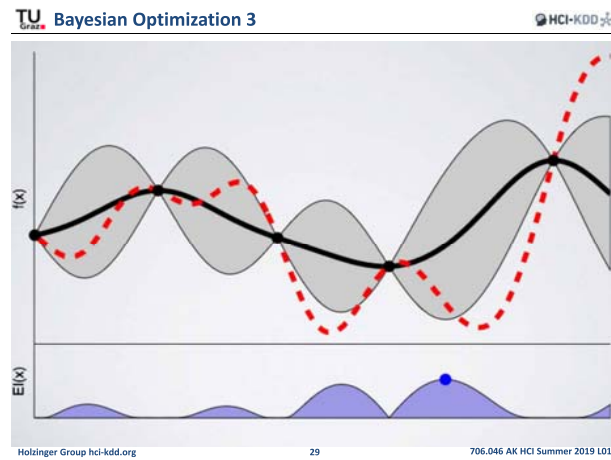
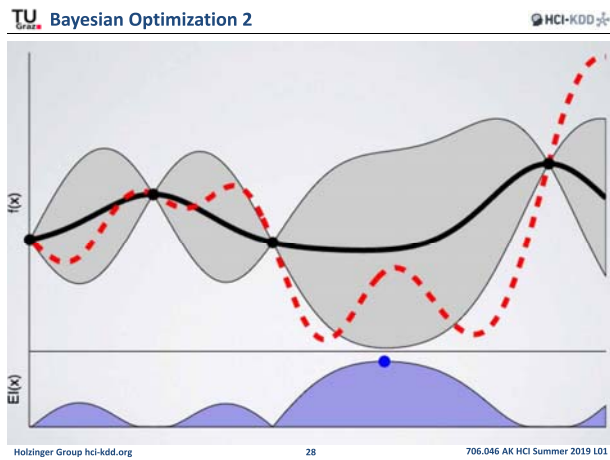
Snoek, J., Larochelle, H. & Adams, R. P. Practical Bayesian optimization of machine learning algorithms. Advances in neural information processing systems, 2012. 2951-2959.

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Bayesian Optimization 1

f(x), pred var, pred mean, truth, evaluations

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TU **Fully automatic → Goal: Taking the human out of the loop** **HCI-KDD** **13**

Algorithm 1 Bayesian optimization

- for $n = 1, 2, \dots$ do
- select new x_{n+1} by optimizing acquisition function α

$$x_{n+1} = \arg \max_x \alpha(x; D_n)$$
- query objective function to obtain y_{n+1}
- augment data $D_{n+1} = \{D_n, (x_{n+1}, y_{n+1})\}$
- update statistical model
- end for

Legend:

- PI: Probability of Improvement
- EI: Expected Improvement
- UCB: Upper Confidence Bound
- TS: Thompson Sampling
- PES: Predictive Entropy Search

Shahriari, B., Swersky, K., Wang, Z., Adams, R. P. & De Freitas, N. 2016. **Taking the human out of the loop: A review of Bayesian optimization.** *Proceedings of the IEEE*, 104, (1), 148-175, doi:10.1109/JPROC.2015.2494218.

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TU **Recommender Systems** **HCI-KDD**

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04 aML

Best practice
examples of
aML ...



Guizzo, E. 2011. How google's self-driving car works. IEEE Spectrum Online, 10, 18.



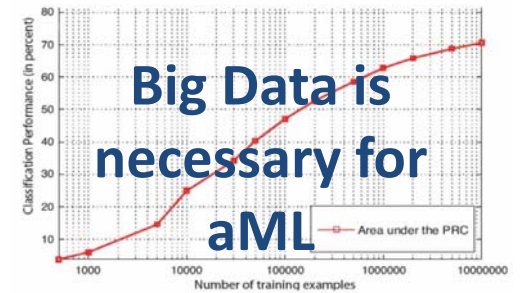
a woman riding a horse on a dirt road
an airplane is parked on the tarmac at an airport
a group of people standing on top of a beach

<https://cs.stanford.edu/people/karpathy/deepimagesent/>

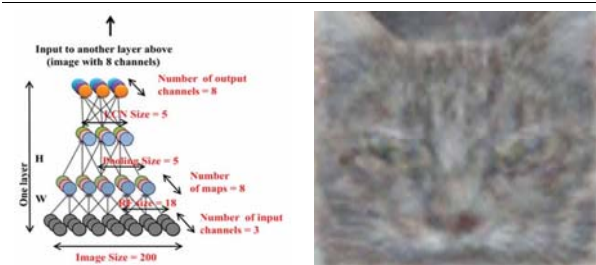
Andrej Karpathy & Li Fei-Fei. Deep visual-semantic alignments for generating image descriptions. Proceedings of the IEEE conference on computer vision and pattern recognition, 2015. 3128-3137.



"a young boy is holding a baseball bat."



Sonnenburg, S., Rätsch, G., Schäfer, C. & Schölkopf, B. 2006. Large scale multiple kernel learning. Journal of Machine Learning Research, 7, (7), 1531-1565.

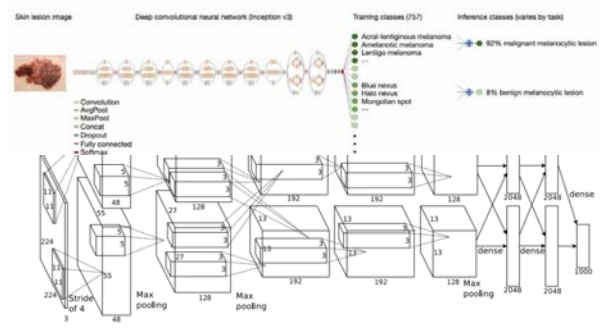


$$x^* = \arg \min_x f(x; W, H), \text{ subject to } \|x\|_2 = 1.$$

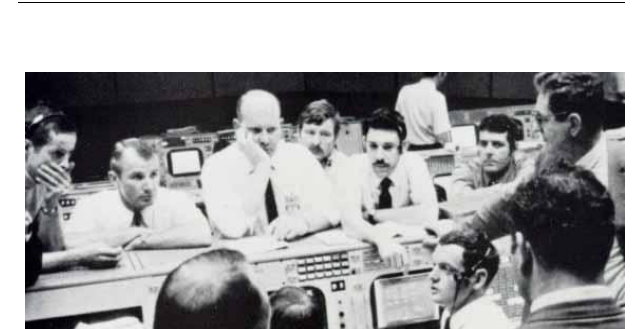
Le, Q. V., Ranzato, M. A., Monga, R., Devin, M., Chen, K., Corrado, G. S., Dean, J. & Ng, A. Y. 2011. Building high-level features using large scale unsupervised learning. arXiv preprint arXiv:1112.6209.

Le, Q. V. 2013. Building high-level features using large scale unsupervised learning. IEEE Intl. Conference on Acoustics, Speech and Signal Processing ICASSP. IEEE. 8595-8598, doi:10.1109/ICASSP.2013.6639343.

Esteve, A., Kuprel, B., Novoa, R. A., Ko, J., Swetter, S. M., Blau, H. M. & Thrun, S. 2017. Dermatologist-level classification of skin cancer with deep neural networks. Nature, 542, (7639), 115-118, doi:10.1038/nature21056.

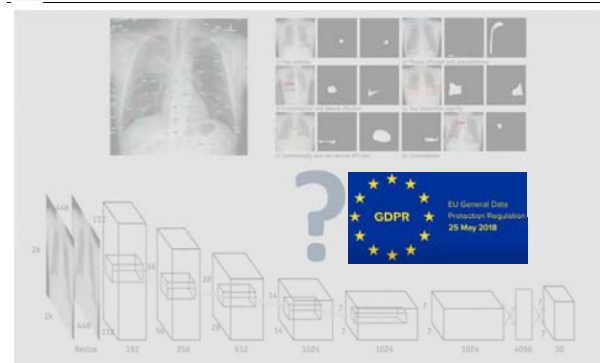


Krizhevsky, A., Sutskever, I. & Hinton, G. E. Imagenet classification with deep convolutional neural networks. In: Pereira, F., Burges, C. J. C., Bottou, L. & Weinberger, K. Q., eds. Advances in neural information processing systems (NIPS 2012), 2012 Lake Tahoe. 1097-1105.

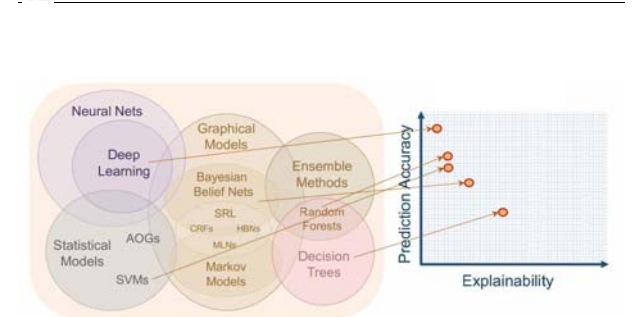


Source: NASA, Image is in the public domain

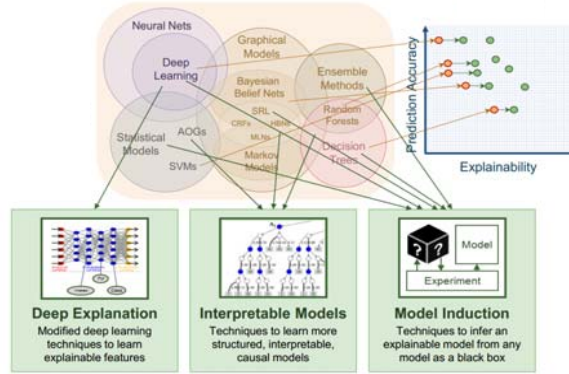
The need for explainability



June-Goo Lee, Sanghoon Jun, Young-Won Cho, Hyunna Lee, Guk Bae Kim, Joon Beom Seo & Namkug Kim 2017. Deep learning in medical imaging: general overview. Korean journal of radiology, 18, (4), 570-584, doi:10.3348/kjr.2017.18.4.570.

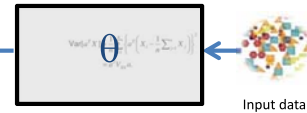


David Gunning 2016. Explainable artificial intelligence (XAI): Technical Report Defense Advanced Research Projects Agency DARPA-BAA-16-53, Arlington, USA, DARPA.



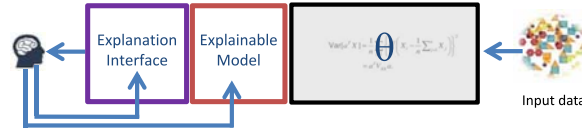
David Gunning 2016. Explainable artificial intelligence (XAI): Technical Report Defense Advanced Research Projects Agency DARPA-BAA-16-53, Arlington, USA, DARPA.

Why did the algorithm do that?
Can I trust these results?
How can I correct an error?



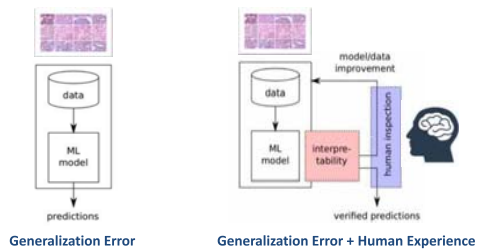
Input data

A possible solution



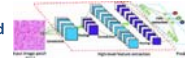
Input data

The domain expert can understand why ...
The domain expert can learn and correct errors ...
The domain expert can re-enact on demand ...



Andreas Holzinger 2016. Interactive Machine Learning for Health Informatics: When do we need the human-in-the-loop? Brain Informatics, 3, (2), 119-131, doi:10.1007/s40708-016-0042-6.

Verify that algorithms/classifiers work as expected
Wrong decisions can be costly and dangerous



Understanding the weaknesses and errors of the ML-Model - Detection of bias in both directions



Scientific interpretability, replicability, causality
The "why" is often more important than the prediction



Enable re-traceability, re-enactivity
Compliance to legislation "right for explanation",
retain human reliability, fosters trust and acceptance

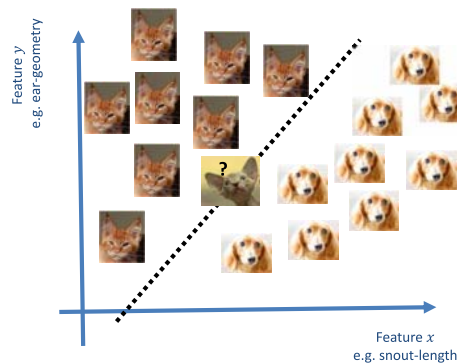


15b

- "How do humans generalize from so few examples?"
 - Learning relevant representations
 - Disentangling the explanatory factors
 - Finding the shared underlying explanatory factors, in particular between $P(x)$ and $P(Y|X)$, with a causal link between $Y \rightarrow X$

Bengio, Y., Courville, A. & Vincent, P. 2013. Representation learning: A review and new perspectives. IEEE transactions on pattern analysis and machine intelligence, 35, (8), 1798-1828, doi:10.1109/TPAMI.2013.50.

Tenenbaum, J. B., Kemp, C., Griffiths, T. L. & Goodman, N. D. 2011. How to grow a mind: Statistics, structure, and abstraction. Science, 331, (6022), 1279-1285, doi:10.1126/science.1192788.



05
iML

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Hans Holbein d.J., 1533,
The Ambassadors,
London: National Gallery



Lopez-Paz, D., Muandet, K., Schölkopf, B. & Tolstikhin, I. 2015. Towards a learning theory of cause-effect inference. Proceedings of the 32nd International Conference on Machine Learning, JMLR, Lille, France.

<https://www.youtube.com/watch?v=9KiVNIUMmCc>

Even Children can make inferences from little data ...

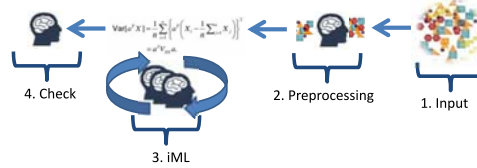


Tenenbaum, J. B., Kemp, C., Griffiths, T. L. & Goodman, N. D. 2011. How to grow a mind: Statistics, structure, and abstraction. Science, 331, (6022), 1279-1285, doi:10.1126/science.1192788.



See also: Ian J. Goodfellow, Jonathon Shlens & Christian Szegedy 2014. Explaining and harnessing adversarial examples. arXiv:1412.6572, and see more examples: <https://imgur.com/a/K4RWn>
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Interactive Machine Learning: Human is seen as an agent involved in the actual learning phase, step-by-step influencing measures such as distance, cost functions ...



Holzinger, A. 2016. Interactive Machine Learning for Health Informatics: When do we need the human-in-the-loop? Brain Informatics (BRIN), 3, (2), 119-131, doi:10.1007/s40708-016-0042-6.
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```

Input : ProblemSize, m, β, ρ, σ, q0
Output: Pbest
Pbest ← CreateHeuristicSolution(ProblemSize);
PbestCost ← Cost(Pbest);
Pheromoneinit ←  $\frac{1.0}{\text{ProblemSize} \times \text{PbestCost}}$ ;
Pheromone ← InitializePheromone(Pheromoneinit);
while ¬StopCondition() do
  for i = 1 to m do
    Si ← ConstructSolution(Pheromone, ProblemSize, β, q0);
    SiCost ← Cost(Si);
    if SiCost ≤ PbestCost then
      PbestCost ← SiCost;
      Pbest ← Si;
    end
    LocalUpdateAndDecayPheromone(Pheromone, Si, SiCost, ρ);
  end
  GlobalUpdateAndDecayPheromone(Pheromone, Pbest, PbestCost, ρ);
  while isUserInteraction() do
    GlobalAddAndRemovePheromone(Pheromone, Pbest, PbestCost, ρ);
  end
end
return Pbest;

```

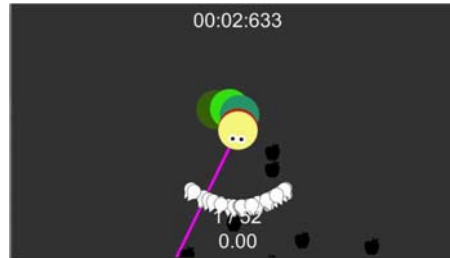
Holzinger, A., Plass, M., Holzinger, K., Crisan, G., Pintea, C. & Palade, V. 2016. Towards interactive Machine Learning (IML): Applying Ant Colony Algorithms to solve the Traveling Salesman Problem with the Human-in-the-Loop approach. Springer Lecture Notes in Computer Science LNCS 9817. 81-95, doi:10.1007/978-3-319-45507-56.
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$$p_{ij} = \frac{[\tau_{ij}]^\alpha \cdot [\eta_{ij}]^\beta}{\sum_{l \in J_i^k} [\tau_{il}]^\alpha \cdot [\eta_{il}]^\beta}$$

- p_{ij} ... **probability** of ants that they, at a particular node i , select the route from node $i \rightarrow j$ (“**heuristic desirability**”)
- $\alpha > 0$ and $\beta > 0$... the **influence parameters** (α ... history coefficient, β ... heuristic coefficient) usually $\alpha \approx \beta \approx 2 < 5$
- τ_{ij} ... the **pheromone value** for the components, i.e. the amount of pheromone on edge (i, j)
- k ... the set of usable components
- J_i ... the set of nodes that ant k can reach from v_i (tabu list)
- $\eta_{ij} = \frac{1}{d_{ij}}$... attractiveness computed by a heuristic, indicating the “a-priori **desirability**” of the move

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<http://hci-kdd.org/gamification-interactive-machine-learning/>



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LIVE DEMO

(<https://iml.hci-kdd.org/imlTspSolver/>)

ANDROID:

<https://play.google.com/store/apps/details?id=com.hcikdd.imlacosolver>



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<http://hci-kdd.org/gamification-interactive-machine-learning/>

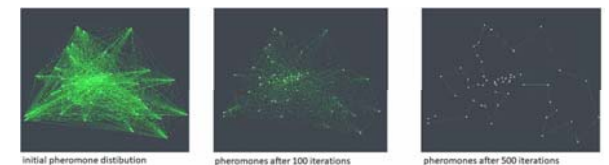


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- **Ant algorithm:** Swarm algorithm driven by pheromones. Ants deposit pheromones on trails, which helps other ants decide, which trail to choose. *In our example we use the algorithm to find the shortest tour in a point set. (Traveling Salesman Problem)*
 - visualization of pheromones is a good interpretation of the ant algorithm

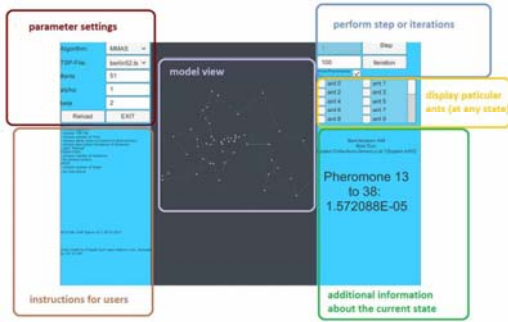
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- The pheromones are showing “the state” (high or low frequented paths of ants) of the algorithm.



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<http://iml.hci-kdd.org/imlTspSolver/>

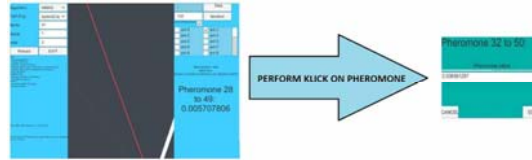


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- iteration vs. step: look inside the iteration
- make the ant algorithm interactive
 - change pheromones at any time
 - change routes of certain ants in the current iteration (future work)

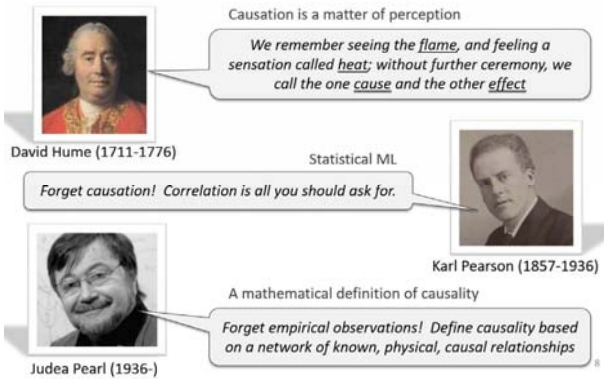


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06 Causality and Causability



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Dependence vs. Causation

Storks Deliver Babies (p. 0.008)
Robert Matthews
Article first published online: 20 DEC 2001
DOI: 10.1111/j.1467-9892.00213
Learning Statistics, 2008



Teaching Statistics
Volume 22, Issue 2
18 June 2008

Country	Area (km ²)	Storks (per 1000)	Birth rate (per 1000)	Birth rate (per 1000)
Albania	28,750	100	3.2	61
Austria	83,860	300	7.8	87
Belgium	30,520	1	8.8	119
Belgium	111,000	3000	8.8	117
Denmark	43,100	9	5.1	39
France	344,000	140	56	774
Germany	357,000	3300	76	901
Greece	132,000	2500	38	104
Holland	41,900	4	15	188
Hungary	93,000	3000	11	124
Italy	301,200	5	57	551
Poland	312,000	30,000	10	120
Portugal	92,500	1500	10	120
Romania	237,500	3000	23	367
Spain	504,750	8000	39	439
Switzerland	41,200	130	6.7	82
Turkey	779,650	25,000	36	176

Table 1. Geographic, bottom and work data for 17 European countries

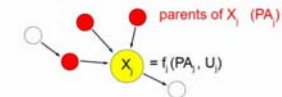
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Functional Causal Model (Pearl et al.)

- Set of observables $X_1, \dots, X_n$
- directed acyclic graph G with vertices $X_1, \dots, X_n$
- Semantics: parents = direct causes
- $X_i = f_i(\text{ParentsOf}_i, \text{Noise}_i)$, with independent $\text{Noise}_1, \dots, \text{Noise}_n$.
- "Noise" means "unexplained" (or "exogenous"), we use U_i
- Can add requirement that $f_1, \dots, f_n, \text{Noise}_1, \dots, \text{Noise}_n$ "independent" (cf. Lemeire & Dirks 2006, Janzing & Schölkopf 2010 — more below)



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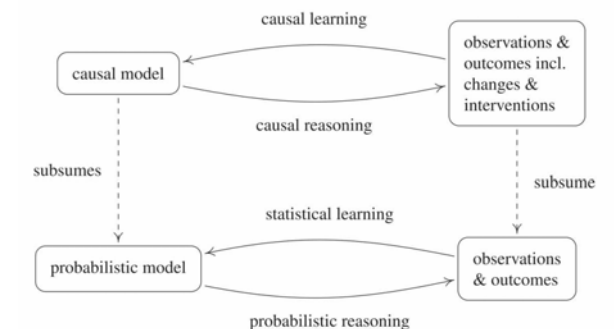
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Explainability	in a technical sense highlights decision-relevant parts of the used representations of the algorithms and active parts in the algorithmic model, that either contribute to the model accuracy on the training set, or to a specific prediction for one particular observation. It does not refer to an explicit human model.
Causability	as the extent to which an explanation of a statement to a human expert achieves a specified level of causal understanding with effectiveness, efficiency and satisfaction in a specified context of use.

07 Measuring Causality?

- Causability := a property of a person, while
- Explainability := a property of a system



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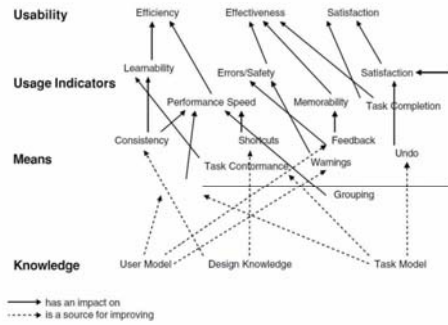
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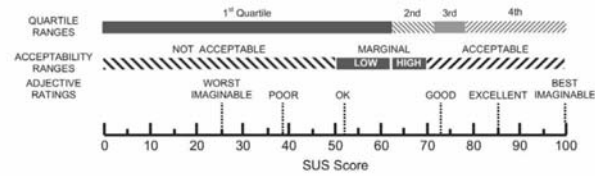
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Veer, G. C. v. d. & Welie, M. v. (2004) DUTCH: Designing for Users and Tasks from Concepts to Handles. In: Diaper, D. & Stanton, N. (Eds.) *The Handbook of Task Analysis for Human-Computer Interaction*. Mahwah (New Jersey), Lawrence Erlbaum, 155-173.



Bangor, A., Kortum, P. T. & Miller, J. T. (2008) An empirical evaluation of the System Usability Scale. *International Journal of Human-Computer Interaction*, 24, 6, 574-594.

The System Usability Scale Standard Version		Strongly Disagree					Strongly Agree				
		1	2	3	4	5					
1	I think that I would like to use this system frequently.		0	0	0	0	0				
2	I found the system unnecessarily complex.		0	0	0	0	0				
3	I thought the system was easy to use.		0	0	0	0	0				
4	I think that I would need the support of a technical person to be able to use this system.		0	0	0	0	0				
5	I found the various functions in this system were well integrated.		0	0	0	0	0				
6	I thought there was too much inconsistency in this system.		0	0	0	0	0				
7	I would imagine that most people would learn to use this system very quickly.		0	0	0	0	0				
8	I found the system very awkward to use.		0	0	0	0	0				
9	I felt very confident using the system.		0	0	0	0	0				
10	I needed to learn a lot of things before I could get going with this system.		0	0	0	0	0				

Our Goal in this AK: design, develop & test a System Causability Scale