

**Assoc.Prof. Dr. Andreas Holzinger**

**185.A83 Machine Learning for Health Informatics**

**2020S, VU, 2.0 h, 3.0 ECTS**

**Andreas Holzinger, Marcus Bloice, Florian Endel, Anna Saranti**

**Lecture 01 - Week 12**

# **From health informatics to ethical responsible medical AI**

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**<https://human-centered.ai/machine-learning-for-health-informatics-class-2020>**



## LV·185.A83·Machine·Learning·for·Health·Informatics·(Class·of·2020)¶

Andreas·HOLZINGER,·Marcus·BLOICE,·Florian·ENDEL,·Anna·SARANTI¶

Study·Code:·066·936·Master·program·Medical·Informatics¶

<https://tiss.tuwien.ac.at/curriculum/public/curriculum.xhtml?dswid=9468&dswid=253&key=56089&semester=NEXT>¶

Semester·hours:·2.0·h;·ECTS·Credits:·3.0;·Type:·VU·Lecture·and·Exercises·with·Python¶

ECTS·Breakdown·(sum=75·h,·corresponds·with·3·ECTS,·where·1·ECTS=·25·h·workload):¶

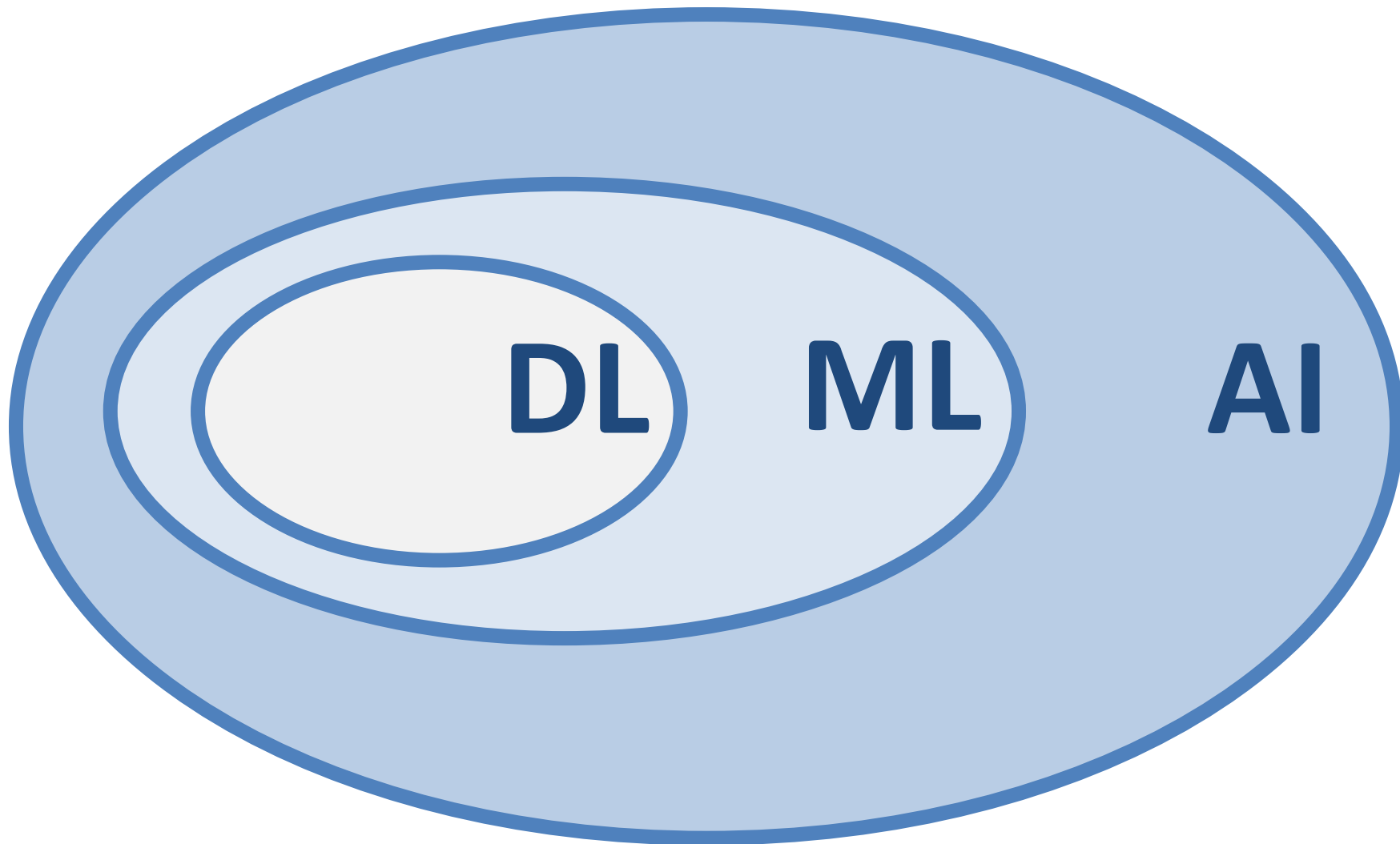
Presence·during·lecture□	8·*·3·h□	24·h□	□
Preparation·before·and·after·lecture□	8·*·1·h□	08·h□	□
Preparation·of·assignments·and·presentation□	28·h·+·2·h·□	30·h□	□
Written·exam·including·preparation□	1·h·+·12·h·□	13·h□	□
TOTAL·students'·workload□	□	<b>75·h□</b>	□

Class·URL:·<https://human-centered.ai/machine-learning-for-health-informatics-class-2020>¶

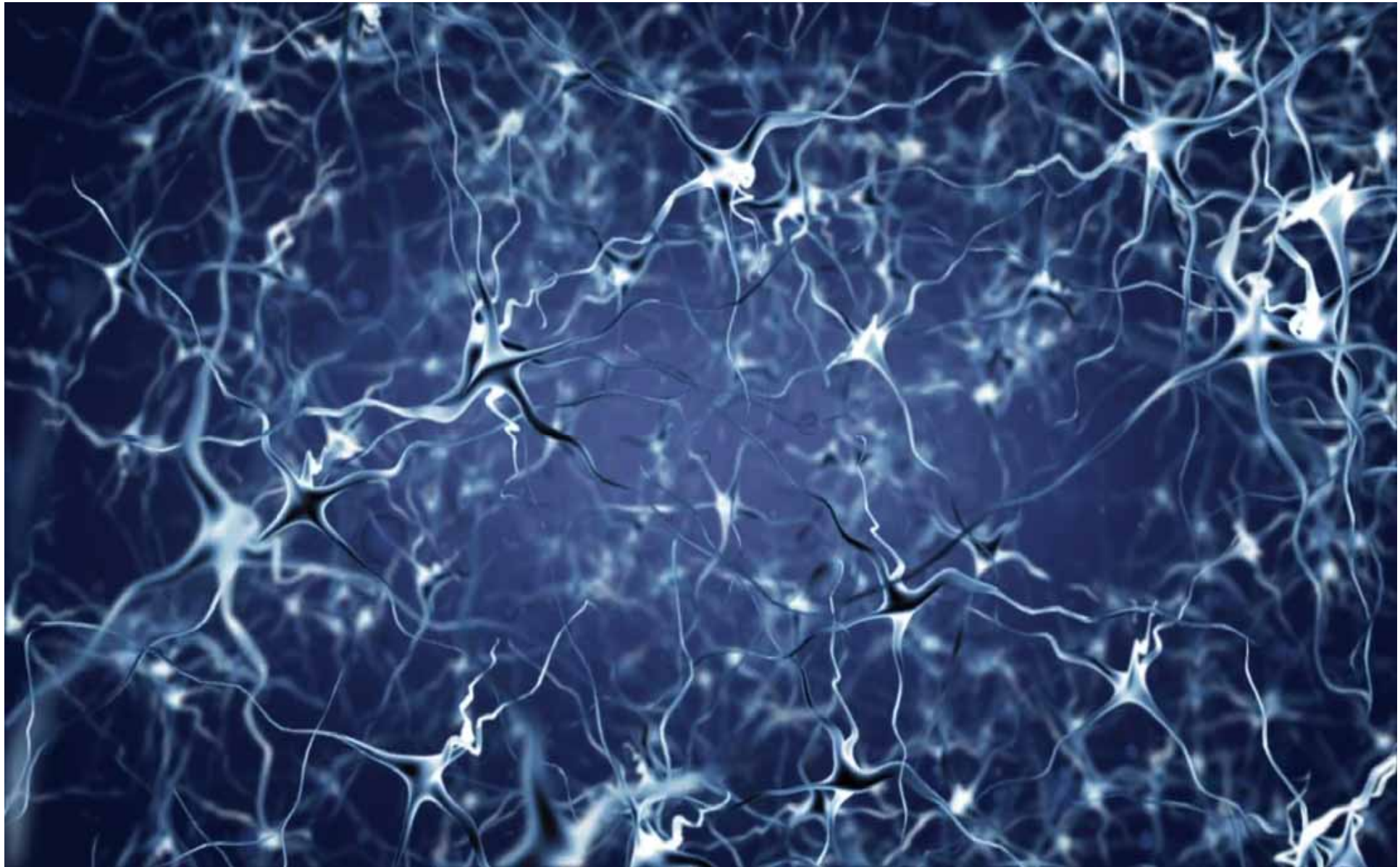
Class·Schedule·for·2020·(subject·to·change:·please·check·class·URL·for·any·changes):¶

<i>Nr</i> □	<i>Week</i> □	<i>Topic</i> □	□
01□	12□	Introduction·and·overview:·↵ From·health·informatics·to·ethical·responsible·medical·AI□	□
02□	12□	Data·for·machine·learning:·Probabilistic·information·and·entropy·¶	□

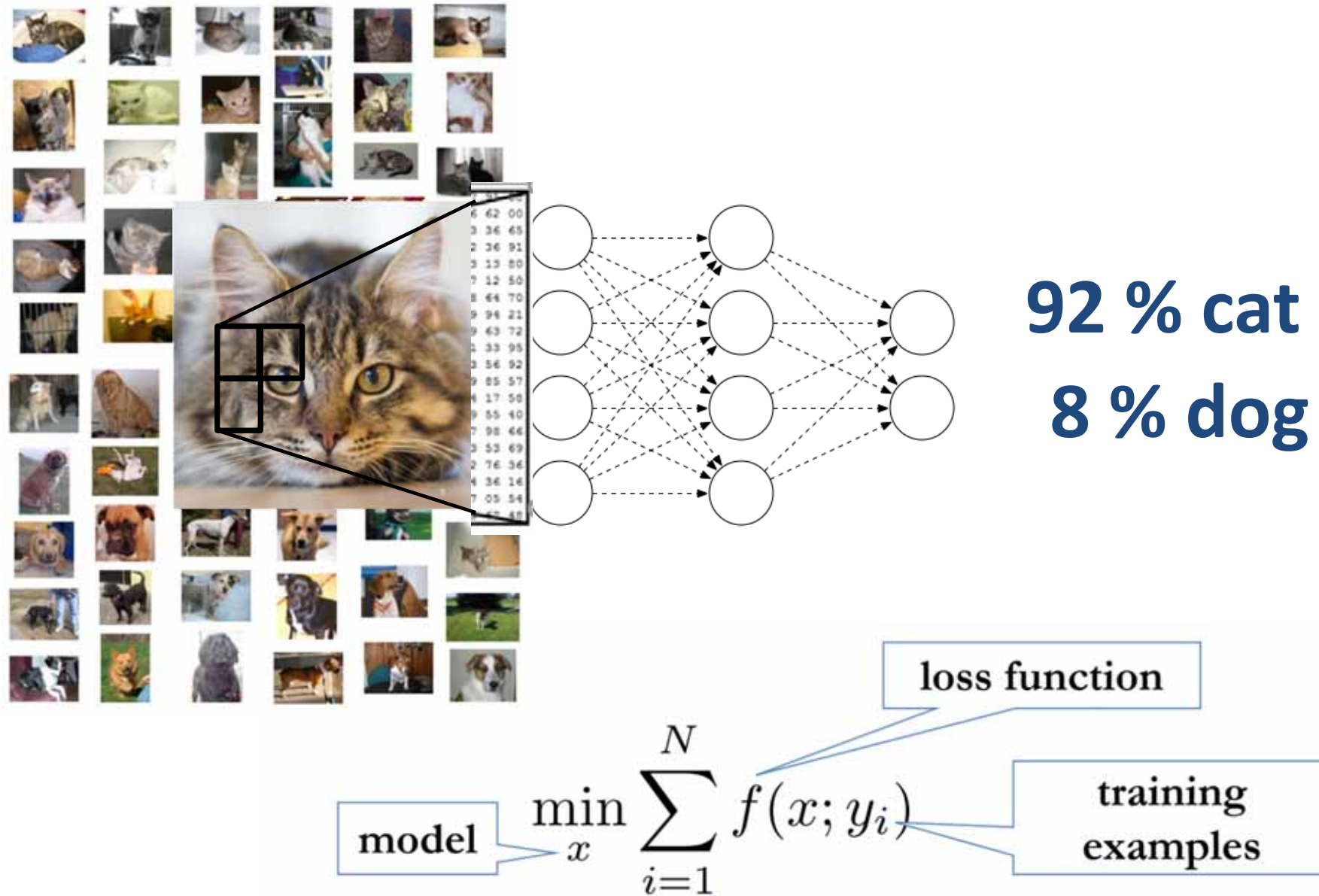
# Before we start ...

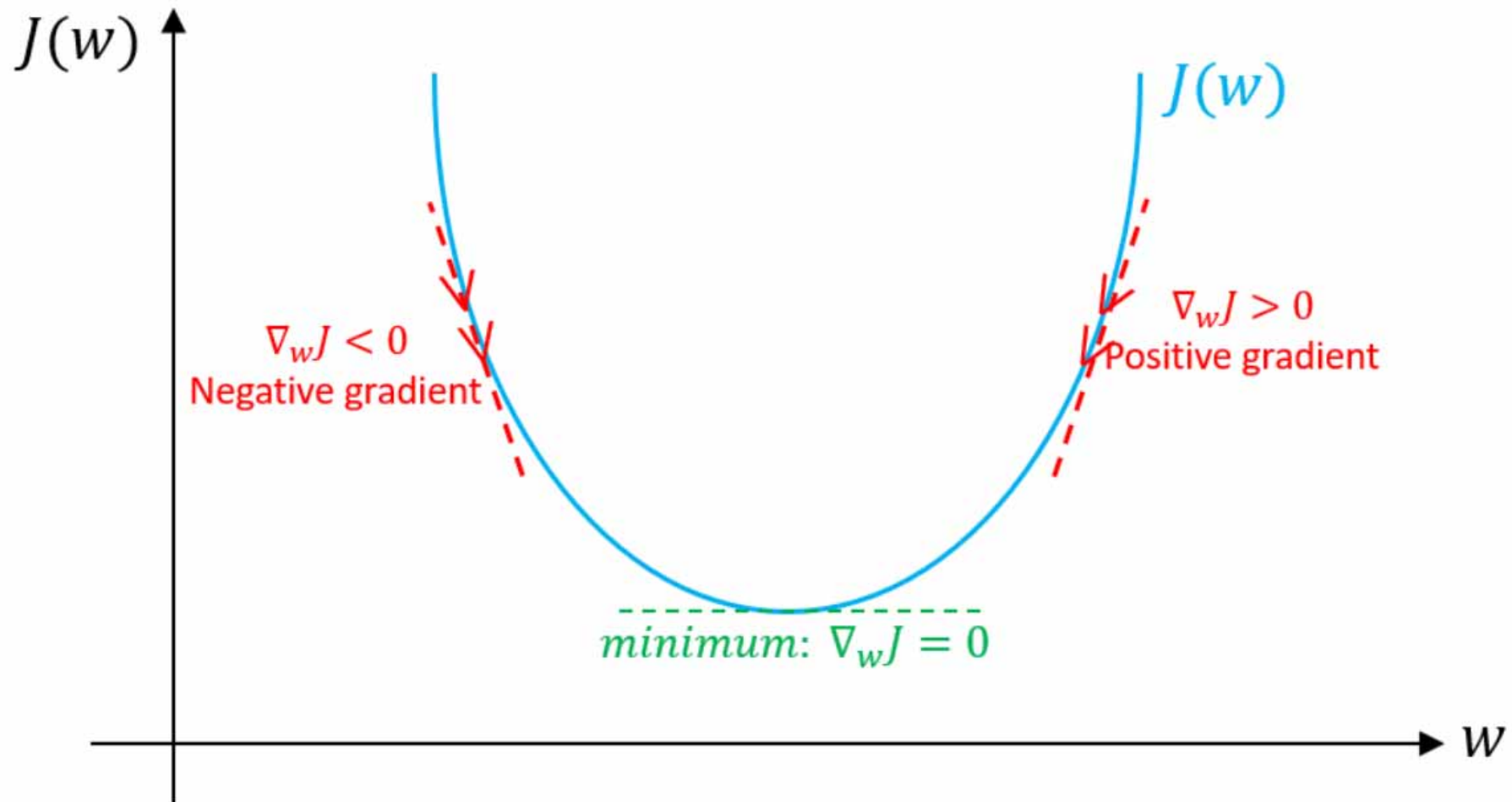


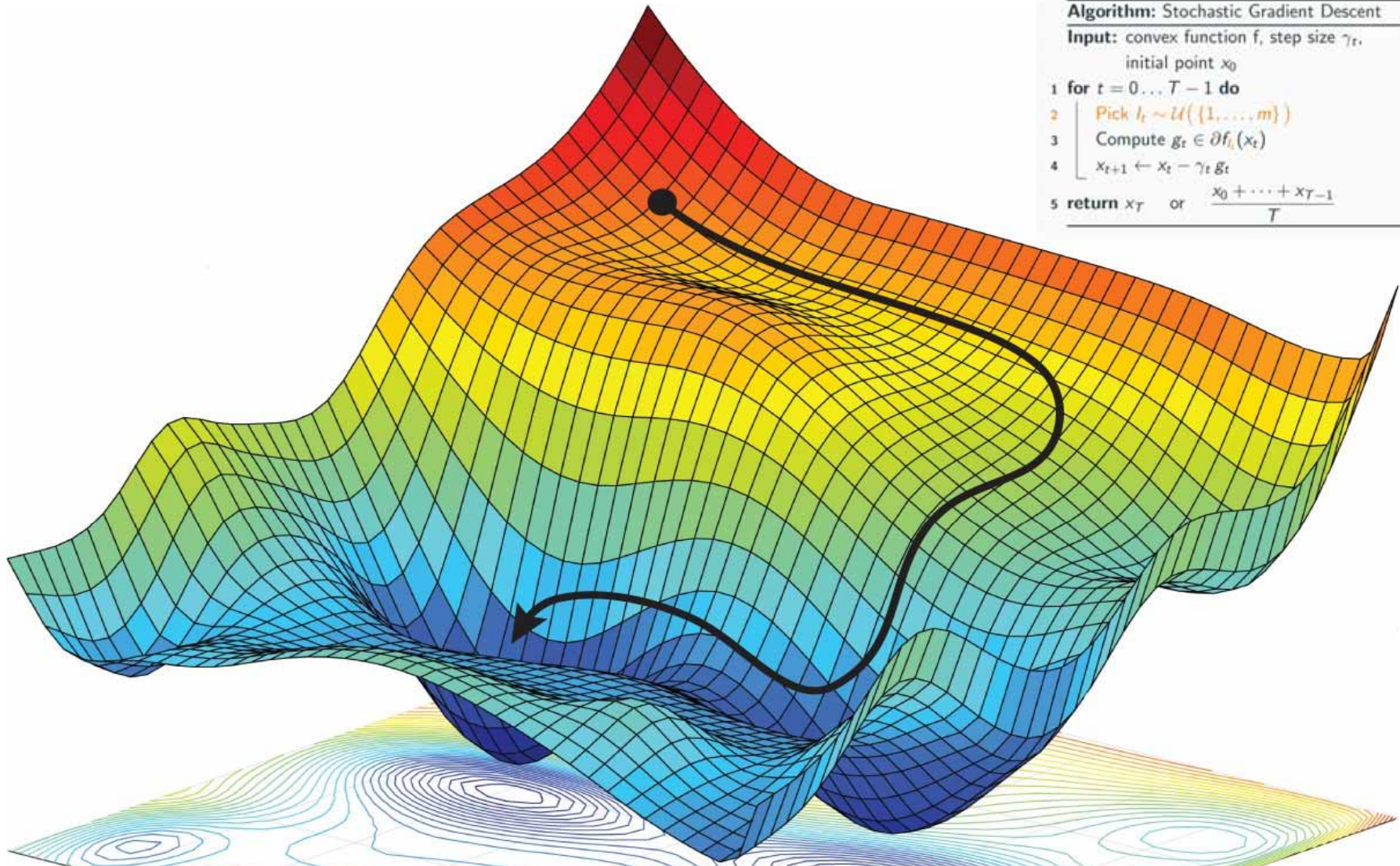
Andreas Holzinger, Peter Kieseberg, Edgar Weippl & A Min Tjoa 2018. Current Advances, Trends and Challenges of Machine Learning and Knowledge Extraction: From Machine Learning to Explainable AI. Springer Lecture Notes in Computer Science LNCS 11015. Cham: Springer, pp. 1-8, doi:[10.1007/978-3-319-99740-7\\_1](https://doi.org/10.1007/978-3-319-99740-7_1)









**Algorithm:** Stochastic Gradient Descent**Input:** convex function  $f$ , step size  $\gamma_t$ ,initial point  $x_0$ 1 for  $t = 0 \dots T - 1$  do2   Pick  $I_t \sim \mathcal{U}(\{1, \dots, m\})$ 3   Compute  $g_t \in \partial f_{I_t}(x_t)$ 4    $x_{t+1} \leftarrow x_t - \gamma_t g_t$ 5 return  $x_T$  or  $\frac{x_0 + \dots + x_{T-1}}{T}$ 

$$\min_{x \in \mathbb{R}^d} \left\{ f(x) := \mathbb{E}_i[f_i(x)] = \frac{1}{n} \sum_{i=1}^n f_i(x) \right\}$$



For a tutorial on Machine Learning with Python please look up:

<https://graz.pure.elsevier.com/de/publications/a-tutorial-on-machine-learning-and-data-science-tools-with-python>

# Ok, but now let's start ...

- **01 Integrative ML: Human-Centered AI**
- **02 Application Area Health**
- **03 Probabilistic Learning**
- **04 Automatic Machine Learning (aML)**
- **05 Interactive Machine Learning (iML)**
- **06 “Explainable AI”**
- **Conclusion and future outlook**

# 01 What is the



# approach?

## MAchine Learning & Knowledge Extraction MAKE

(Safety) 4 - Privacy, Data Protection, Safety & Security



(Space and Time) 5 - Network, 6-Topology, 7-Entropy

Andreas Holzinger 2017. Introduction to Machine Learning and Knowledge Extraction (MAKE). *Machine Learning and Knowledge Extraction*, 1, (1), 1-20, doi:10.3390/make1010001.





<https://human-centered.ai/explainable-ai-2020>

# “Solve intelligence – then solve everything else”



<https://youtu.be/XAbLn66iHcQ?t=1h28m54s>

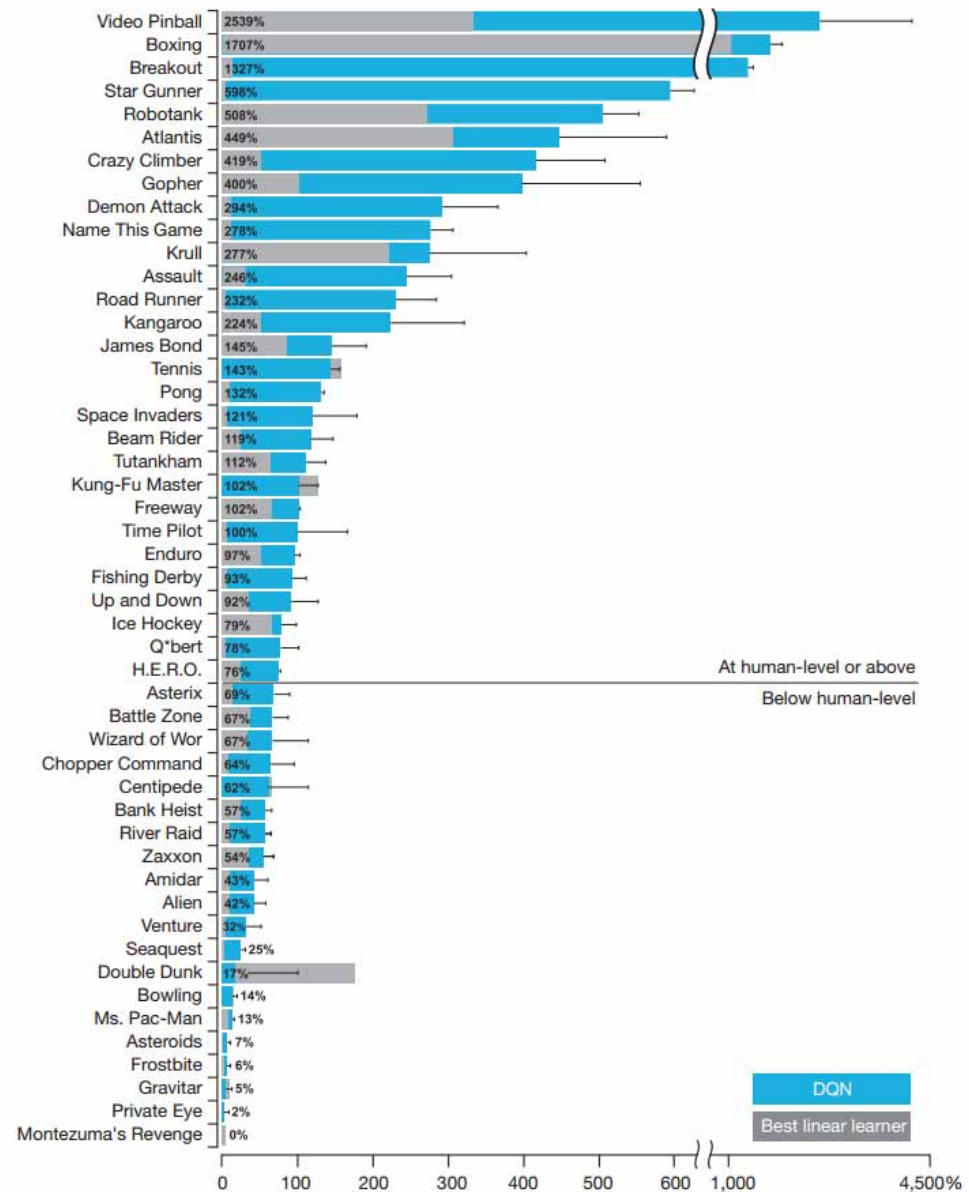
Demis Hassabis, 22 May 2015

The Royal Society,  
Future Directions of Machine Learning Part 2



# Compare your best ML algorithm with a seven-year- old child ...

Mnih, V., Kavukcuoglu, K., Silver, D., Rusu, A. A., Veness, J., Bellemare, M. G., Graves, A., Riedmiller, M., Fidjeland, A. K., Ostrovski, G., Petersen, S., Beattie, C., Sadik, A., Antonoglou, I., King, H., Kumaran, D., Wierstra, D., Legg, S. & Hassabis, D. 2015. Human-level control through deep reinforcement learning. Nature, 518, (7540), 529-533, doi:10.1038/nature14236

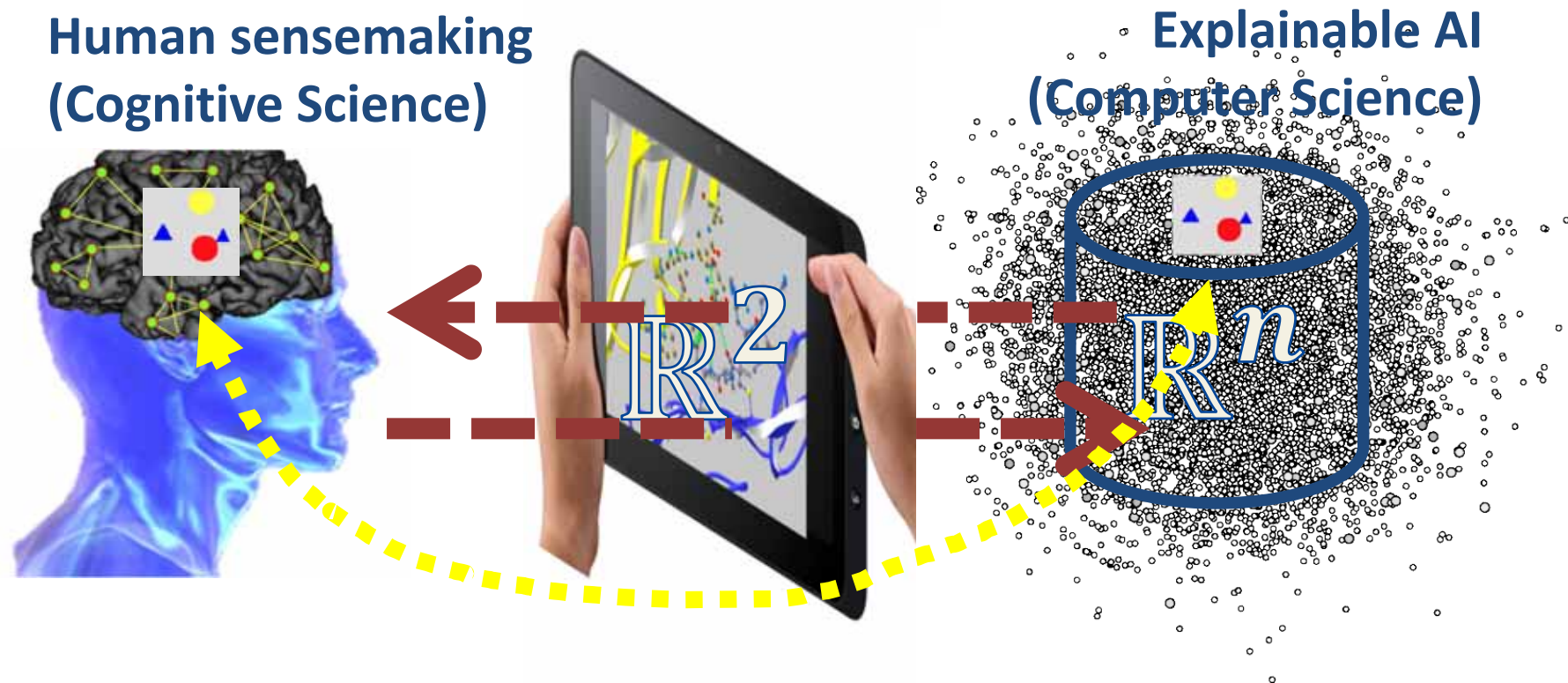


- 1) **learn** from prior data
- 2) **extract** knowledge
- 2) **generalize**, (e.g. guessing where a probability mass function concentrates)
- 4) fight the curse of **dimensionality**
- 5) **disentangle** underlying explanatory factors of data, i.e.
- 6) **understand** the results in the **context** of an application domain (sensemaking)



# Our goal: Understanding Context !

- Causability := a property of a person (Human)
- Explainability := a property of a system (Computer)



Andreas Holzinger et al. 2019. Causability and Explainability of AI in Medicine. Wiley Interdisciplinary Reviews: Data Mining and Knowledge Discovery, doi:10.1002/widm.1312.



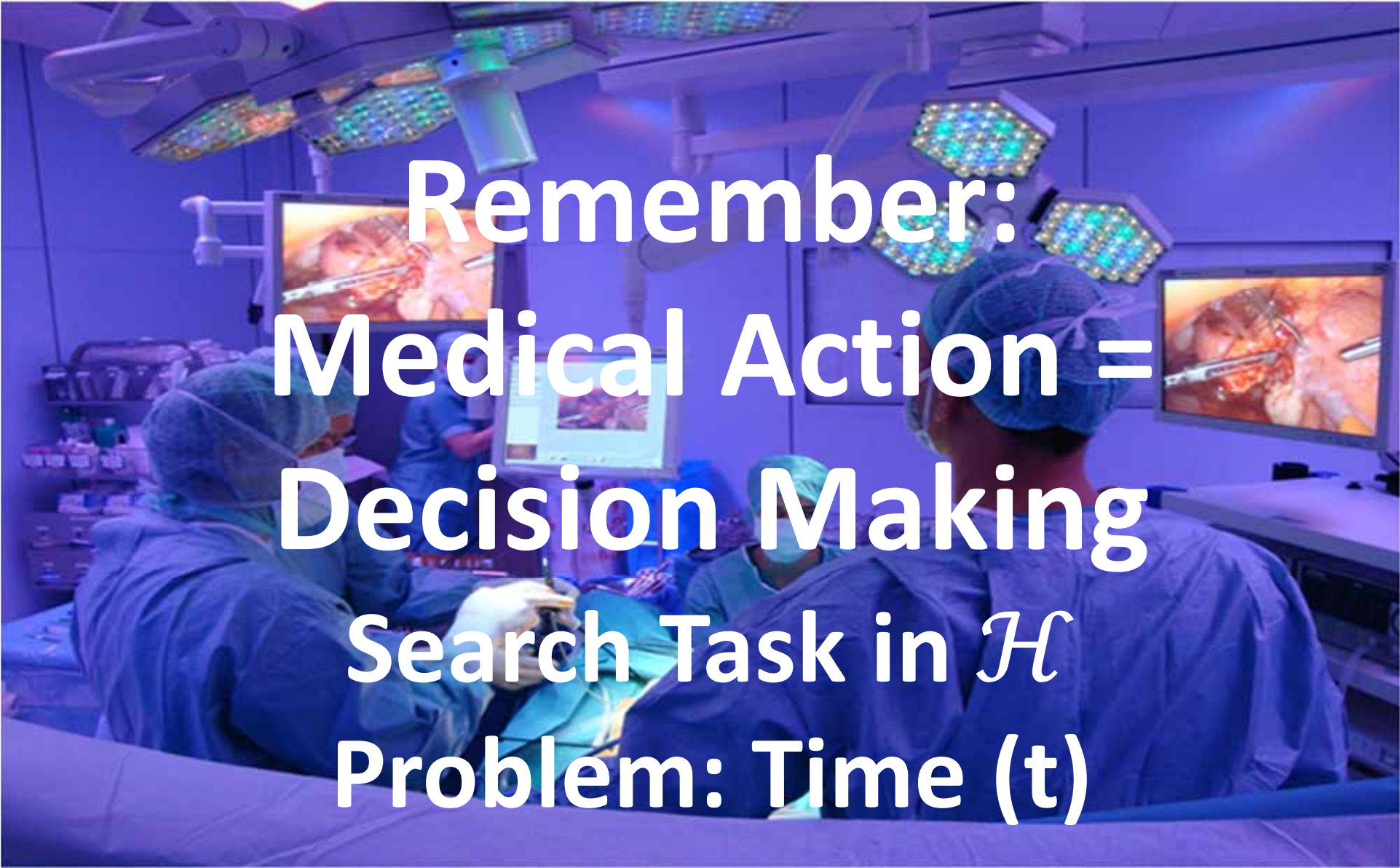
Source: Image is in the public domain and is used according UrhG §42 lit. f Abs 1 as "Belegfunktion" for discussion with students

Lotfi A. Zadeh 2008. Toward Human Level Machine Intelligence - Is It Achievable? The Need for a Paradigm Shift. IEEE Computational Intelligence Magazine, 3, (3), 11-22, doi:10.1109/MCI.2008.926583.



# 02 Application Area Health Informatics



A photograph of an operating room with surgeons and monitors, overlaid with white text.

Remember:  
Medical Action =  
Decision Making  
Search Task in  $\mathcal{H}$   
Problem: Time (t)







Source: Cisco (2008).  
Cisco Health Presence  
Trial at Aberdeen Royal  
Infirmary in Scotland

- 400 BC Hippocrates (460-370 BC), father of western medicine:
  - A medical record should accurately reflect the course of a disease
  - A medical record should indicate the probable cause of a disease
- **1890** William Osler (1849-1919), father of modern western medicine
  - **Medicine is a science of uncertainty and an art of probabilistic decision making**
- Today
  - Prediction models are based on data features, patient health status is modelled as high-dimensional feature vectors ...

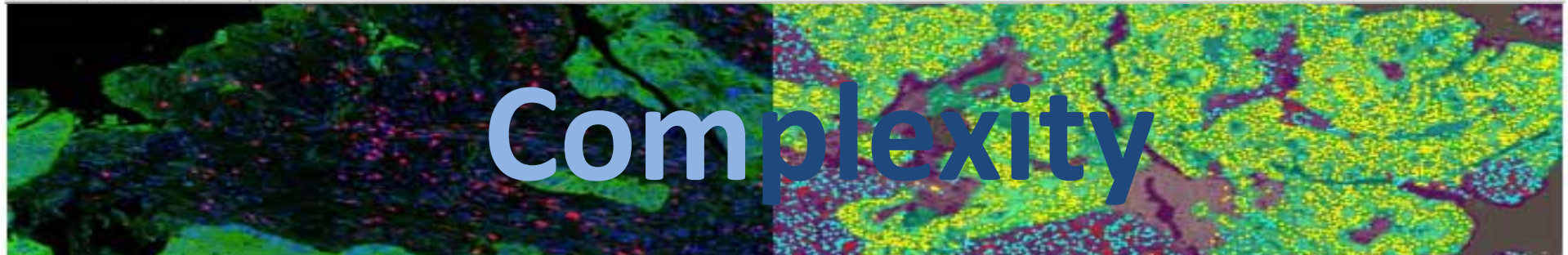
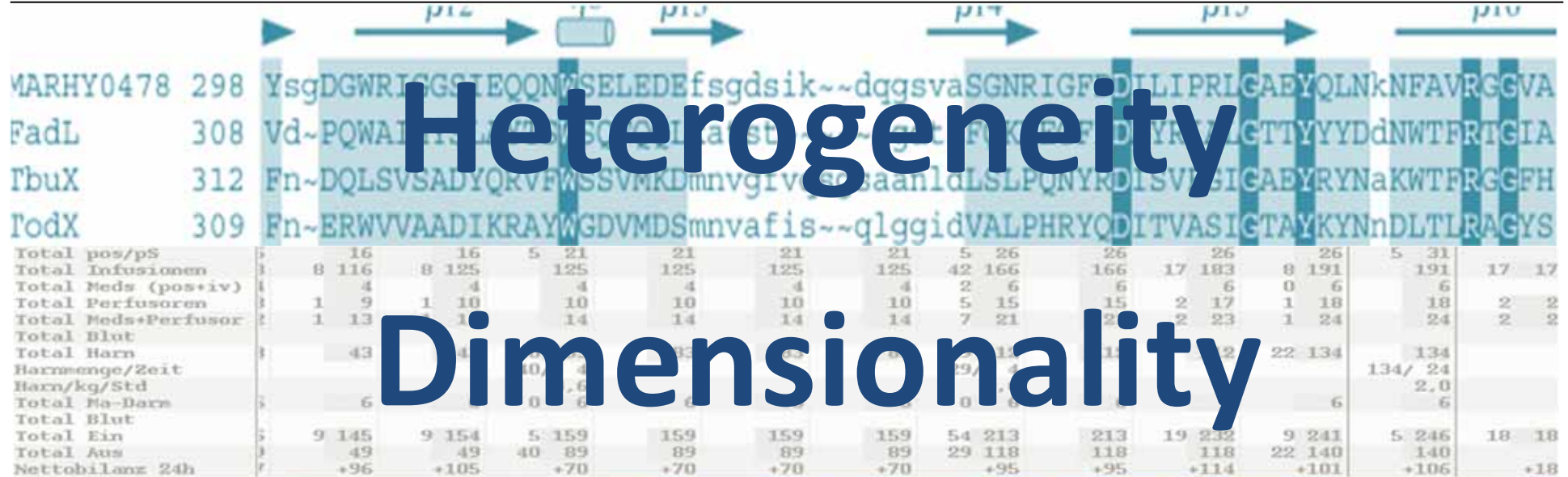


The images on this slide are used according to UrhG §42 lit. f Abs 1 as “Belegfunktion” for discussion with students



# Our central hypothesis: Information may bridge this gap

Andreas Holzinger & Klaus-Martin Simoncic (eds.) 2011. Information Quality in e-Health. Lecture Notes in Computer Science LNCS 7058, Heidelberg, Berlin, New York: Springer, doi:10.1007/978-3-642-25364-5.



**Uncertainty**

Andreas Holzinger, Matthias Dehmer & Igor Jurisica 2014. Knowledge Discovery and interactive Data Mining in Bioinformatics - State-of-the-Art, future challenges and research directions. Springer/Nature BMC Bioinformatics, 15, (S6), I1, doi:10.1186/1471-2105-15-S6-I1.

# 03 Probabilistic Learning

The true logic of this world is  
in the calculus of  
probabilities.

James Clerk Maxwell



Maxwell, J. C. (1850). Letter to Lewis Campbell; reproduced in L. Campbell and W. Garrett, The Life of James Clerk Maxwell, Macmillan, 1881.



# Probability theory is nothing, but common sense reduced to calculation ...

$$\hat{y} = \hat{f}(\mathbf{x}) = \operatorname{argmax}_{c=1}^C p(y = c | \mathbf{x}, \mathcal{D})$$

Pierre-Simon Laplace 1825. Philosophical Essay on Probabilities:  
Translated 1995 from the fifth French edition of 1825 With  
Notes by Andrew I. Dale, New York, Springer Science.



Image is in the public domain

**Pierre Simon de Laplace (1749-1827)**

- **1763:** Richard Price publishes post hum the work of Thomas Bayes (see next slide)
- **1781:** Pierre-Simon Laplace: Probability theory is nothing, but common sense reduced to calculation ...
- **1812:** Théorie Analytique des Probabilités, now known as Bayes' Theorem
- **Hypothesis**  $h \in \mathcal{H}$  (uncertain quantities (Annahmen))
- **Data**  $d \in \mathcal{D}$  ... measured quantities (Entitäten)
- **Prior probability**  $p(h)$  ... probability that  $h$  is true
- **Likelihood**  $p(d|h)$  ... “how probable is the prior”
- **Posterior Probability**  $p(h|d)$  ... probability of  $h$  given  $d$

$$p(h|d) \propto p(d|h) * p(h) \qquad p(h|d) = \frac{p(d|h)p(h)}{p(d)}$$



What is the simplest mathematical operation for us?

$$p(x) = \sum_y (p(x, y)) \quad (1)$$

How do we call repeated adding?

$$p(x, y) = p(y|x) * p(x) \quad (2)$$

Laplace (1773) showed that we can write:

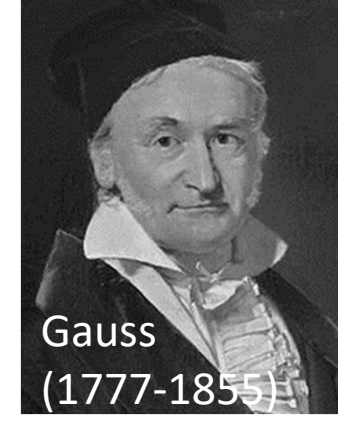
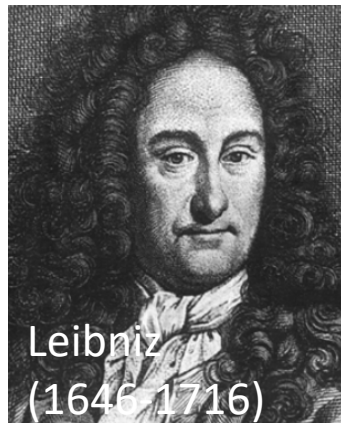
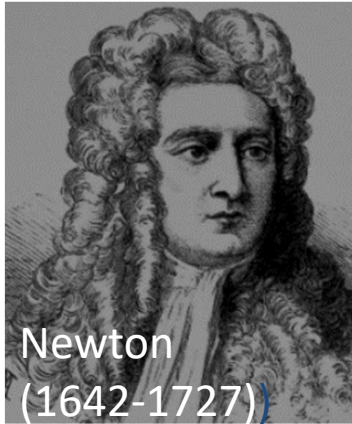
$$p(x, y) * p(x) = p(y|x) * p(x) \quad (3)$$

Now we introduce a third, more complicated operation:

$$\frac{p(x, y) * p(x)}{p(x)} = \frac{p(y|x) * p(x)}{p(x)} \quad (4)$$

We can reduce this fraction by  $p(x)$  and we receive what is called Bayes rule:

$$p(x, y) = \frac{p(y|x) * p(x)}{p(y)} \quad p(h|d) = \frac{p(d|h)p(h)}{p(d)} \quad (5)$$



- **Newton, Leibniz, ... developed calculus – mathematical language for describing and dealing with rates of change**
- **Bayes, Laplace, ... developed probability theory - the mathematical language for describing and dealing with uncertainty**
- **Gauss generalized those ideas**

$$p(x_i) = \sum P(x_i, y_j)$$

$$p(x_i, y_j) = p(y_j|x_i)P(x_i)$$

Bayes, T. (1763). An Essay towards solving a Problem in the Doctrine of Chances (Postum communicated by Richard Price). Philosophical Transactions, 53, 370-418.

**Bayes’ Rule is a corollary of the Sum Rule and Product Rule:**

$$p(x_i|y_j) = \frac{p(y_j|x_i)p(x_i)}{\sum p(x_i, y_j)p(x_i)}$$

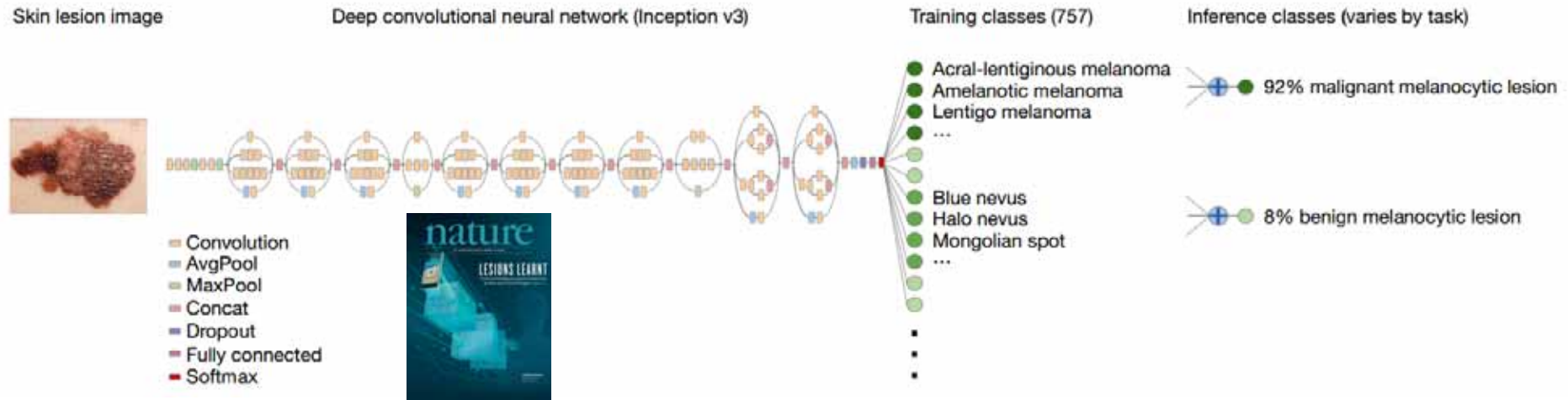
$$P(\text{hypothesis}|\text{data}) = \frac{P(\text{hypothesis})P(\text{data}|\text{hypothesis})}{\sum_h P(h)P(\text{data}|h)} \quad P(\theta|\mathcal{D}, m) = \frac{P(\mathcal{D}|\theta, m)P(\theta|m)}{P(\mathcal{D}|m)}$$

$P(D|\theta, m)$  likelihood of parameters  $\theta$  in model  $m$

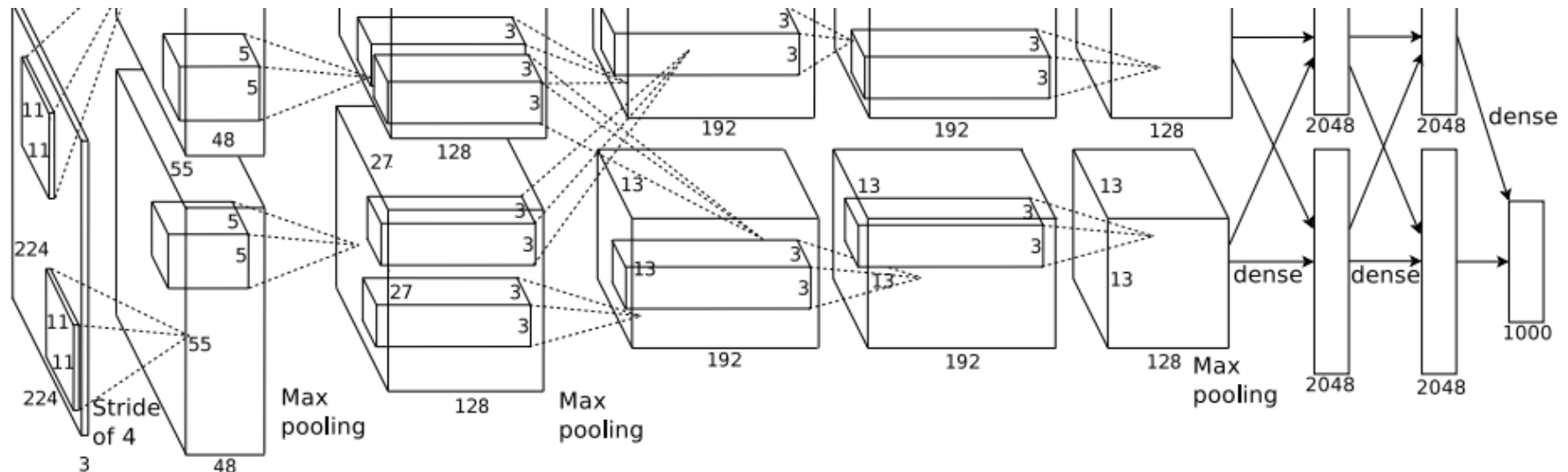
$P(\theta|m)$  prior probability of  $\theta$

$P(\theta|D, m)$  posterior of  $\theta$  given data  $D$

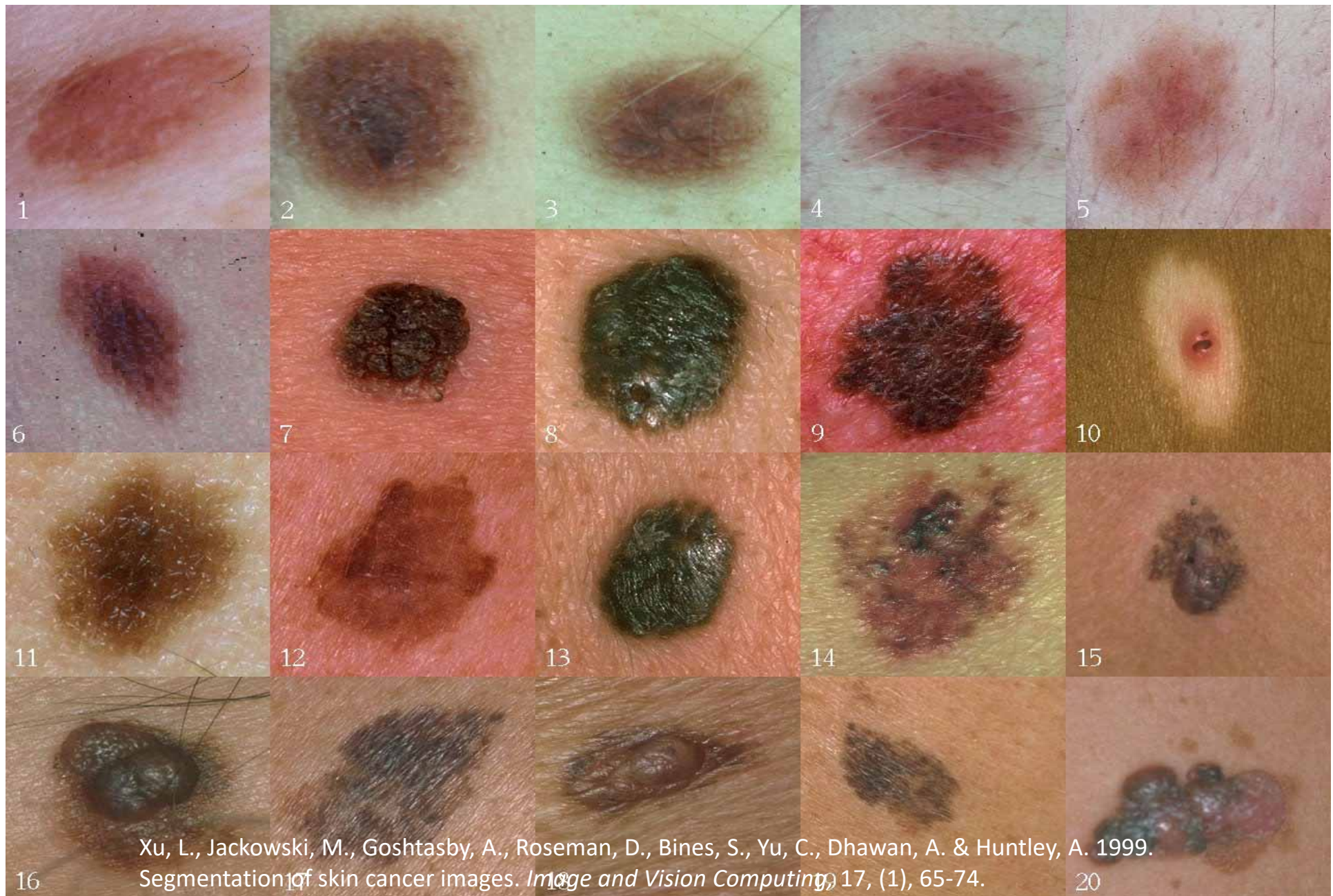
Barnard, G. A., & Bayes, T. (1958). Studies in the history of probability and statistics: IX. Thomas Bayes's essay towards solving a problem in the doctrine of chances. Biometrika, 45(3/4), 293-315.



Esteva, A., Kuprel, B., Novoa, R. A., Ko, J., Swetter, S. M., Blau, H. M. & Thrun, S. 2017. Dermatologist-level classification of skin cancer with deep neural networks. *Nature*, 542, (7639), 115-118, doi:10.1038/nature21056.

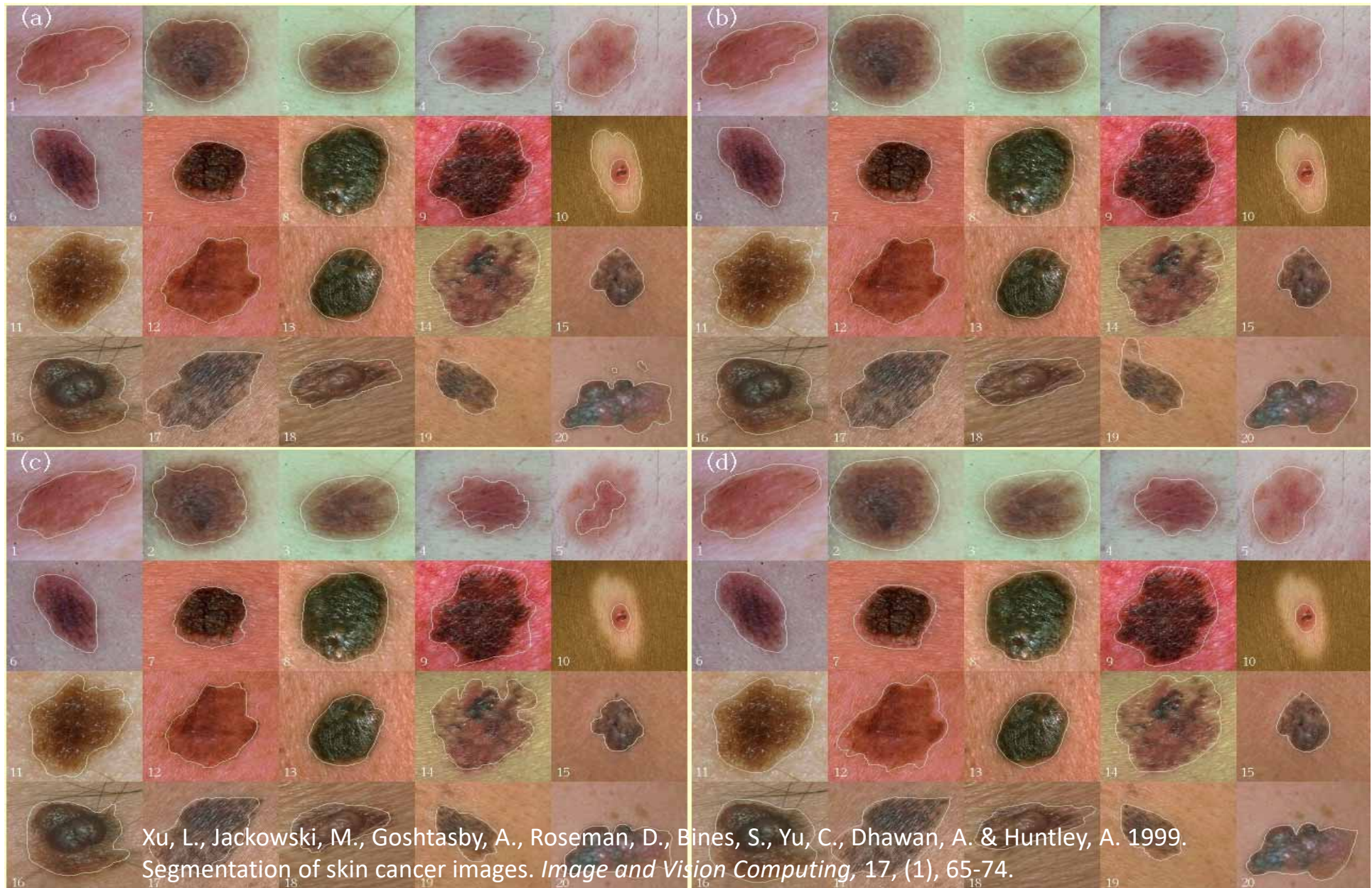






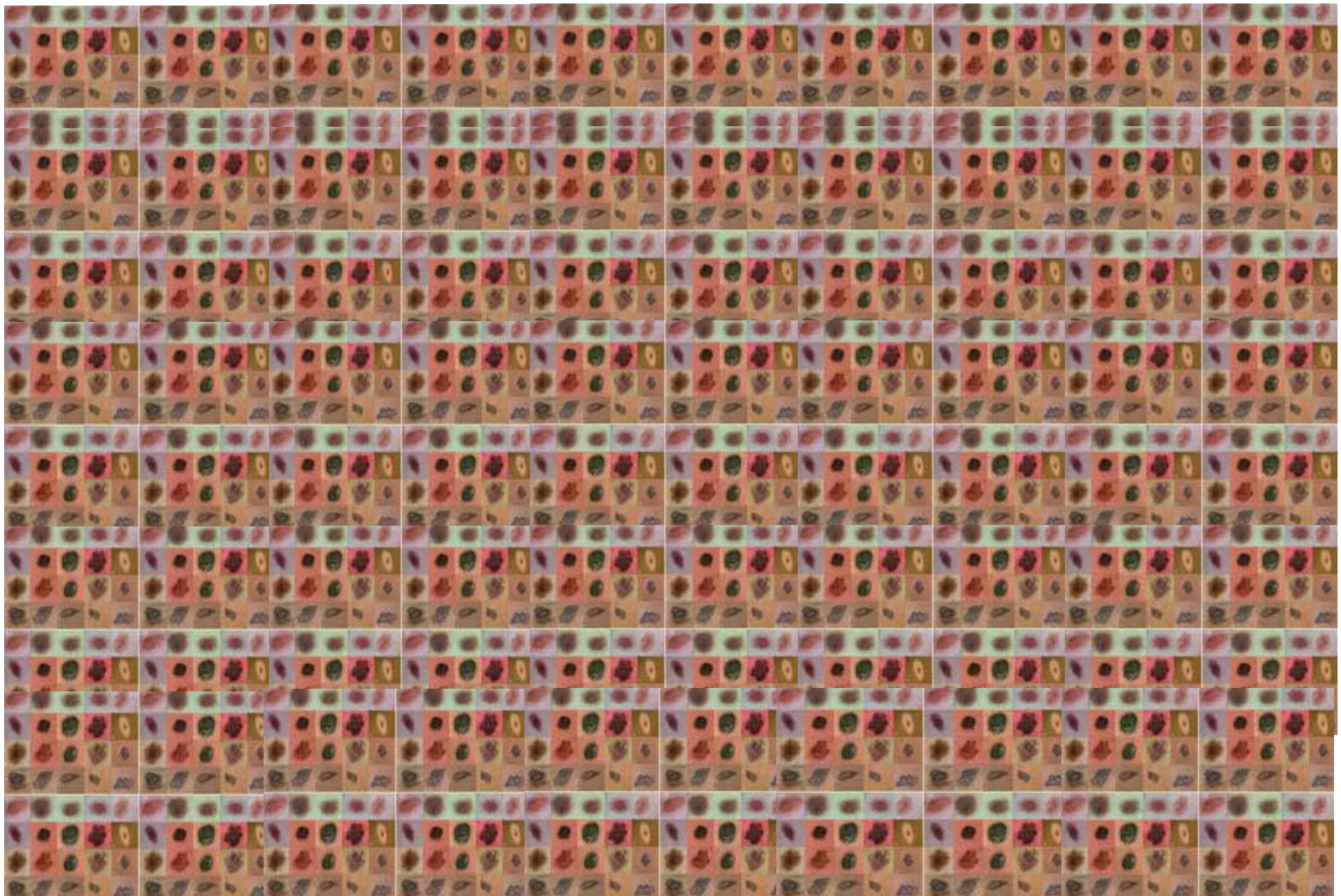
Xu, L., Jackowski, M., Goshtasby, A., Roseman, D., Bines, S., Yu, C., Dhawan, A. & Huntley, A. 1999. Segmentation of skin cancer images. *Image and Vision Computing*, 17, (1), 65-74.





Xu, L., Jackowski, M., Goshtasby, A., Roseman, D., Bines, S., Yu, C., Dhawan, A. & Huntley, A. 1999. Segmentation of skin cancer images. *Image and Vision Computing*, 17, (1), 65-74.





$$\mathcal{D} = x_{1:n} = \{x_1, x_2, \dots, x_n\} \quad p(\mathcal{D}|\theta)$$



$$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta) * p(\theta)}{p(\mathcal{D})}$$

**The inverse probability allows to learn from data, infer unknowns, and make predictions**

Observed data:



$\approx$  Training data:  $\mathcal{D} = x_{1:n} = \{x_1, x_2, \dots, x_n\}$

Feature Parameter:  $\theta$  or hypothesis  $h$   $h \in \mathcal{H}$

Prior belief  $\approx$  prior probability of hypothesis  $h$ :  $p(\theta)$   $p(h)$

Likelihood  $\approx p(x)$  of the data that  $h$  is true  $p(\mathcal{D}|\theta)$   $p(d|h)$

Data evidence  $\approx$  marginal  $p(x)$  that  $h = \text{true}$   $p(\mathcal{D})$   $\sum_{h \in \mathcal{H}} p(d|h) * p(h)$

Posterior  $\approx p(x)$  of  $h$  after seen (“learn”) data  $d$   $p(\theta|\mathcal{D})$   $p(h|d)$

$$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta) * p(\theta)}{p(\mathcal{D})}$$

$$p(h|d) = \frac{p(d|h) * p(h)}{\sum_{h \in \mathcal{H}} p(d|h) p(h)}$$



# Why is this relevant for medicine?



- Take patient information, e.g., observations, symptoms, test results, -omics data, etc. etc.
- Reach conclusions, and **predict** into the future, e.g. how likely will the patient be ...
- Prior = belief before making a particular observation
- Posterior = belief after making the observation and is the prior for the next observation – intrinsically incremental


$$p(x_i|y_j) = \frac{p(y_j|x_i)p(x_i)}{\sum p(x_i, y_j)p(x_i)}$$

# Probabilistic Decision Making

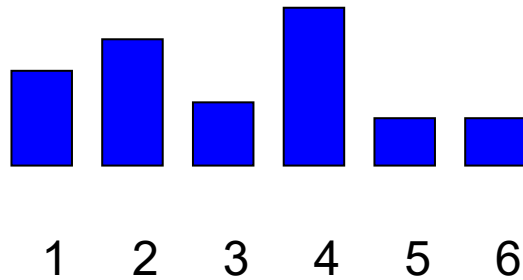
*“It is remarkable that a science which began with the consideration of games of chance should have become the most important object of human knowledge”*

Pierre Simon de Laplace, 1812

- *Probability*  $p(x)$  is the formal study of laws of chance and managing uncertainty; allows to measure (many) events
  - Frequentist\* view: coin toss
  - Bayesian\* view: probability as a measure of belief (this is what made machine learning successful)
  - $p(x) = 1$  means that all events occur for certain
  - Information is a measure for the reduction of uncertainty
  - If something is 100 % certain its uncertainty = 0
  - Uncertainty is max. if all choices are equally probable (I.I.D = independent and identically distributed)
  - Uncertainty (as information) sums up for independent sources:  $\sum_x p(x = X) = 1$

\*) Bayesian vs. Frequentist - please watch the excellent video of Kristin Lennox (2016): <https://www.youtube.com/watch?v=eDMGDhyDxuY>

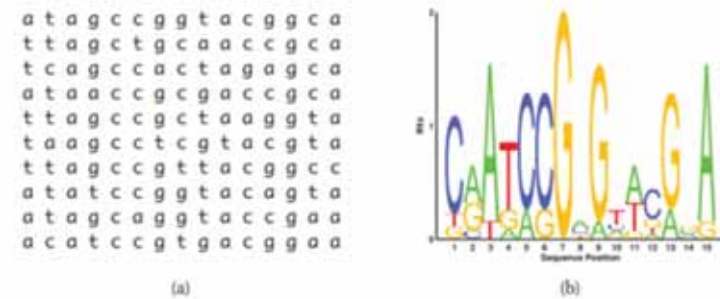
## Discrete distributions:



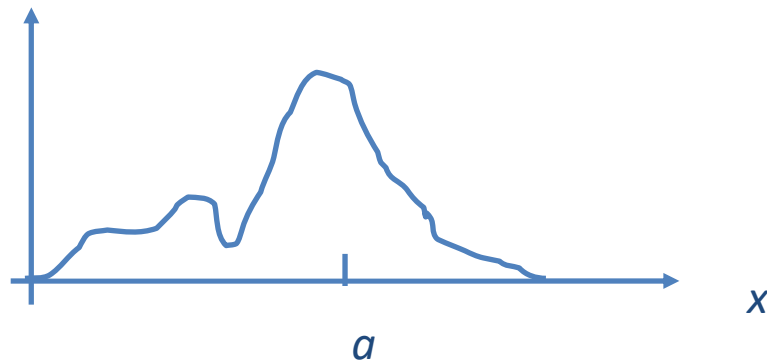
$$\sum_i P(X = x_i) = 1$$

Name	$n$	$K$	$x$
Multinomial	-	-	$\mathbf{x} \in \{0, 1, \dots, n\}^K, \sum_{k=1}^K x_k = n$
Multinoulli	1	-	$\mathbf{x} \in \{0, 1\}^K, \sum_{k=1}^K x_k = 1$ (1-of- $K$ encoding)
Binomial	-	1	$x \in \{0, 1, \dots, n\}$
Bernoulli	1	1	$x \in \{0, 1\}$

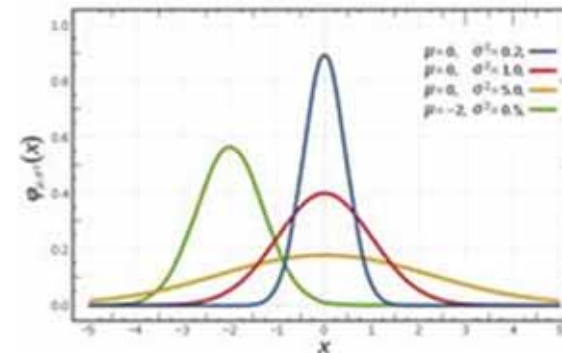
Table 2.1 Summary of the multinomial and related distributions.



## Continuous: Probability density function (PDF) vs Cumulative Density Function (CDF):

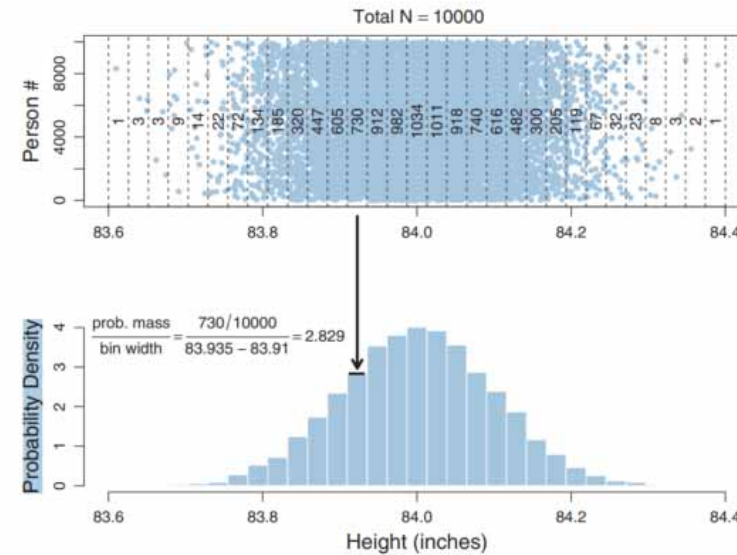
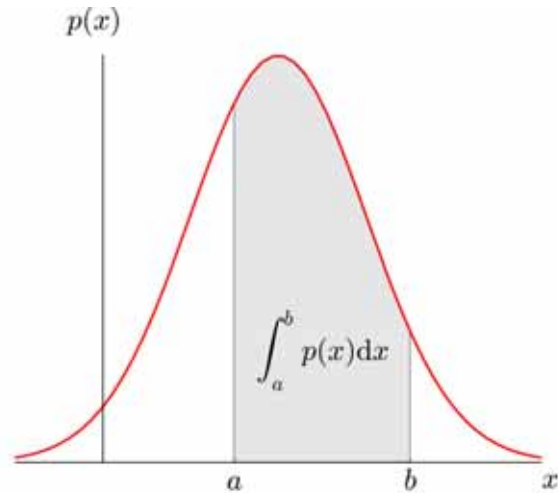


$$P(x \leq a) = \int_{-\infty}^a f(\tau) d\tau$$

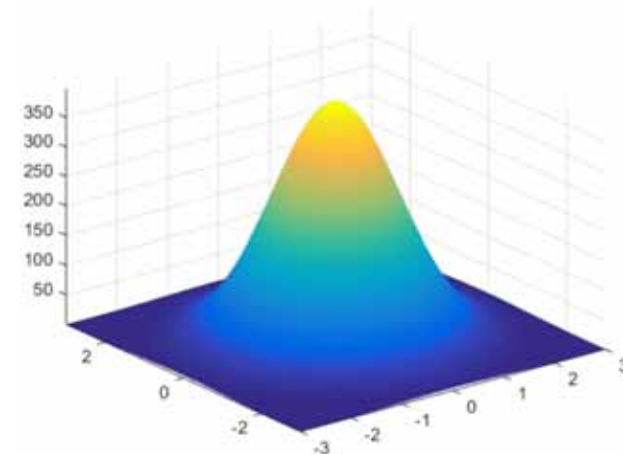
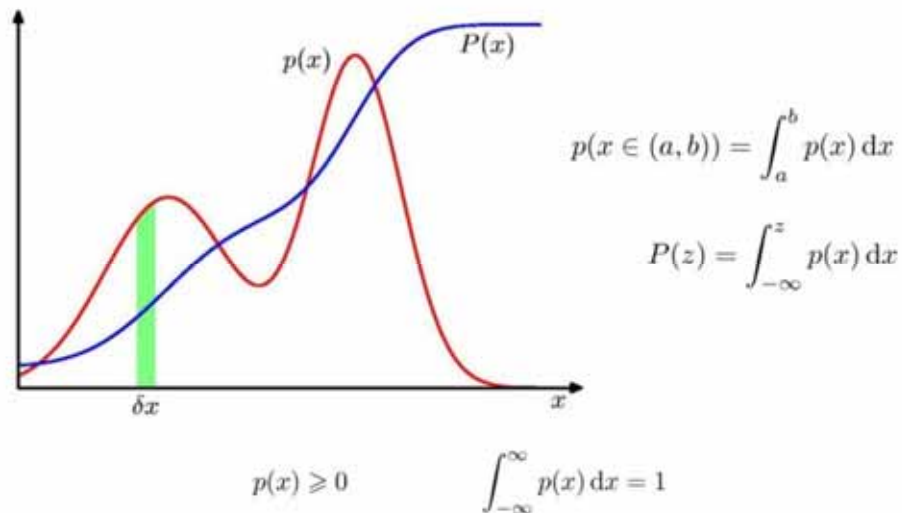


$$\mathcal{N}(x|\mu, \sigma^2) \triangleq \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2}$$



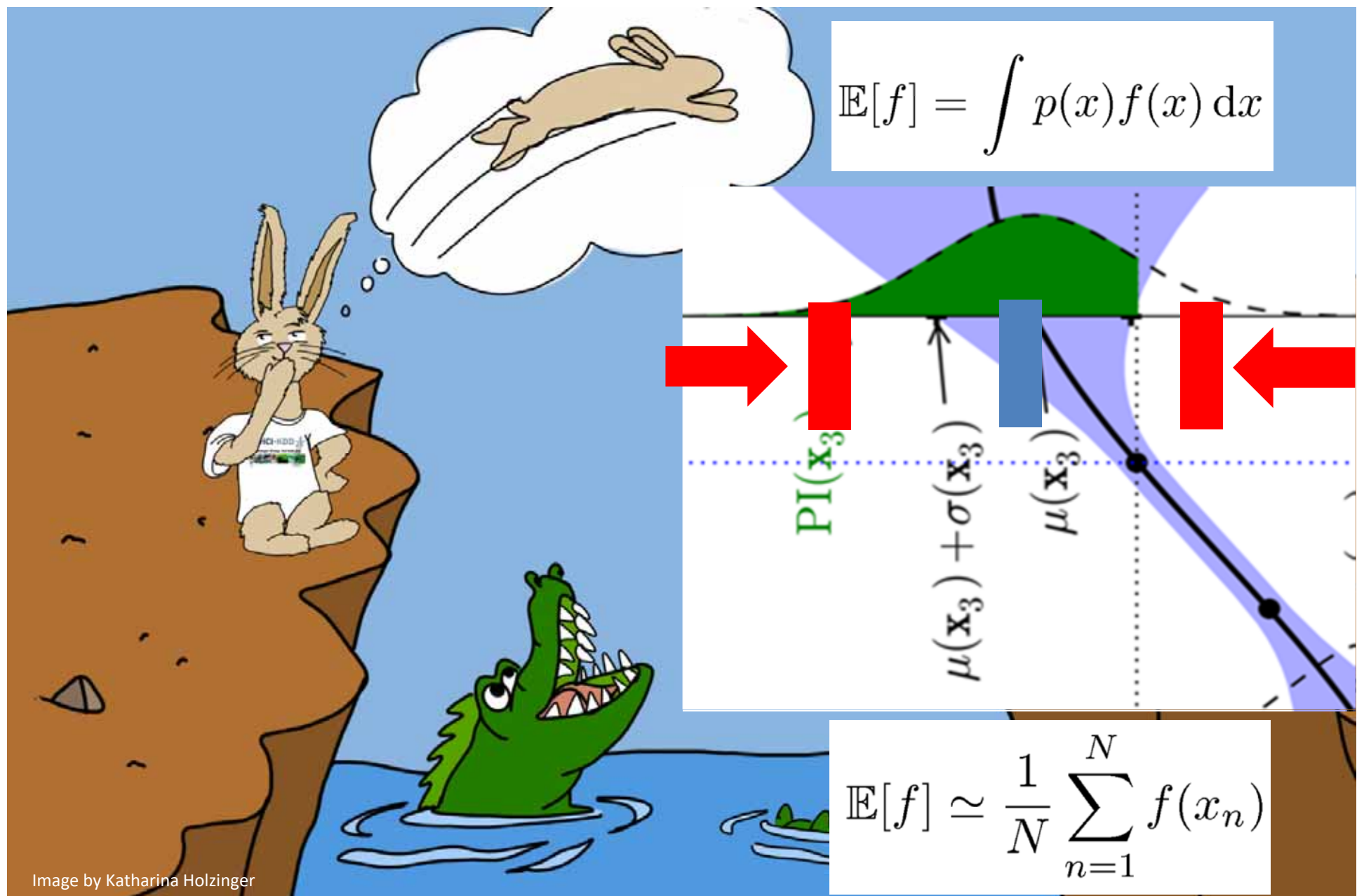


John Kruschke 2014. Doing Bayesian data analysis: A tutorial with R, JAGS, and Stan, Amsterdam et al., Academic Press.



<https://brilliant.org/wiki/multivariate-normal-distribution>

# Expectation and Expected Utility Theory



For a single decision variable an agent can select  $D = d$  for any  $d \in \text{dom}(D)$ .

The expected utility of decision  $D = d$  is



<http://www.eoht.info/page/Oskar+Morgenstern>

$$E(U \mid d) = \sum_{x_1, \dots, x_n} P(x_1, \dots, x_n \mid d) U(x_1, \dots, x_n, d)$$

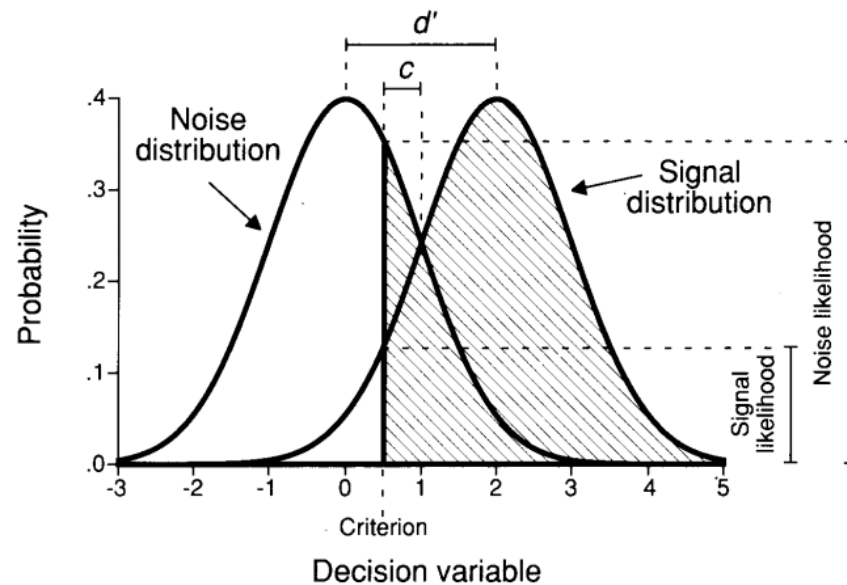
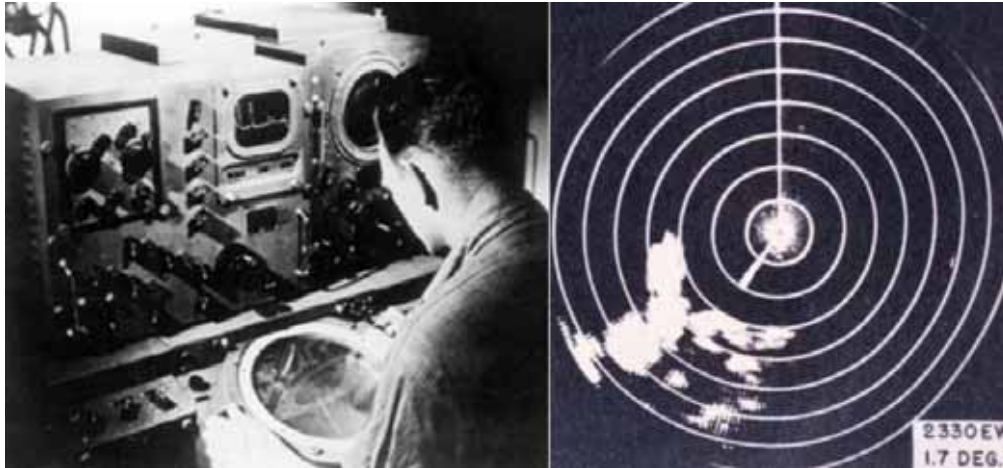
An optimal single decision is the decision  $D = d_{\max}$  whose expected utility is maximal:

$$d_{\max} = \arg \max_{d \in \text{dom}(D)} E(U \mid d)$$

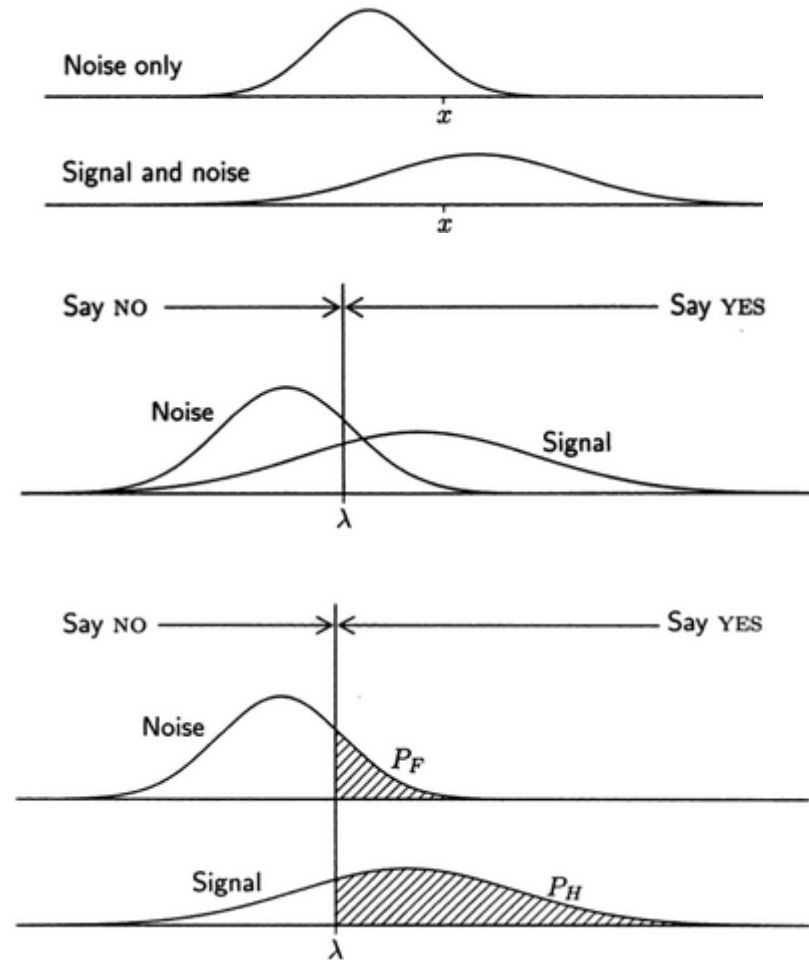
John Von Neumann & Oskar Morgenstern 1944. Theory of games and economic behavior, Princeton university press.

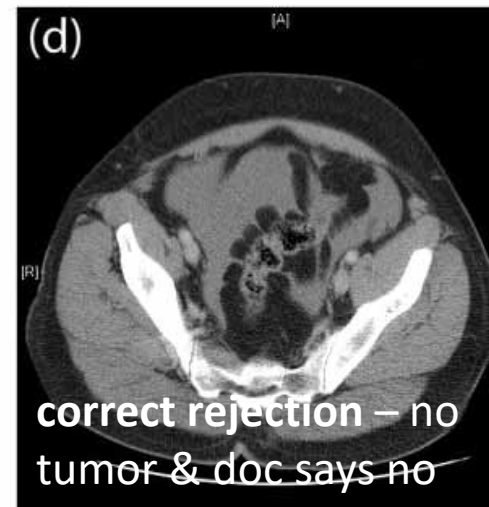
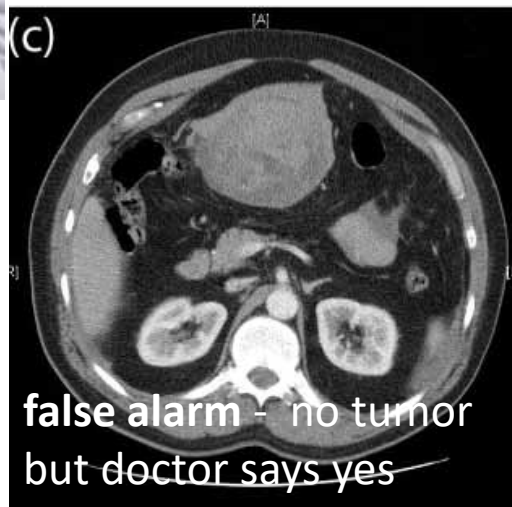
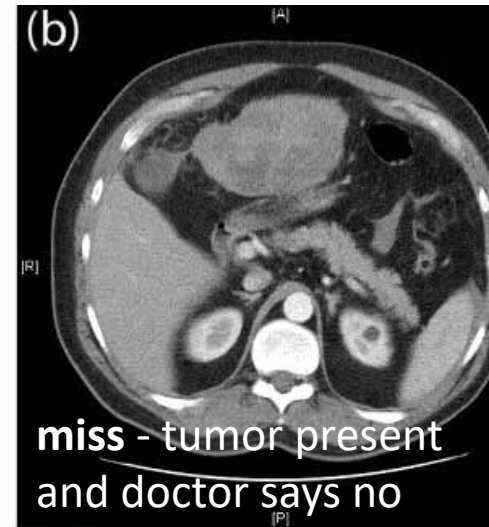
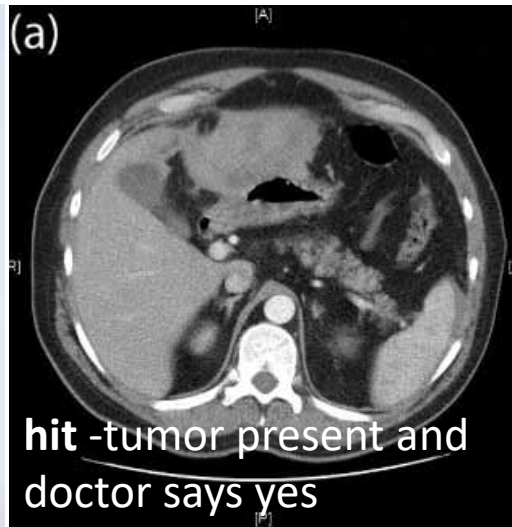


Image source: Staffordshire University Computing Futures Museum <http://www.fcet.staffs.ac.uk/jdw1/sucfm/malvern.htm>



Stanislaw, H. & Todorov, N. 1999. Calculation of signal detection theory measures. Behavior research methods, instruments, & computers, 31, (1), 137-149.





Two doctors, with equally good training, looking at the same CT scan, will have the same information ... but they may have a **different bias/criteria!**

Remember: Two doctors, with equally good training, looking at the same CT scan data, will have the same information ... but they may gain different knowledge due to *bias/criteria*.

		SIGNAL	
		present	absent
RESPONSE	yes	hit	false alarm
	no	miss	correct rejection

*Positive = identified and negative = rejected*

True positive = correctly identified (hit)

False positive = incorrectly identified, false alarm, type I error

True negative = correctly rejected (correct rejection)

False negative = incorrectly rejected, miss, type II error

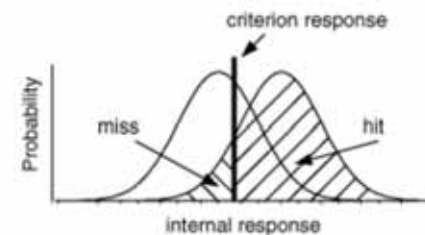
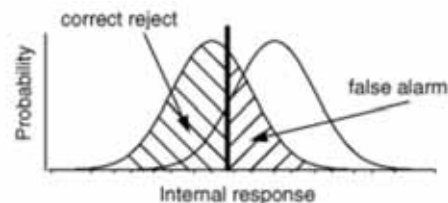
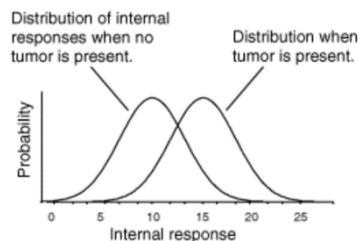
sensitivity, recall, hit rate, or true positive rate (TPR)

$$\text{TPR} = \frac{\text{TP}}{P} = \frac{\text{TP}}{\text{TP} + \text{FN}} = 1 - \text{FNR}$$

specificity, selectivity or true negative rate (TNR)

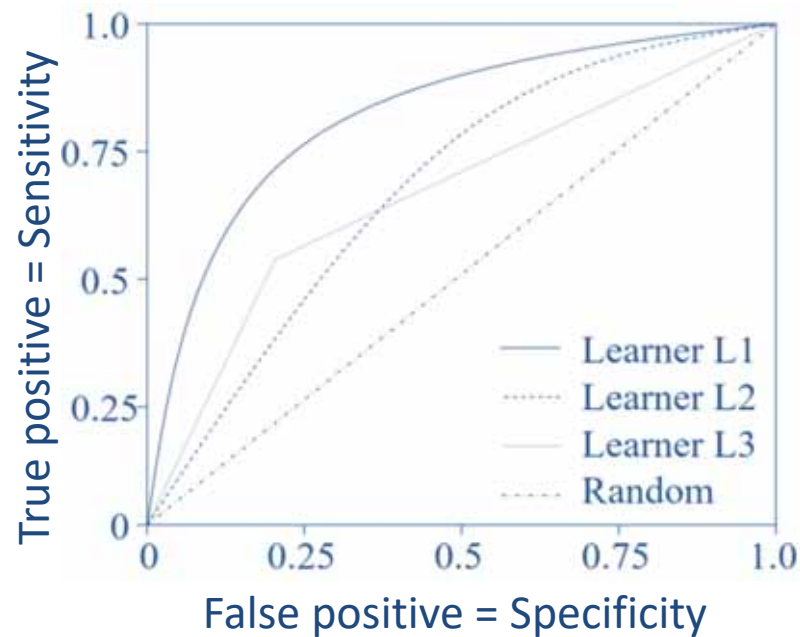
$$\text{TNR} = \frac{\text{TN}}{N} = \frac{\text{TN}}{\text{TN} + \text{FP}} = 1 - \text{FPR}$$

[https://en.wikipedia.org/wiki/Sensitivity\\_and\\_specificity](https://en.wikipedia.org/wiki/Sensitivity_and_specificity)

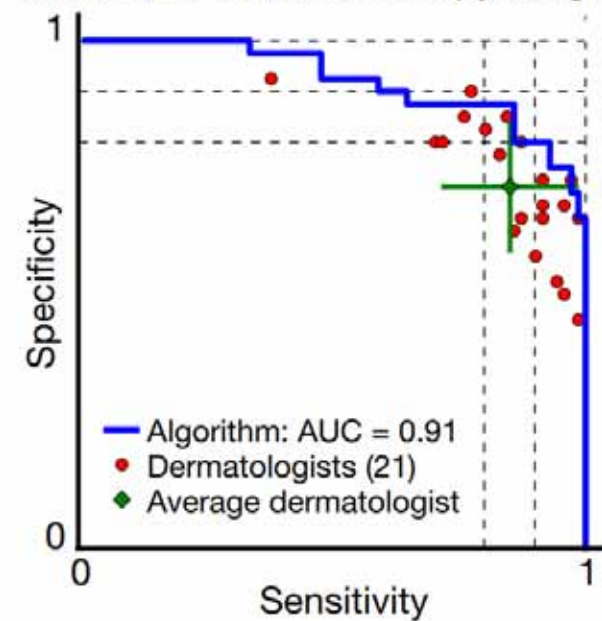


For an example see: Braga & Oliveira (2003) Diagnostic analysis based on ROC curves: theory and applications in medicine. *Int. Journal of Health Care Quality Assurance*, 16, 4, 191-198.

And please look up the Wikipedia page:  
human-centered.ai (Holzinger Group)

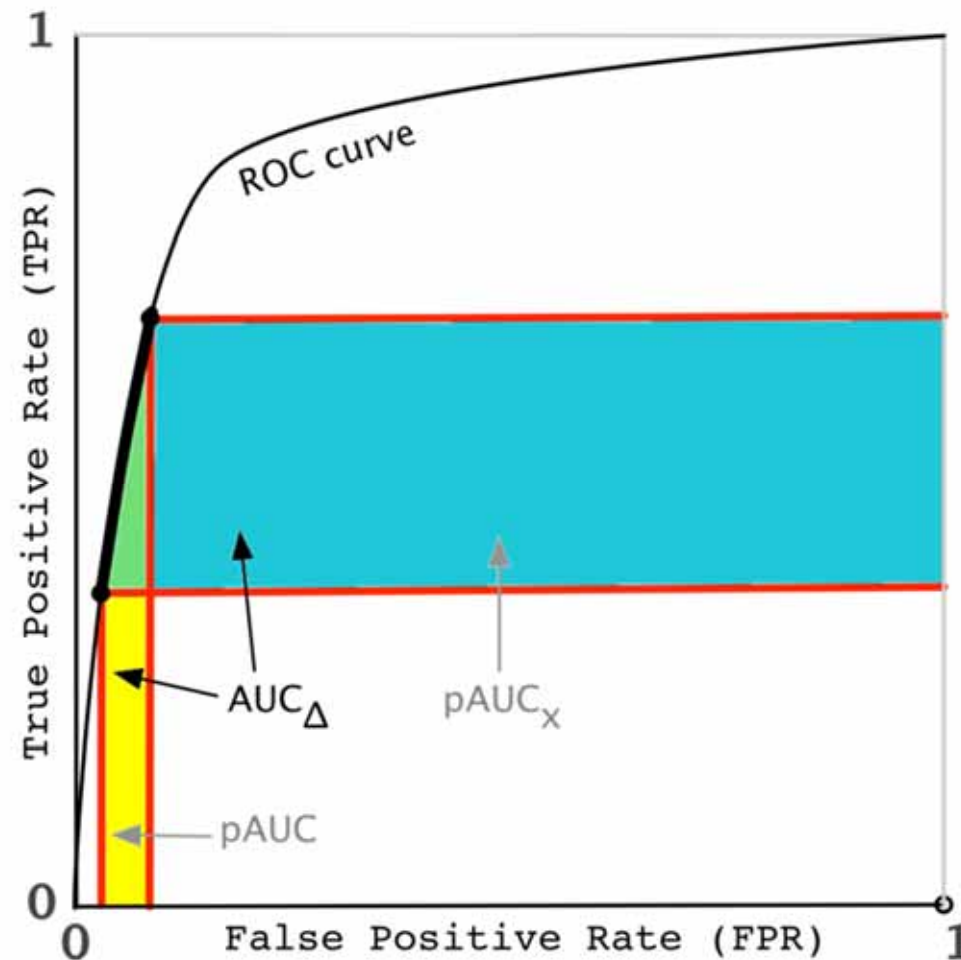


Melanoma: 111 dermoscopy images



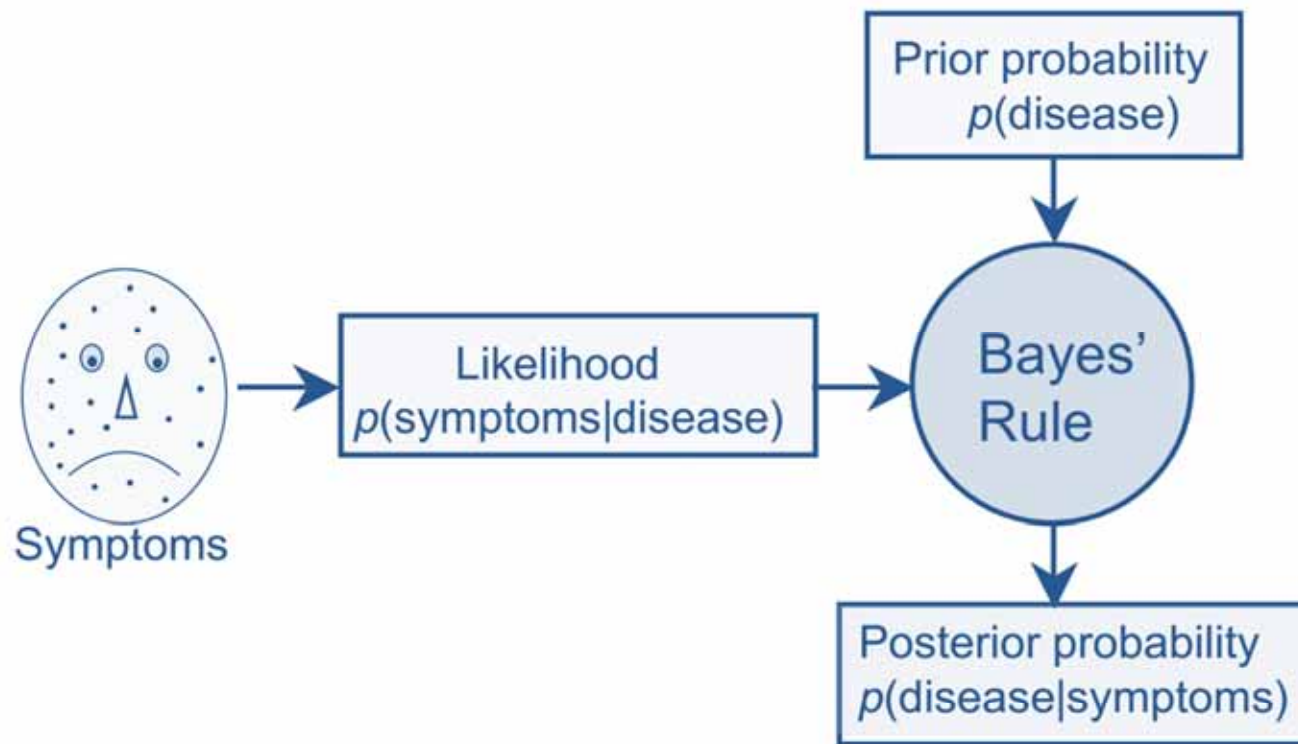
Andrew P. Bradley 1997. The use of the area under the ROC curve in the evaluation of machine learning algorithms. *Pattern Recognition*, 30, (7), 1145-1159, doi:[http://dx.doi.org/10.1016/S0031-3203\(96\)00142-2](http://dx.doi.org/10.1016/S0031-3203(96)00142-2).





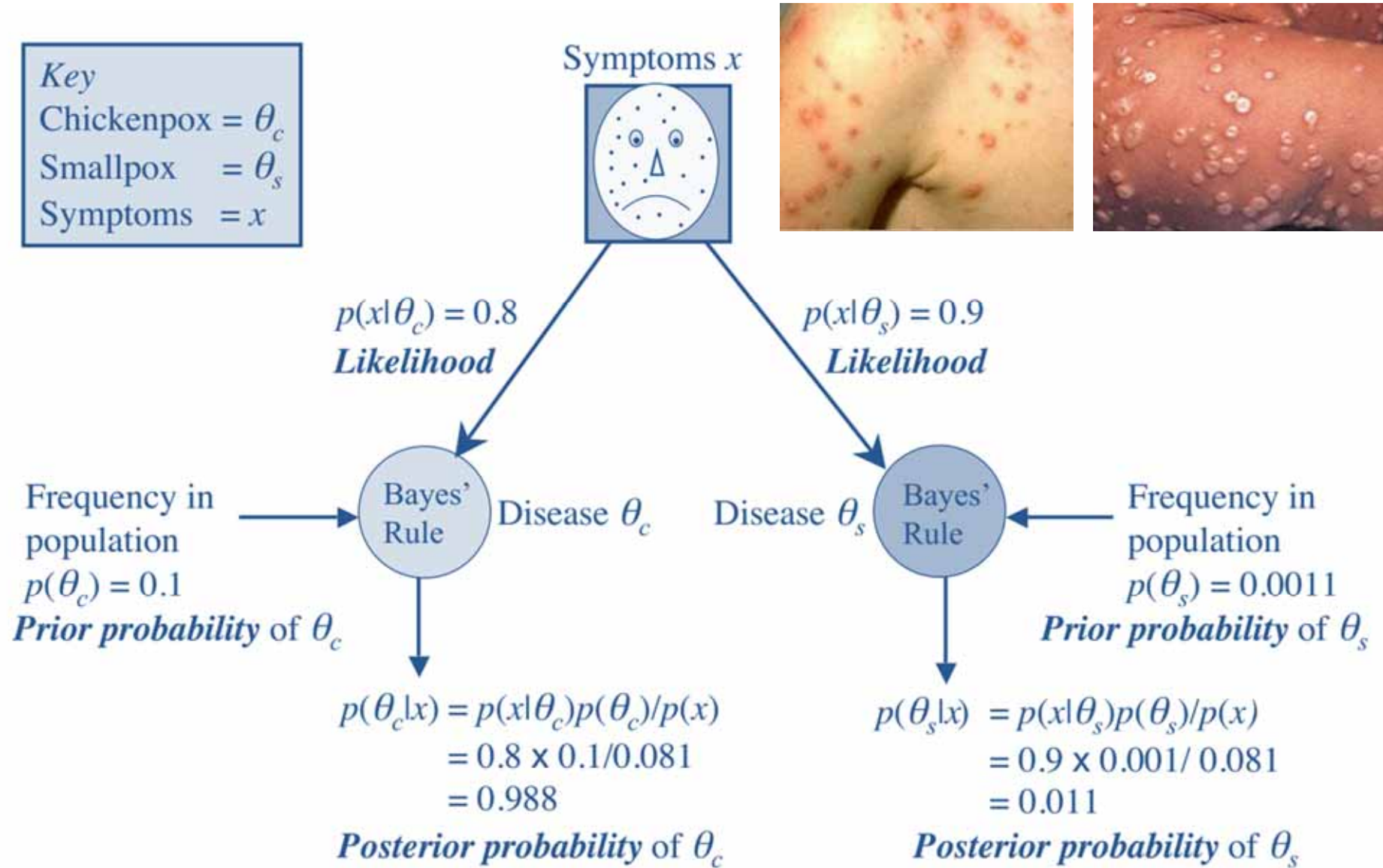
André M. Carrington, Paul W. Fieguth, Hammad Qazi, Andreas Holzinger, Helen H. Chen, Franz Mayr & Douglas G. Manuel 2020. A new concordant partial AUC and partial c statistic for imbalanced data in the evaluation of machine learning algorithms. Springer/Nature BMC Medical Informatics and Decision Making, 20, (1), 4, doi:10.1186/s12911-019-1014-6.

<https://bmcmmedinformdecismak.biomedcentral.com/articles/10.1186/s12911-019-1014-6>



$$p(\text{disease}|\text{symptoms}) = \frac{p(\text{symptoms}|\text{disease})p(\text{disease})}{p(\text{symptoms})}$$

James V. Stone 2013. Bayes' rule: a tutorial introduction to Bayesian analysis. Sebtel Press.



James V. Stone 2013. Bayes' rule: a tutorial introduction to Bayesian analysis. Sebtel Press.

- Your MD has bad news and good news for you.
- Bad news first: You are tested positive for a serious disease, and the test is 99% accurate if you are infected (T)
- Good news: It is a rare disease, striking 1 in 10,000 (D)
- **How worried would you now be?**

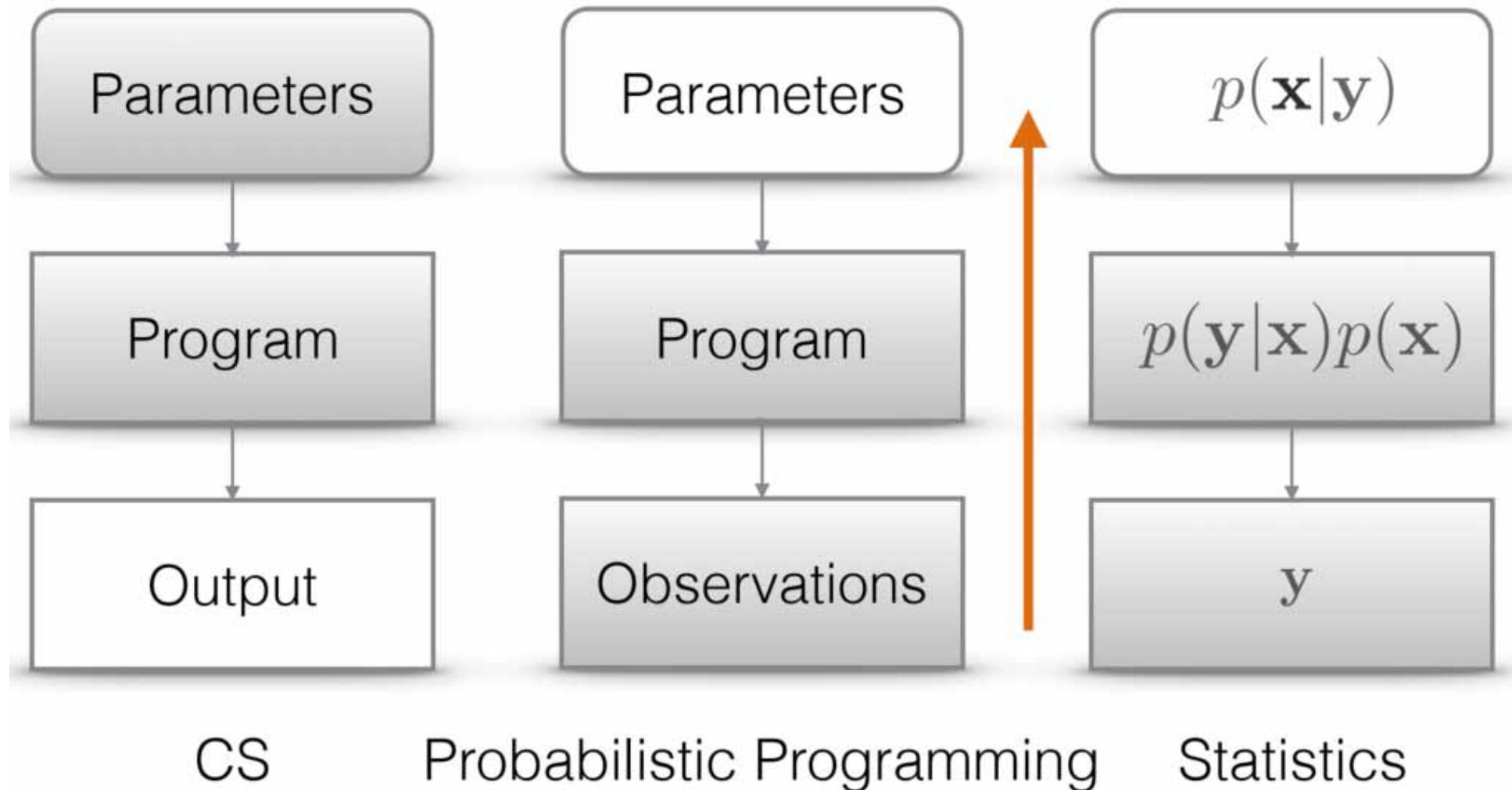
$$\text{posterior } p(x) = \frac{\text{likelihood} * \text{prior } p(x)}{\text{evidence}} \quad p(h|d) = \frac{p(d|h)p(h)}{p(d)}$$

$$p(T = 1|D = 1) = p(d|h) = 0,99 \text{ and} \\ p(D = 1) = p(h) = 0,0001$$

$$p(D = 1 | T = 1) = \frac{(0,99)*(0,0001)}{(1-0,99)*(1-0,0001)+0,99*0,0001} = \\ = \mathbf{0,0098}$$



## Inference



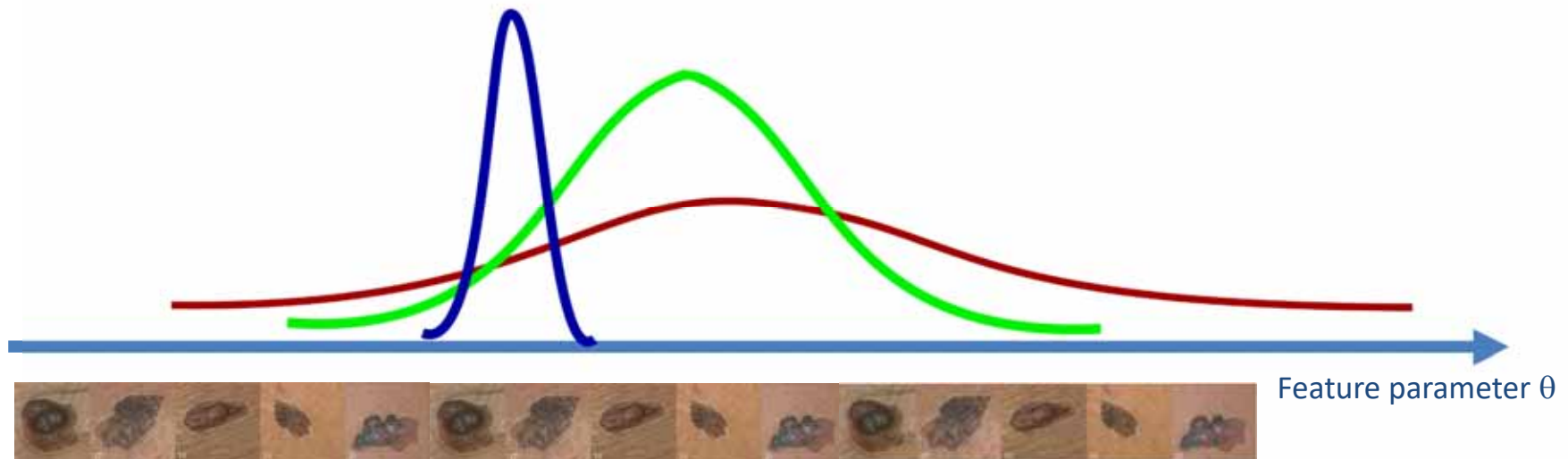
Jan-Willem Van De Meent, Brooks Paige, Hongseok Yang & Frank Wood 2018. An introduction to probabilistic programming. arXiv preprint arXiv:1809.10756.

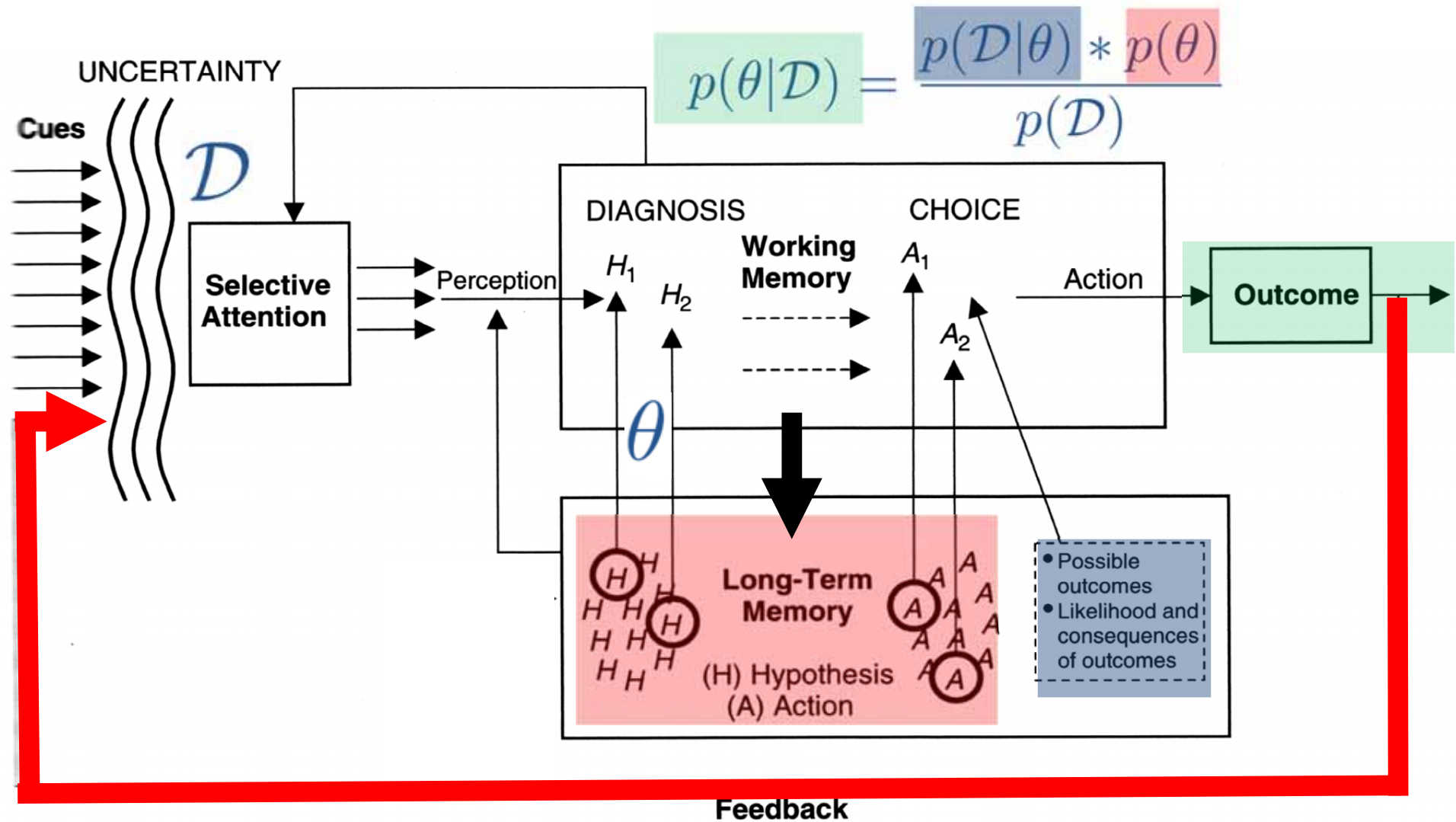
$d$  ... data $\mathcal{H} \dots \{H_1, H_2, \dots, H_n\}$  $\forall h, d \dots$  $h$  ... hypotheses

$$p(h|d) = \frac{p(d|h) * p(h)}{\sum_{h \in \mathcal{H}} p(d|h') p(h')}$$

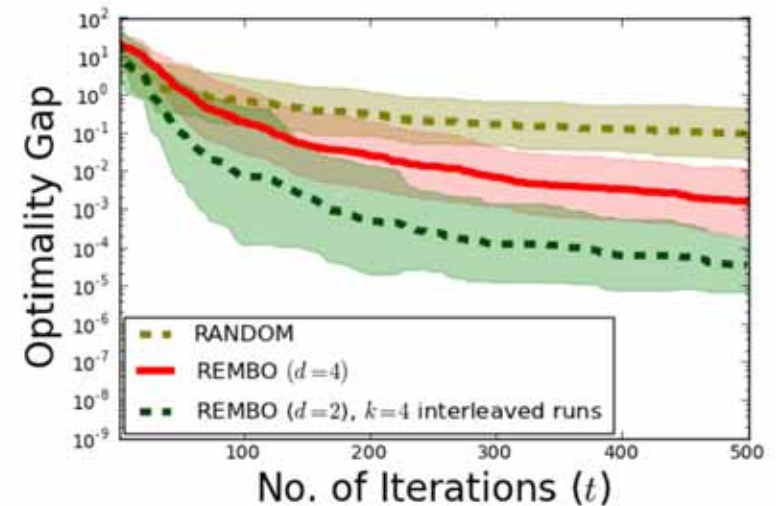
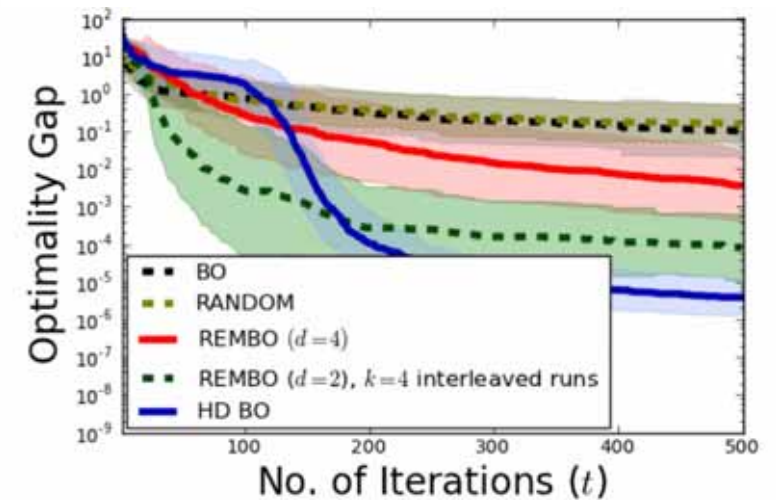
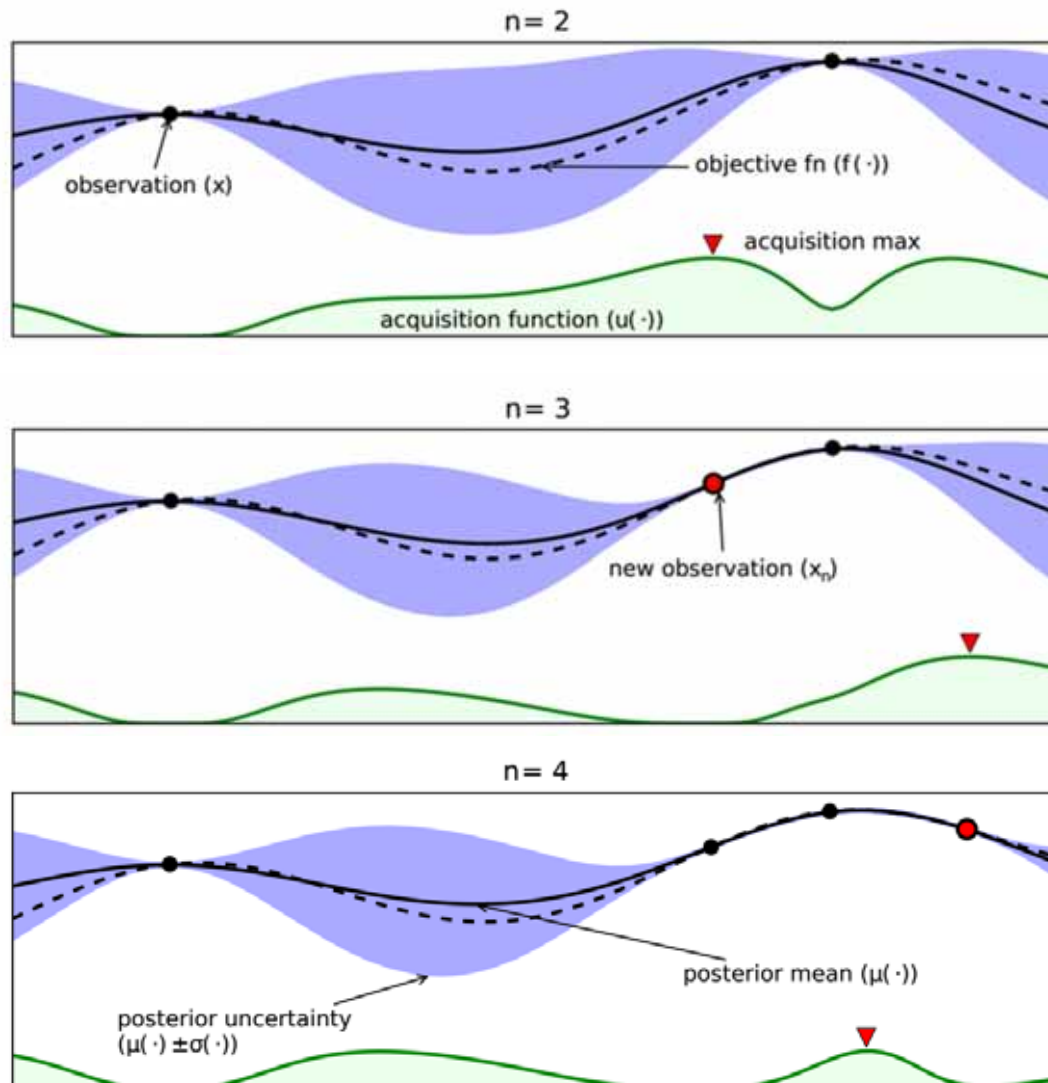
Likelihood      Prior Probability

Posterior Probability

Problem in  $\mathbb{R}^n \rightarrow$  complex



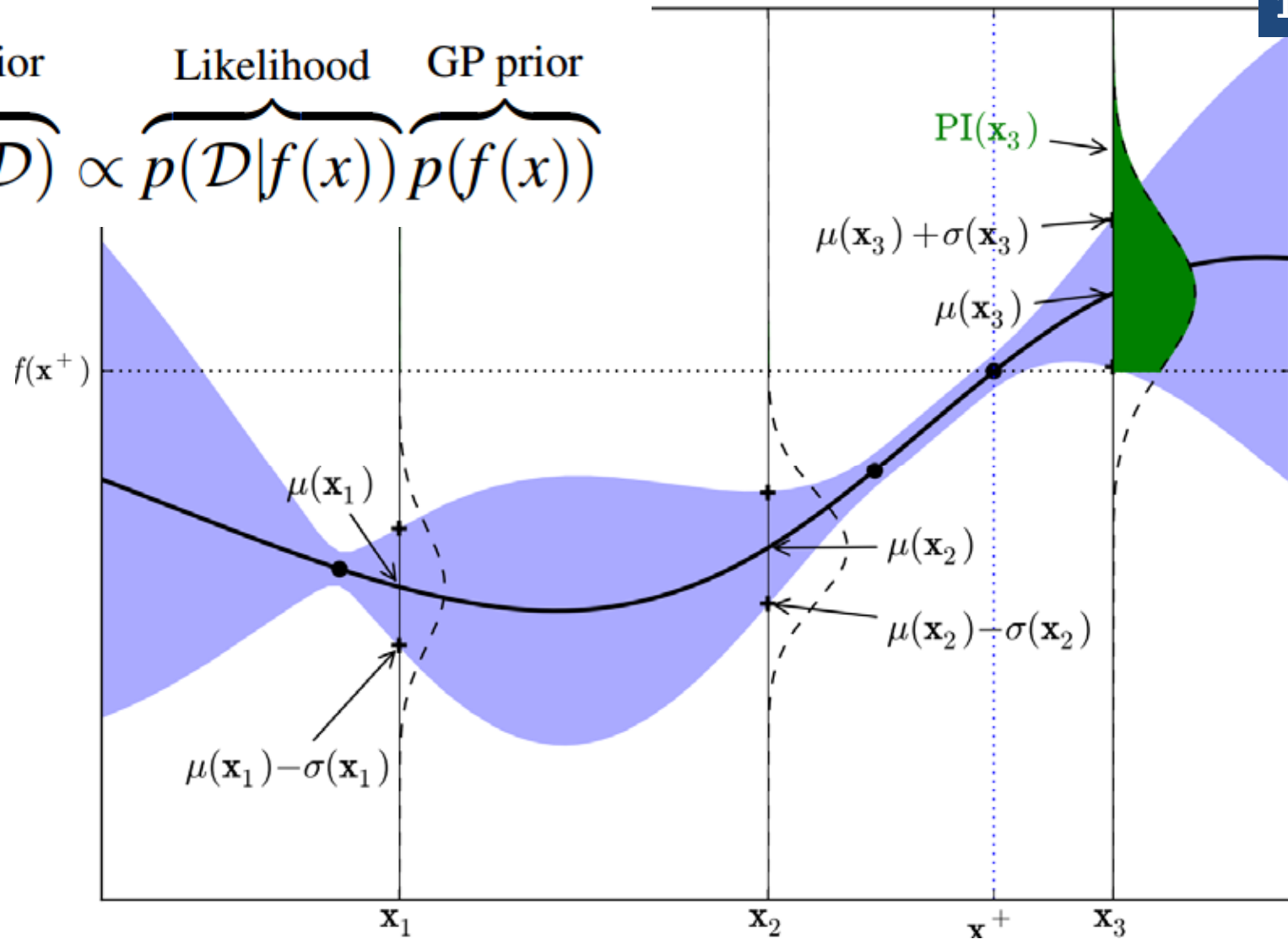
Wickens, C. D. (1984) *Engineering psychology and human performance*.  
Columbus (OH), Charles Merrill, modified by Holzinger, A.



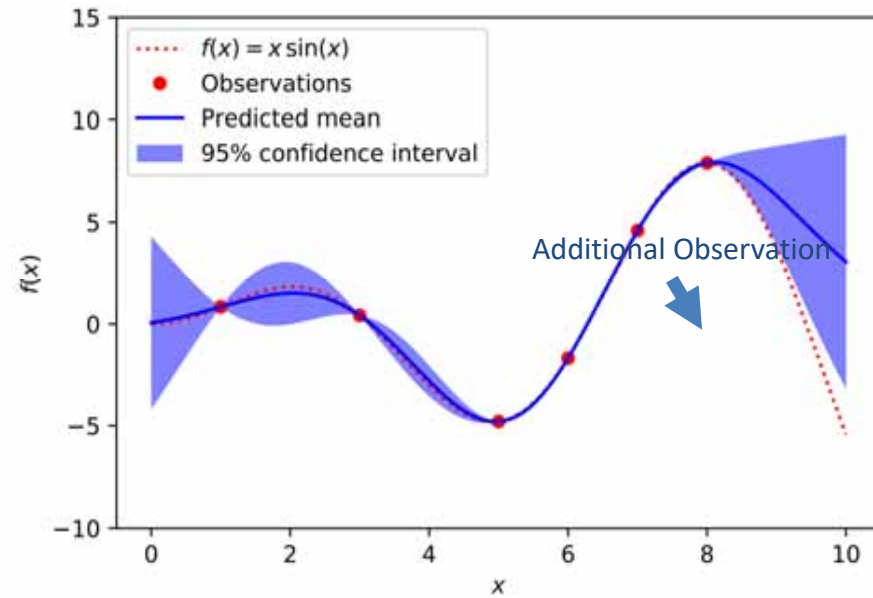
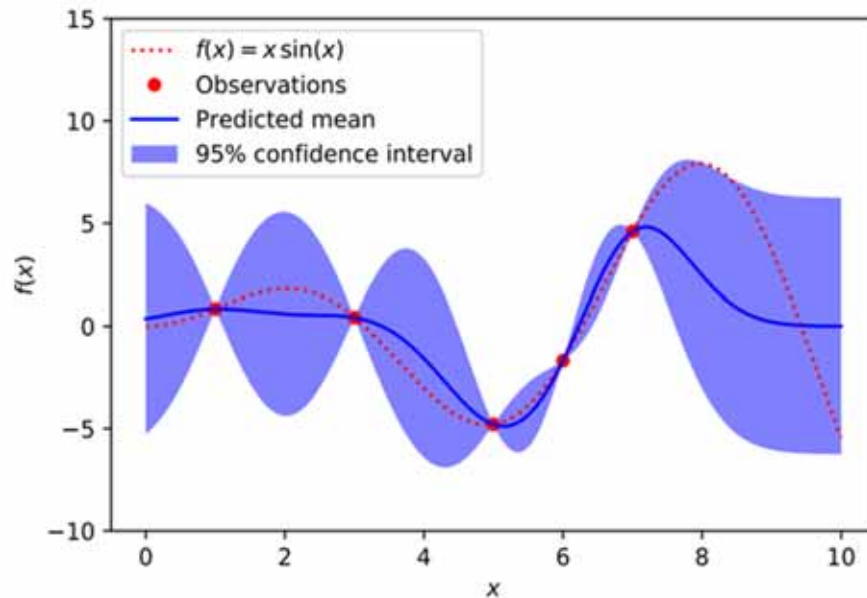
Wang, Z., Hutter, F., Zoghi, M., Matheson, D. & De Feitas, N. 2016. Bayesian optimization in a billion dimensions via random embeddings. Journal of Artificial Intelligence Research, 55, 361-387, doi:10.1613/jair.4806.



$$\overbrace{p(f(x)|\mathcal{D})}^{\text{GP posterior}} \propto \overbrace{p(\mathcal{D}|f(x))}^{\text{Likelihood}} \overbrace{p(f(x))}^{\text{GP prior}}$$



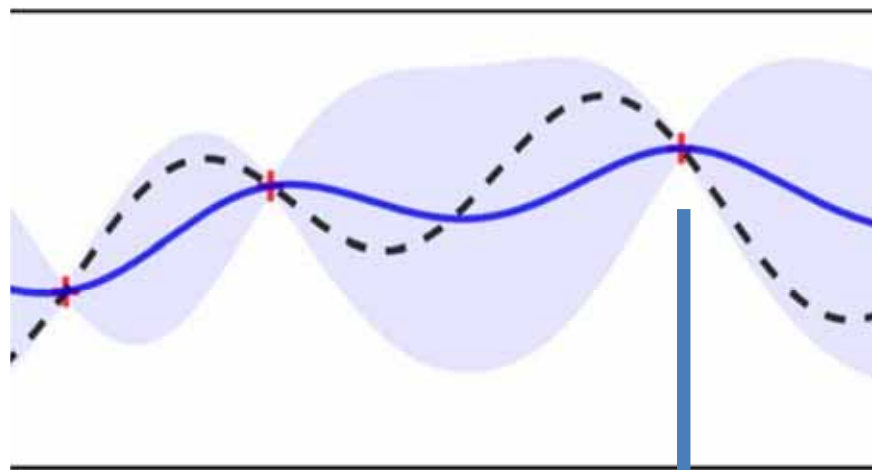
Brochu, E., Cora, V. M. & De Freitas, N. 2010. A tutorial on Bayesian optimization of expensive cost functions, with application to active user modeling and hierarchical reinforcement learning. arXiv:1012.2599.



$$\mathbb{E}[f] = \int p(x) f(x) dx$$

$$\mathbb{E}[f] \simeq \frac{1}{N} \sum_{n=1}^N f(x_n)$$

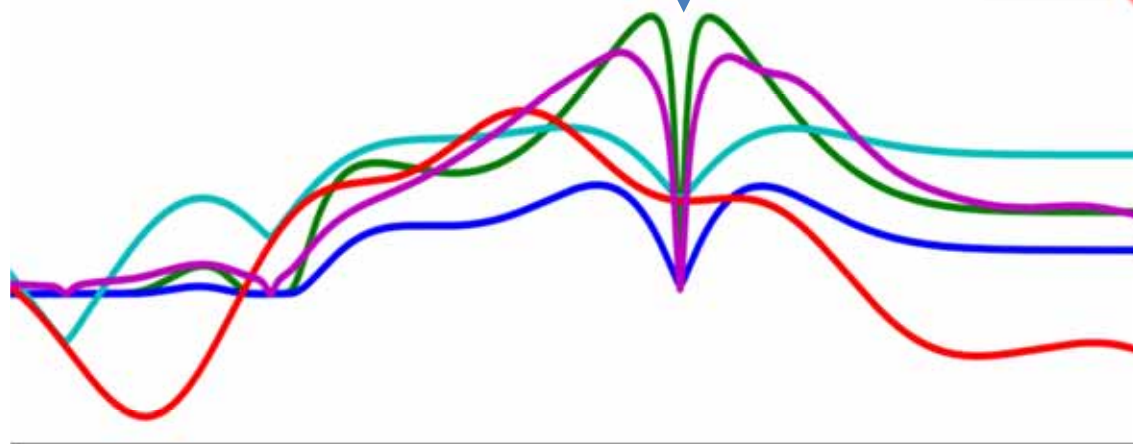
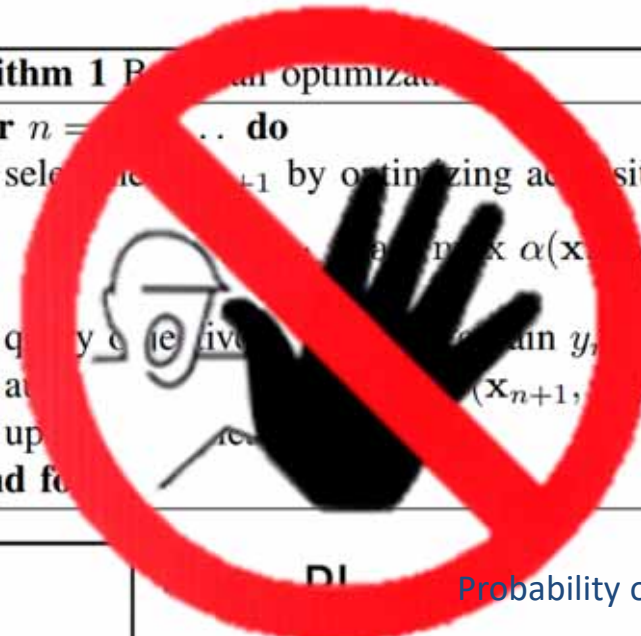
Holzinger, A. 2017. Introduction to Machine Learning and Knowledge Extraction (MAKE). Machine Learning and Knowledge Extraction, 1, (1), 1-20, doi:10.3390/make1010001.

**Algorithm 1** Bayesian optimization

```

1: for  $n = 1, \dots, N$  do
2:   select  $\mathbf{x}_{n+1}$  by optimizing acquisition function  $\alpha$ 
3:   query the objective function to obtain  $y_n$ 
4:   add  $(\mathbf{x}_{n+1}, y_{n+1})$  to the dataset  $\mathcal{D}$ 
5:   update the model  $f$ 
6: end for

```



PI Probability of Improvement

— EI Expected Improvement

— UCB Upper Confidence Bound

— TS Thompson Sampling

— PES Predictive Entropy Search

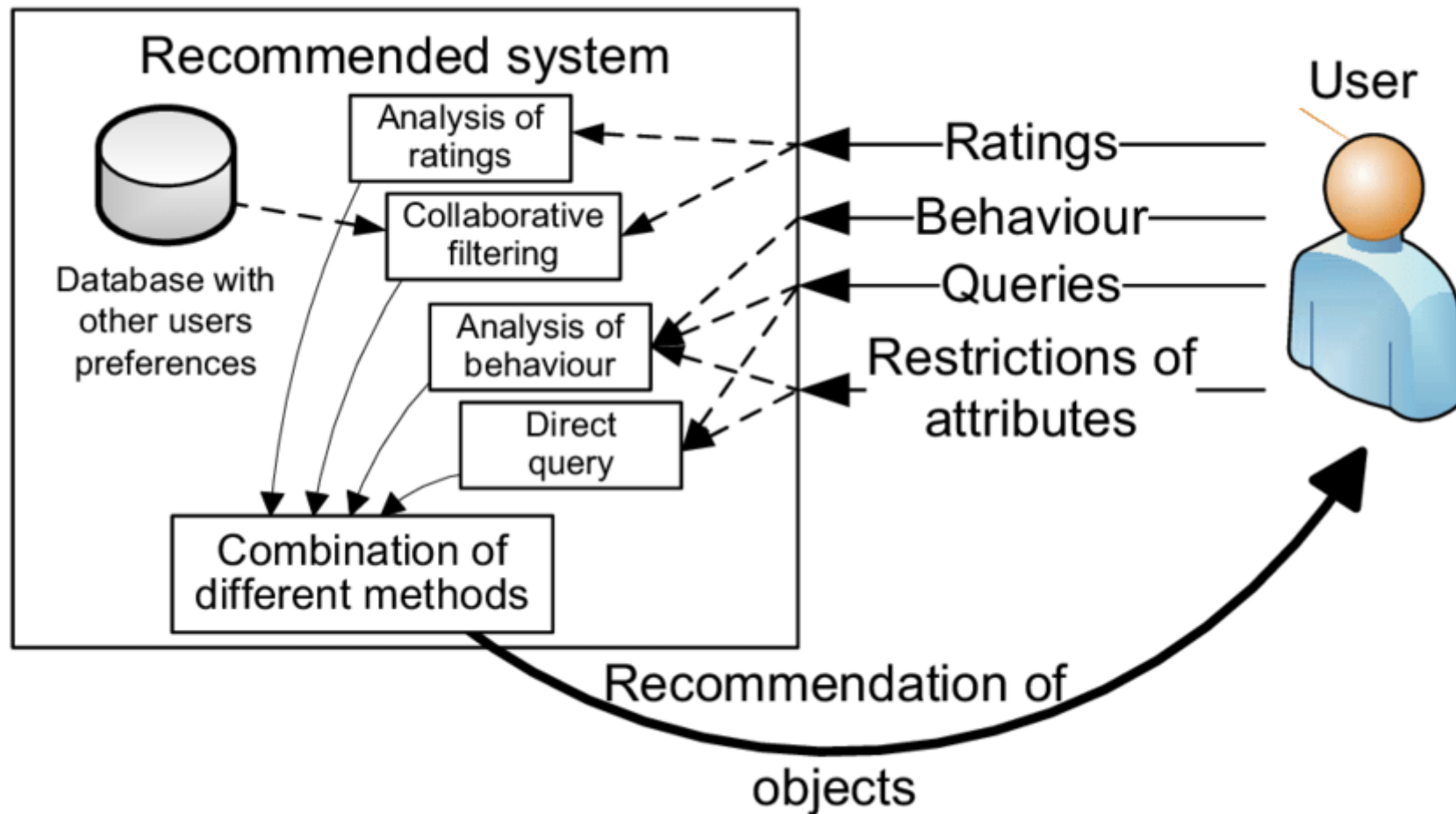
Shahriari, B., Swersky, K., Wang, Z., Adams, R. P. & De Freitas, N. 2016.

**Taking the human out of the loop:** A review of Bayesian optimization.

*Proceedings of the IEEE*, 104, (1), 148-175, doi:10.1109/JPROC.2015.2494218.

## 04 aML





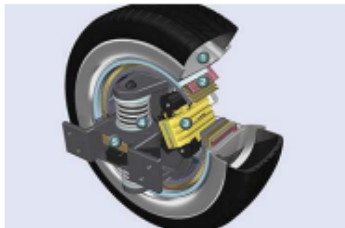
Alan Eckhardt 2009. Various aspects of user preference learning and recommender systems. DATESO. pp. 56-67.



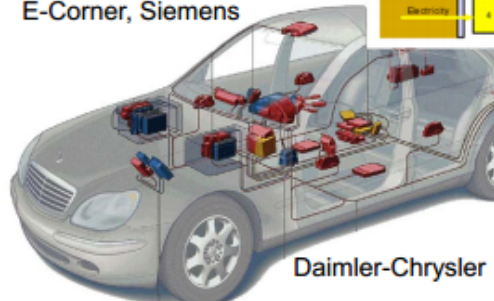
Guizzo, E. 2011. How google's self-driving car works. IEEE Spectrum Online, 10, 18.

## Cyber-Physical Systems (CPS): *Tight integration of networked computation with physical systems*

Automotive

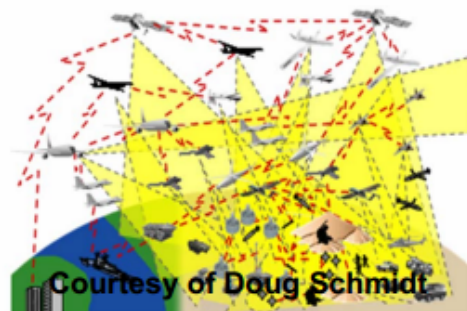


E-Corner, Siemens



Daimler-Chrysler

Military systems:

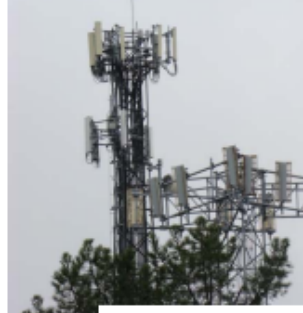


Courtesy of Doug Schmidt

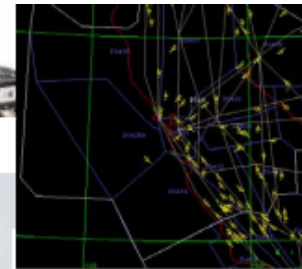
Building Systems



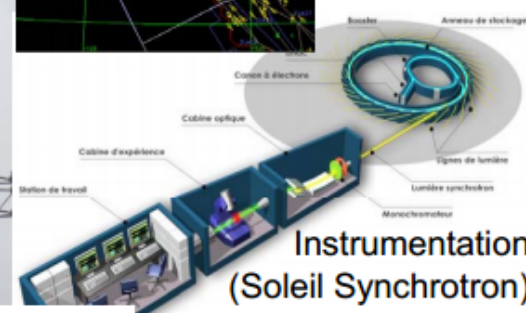
Telecommunications



Avionics



Transportation  
(Air traffic  
control at  
SFO)



Instrumentation  
(Soleil Synchrotron)

Factory automation

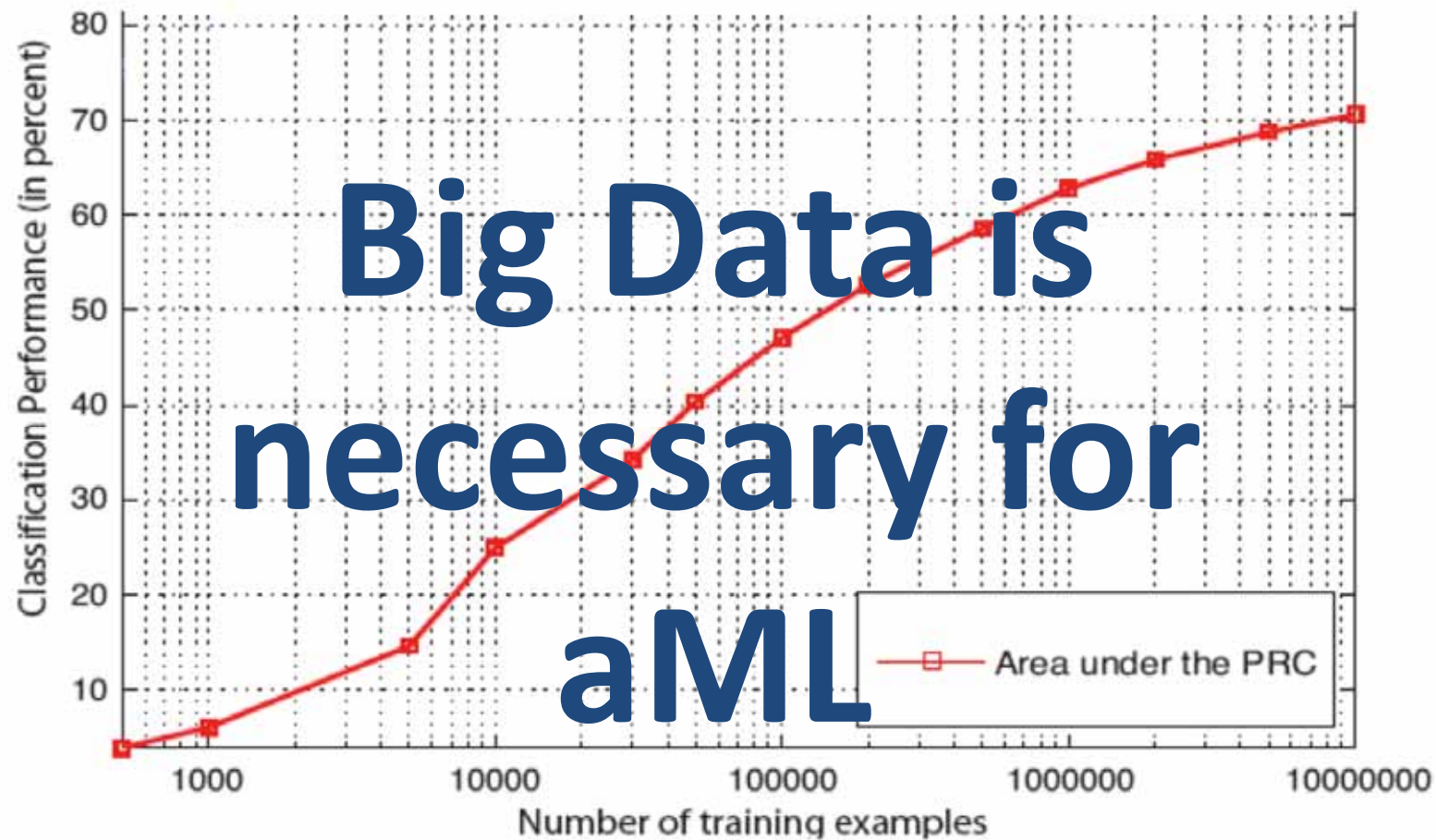


Courtesy of Kuka Robotics Corp.



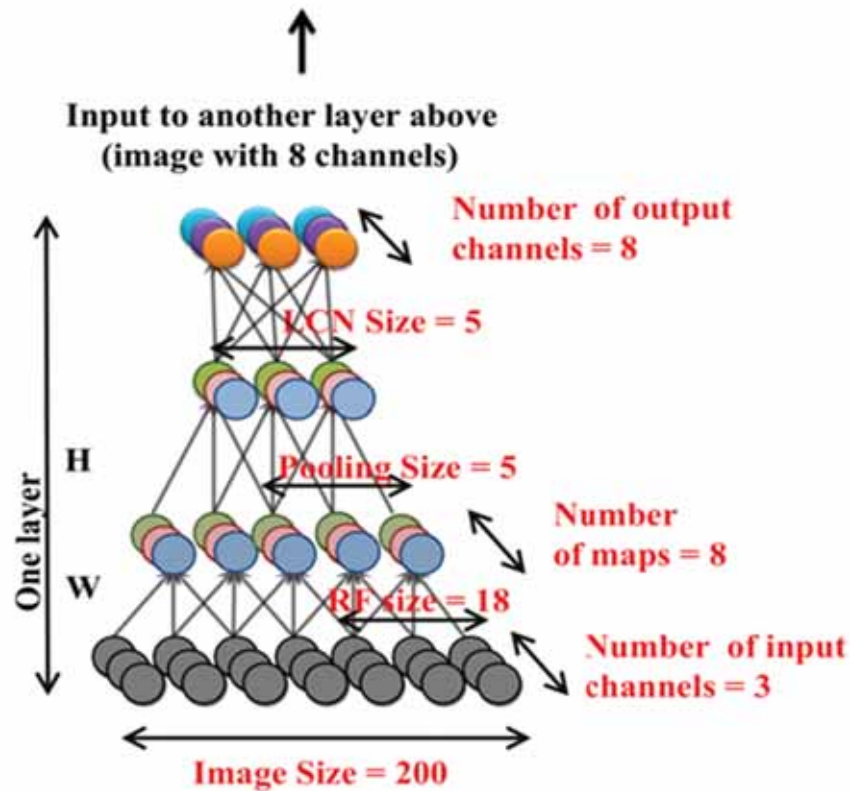
Seshia, S. A., Juniwal, G., Sadigh, D., Donze, A., Li, W., Jensen, J. C., Jin, X., Deshmukh, J., Lee, E. & Sastry, S. 2015.  
Verification by, for, and of Humans: Formal Methods for Cyber-Physical Systems and Beyond. Illinois ECE Colloquium.





Sonnenburg, S., Rätsch, G., Schäfer, C. & Schölkopf, B. 2006. Large scale multiple kernel learning. Journal of Machine Learning Research, 7, (7), 1531-1565.



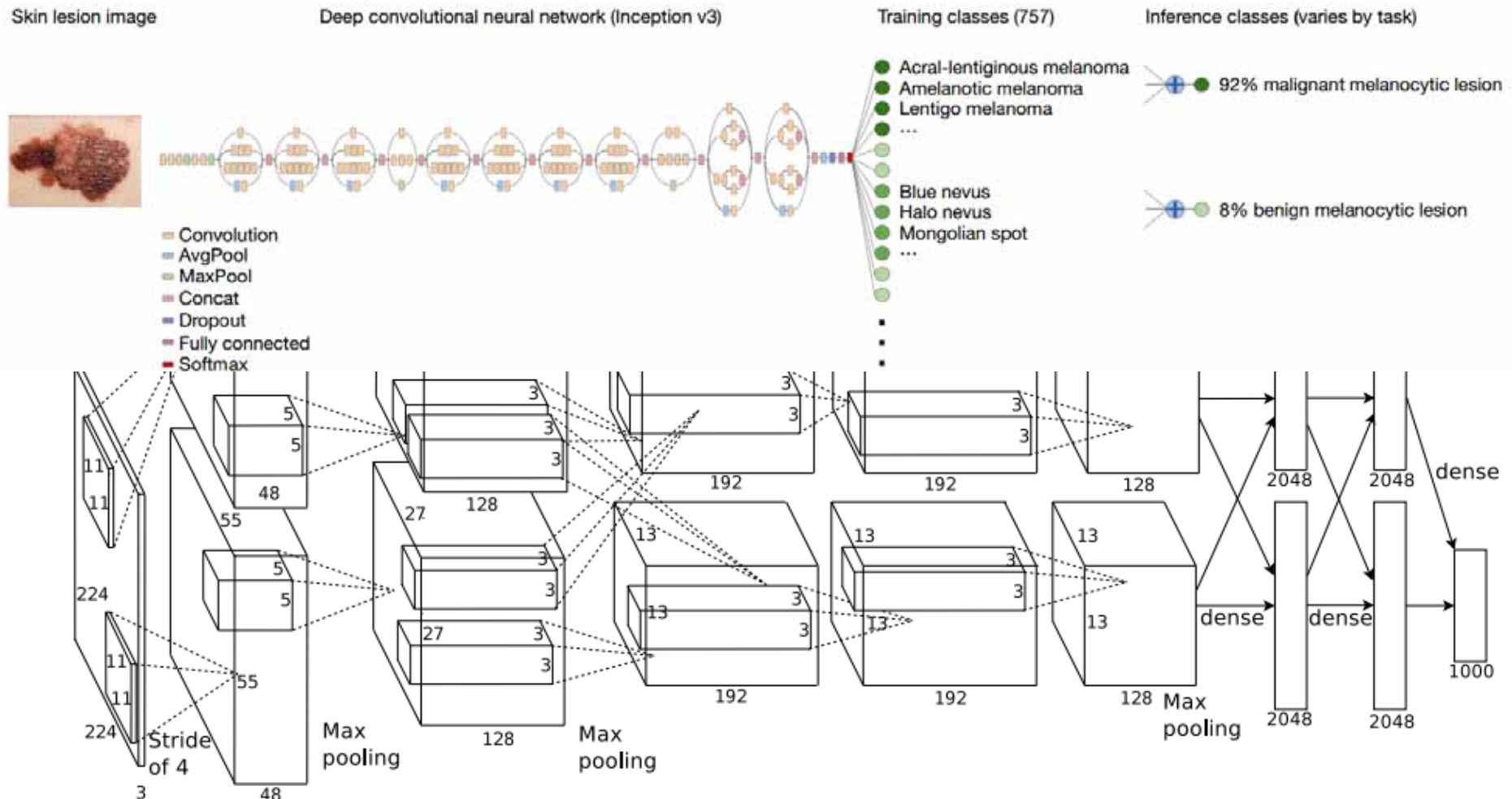


$$x^* = \arg \min_x f(x; W, H), \text{ subject to } \|x\|_2 = 1.$$

Le, Q. V., Ranzato, M. A., Monga, R., Devin, M., Chen, K., Corrado, G. S., Dean, J. & Ng, A. Y. 2011. Building high-level features using large scale unsupervised learning. arXiv preprint arXiv:1112.6209.

Le, Q. V. 2013. Building high-level features using large scale unsupervised learning. *IEEE Intl. Conference on Acoustics, Speech and Signal Processing ICASSP*. IEEE. 8595-8598, doi:10.1109/ICASSP.2013.6639343.

Esteva, A., Kuprel, B., Novoa, R. A., Ko, J., Swetter, S. M., Blau, H. M. & Thrun, S. 2017. Dermatologist-level classification of skin cancer with deep neural networks. Nature, 542, (7639), 115-118, doi:10.1038/nature21056.



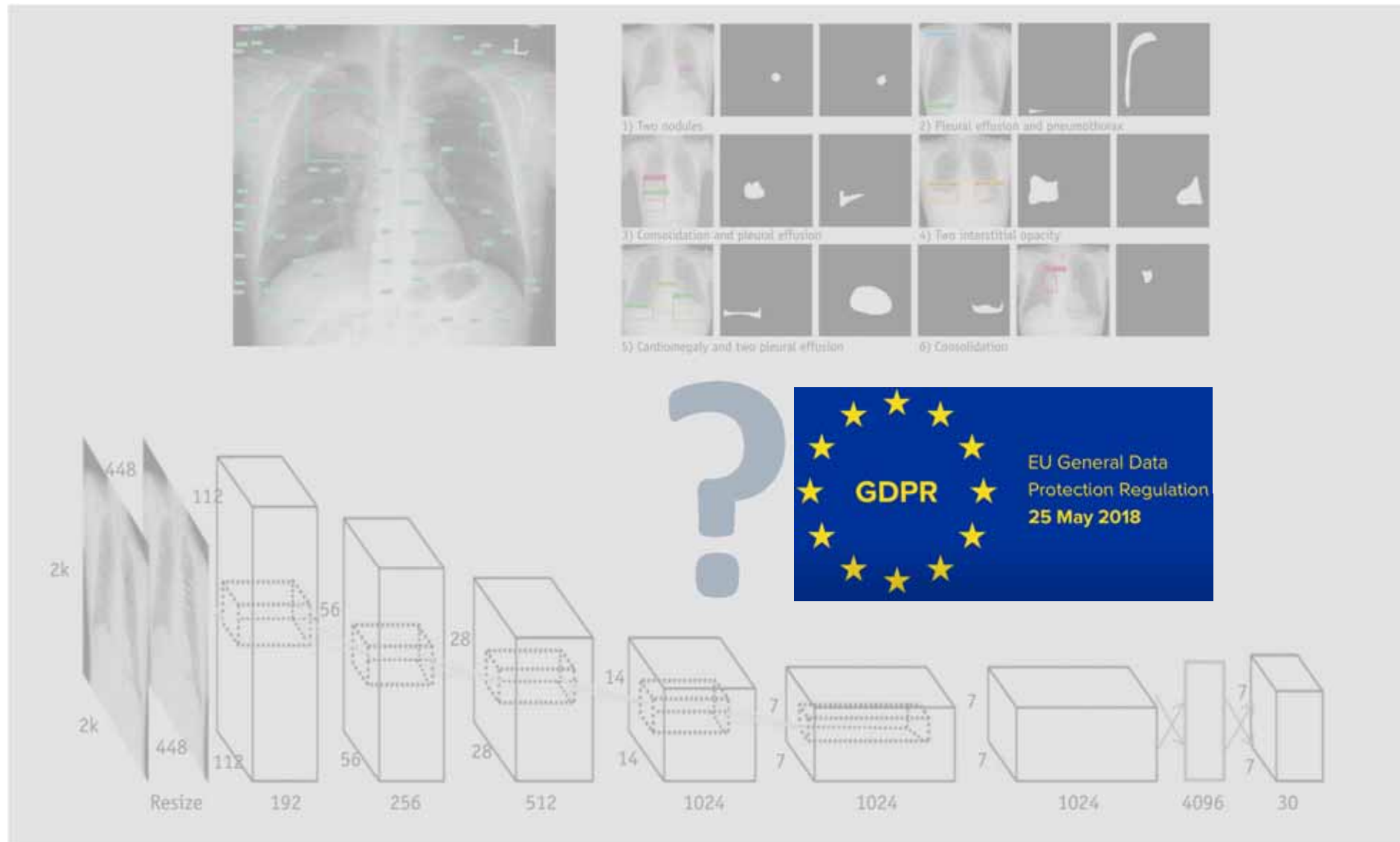
Krizhevsky, A., Sutskever, I. & Hinton, G. E. Imagenet classification with deep convolutional neural networks. In: Pereira, F., Burges, C. J. C., Bottou, L. & Weinberger, K. Q., eds. Advances in neural information processing systems (NIPS 2012), 2012 Lake Tahoe. 1097-1105.

- Sometimes we **do not have “big data”**, where aML-algorithms benefit.
- Sometimes we have
  - **Small amount of data sets**
  - **Rare Events – no training samples**
  - **NP-hard problems, e.g.**
    - Subspace Clustering,
    - k-Anonymization,
    - Protein-Folding, ...



- High dimensionality (curse of dim., many factors contribute)
- Complexity of medical problems (medical world is non-linear, non-stationary, non-IID \*)
- Need of large top-quality data sets
- Sensitive to small disturbances (noise, bias, one-pixel attacks, ...)
- Little prior data (no mechanistic models of the data)
  - \*) = Def.: a sequence or collection of random variables is independent and identically distributed if each random variable has the same probability distribution as the others and all are mutually independent
- However, most of all ...





June-Goo Lee, Sanghoon Jun, Young-Won Cho, Hyunna Lee, Guk Bae Kim, Joon Beom Seo & Namkug Kim 2017. Deep learning in medical imaging: general overview. Korean journal of radiology, 18, (4), 570-584, doi:10.3348/kjr.2017.18.4.570.

# 05 iML

- iML := algorithms which interact with agents\*) and can optimize their learning behaviour through this interaction

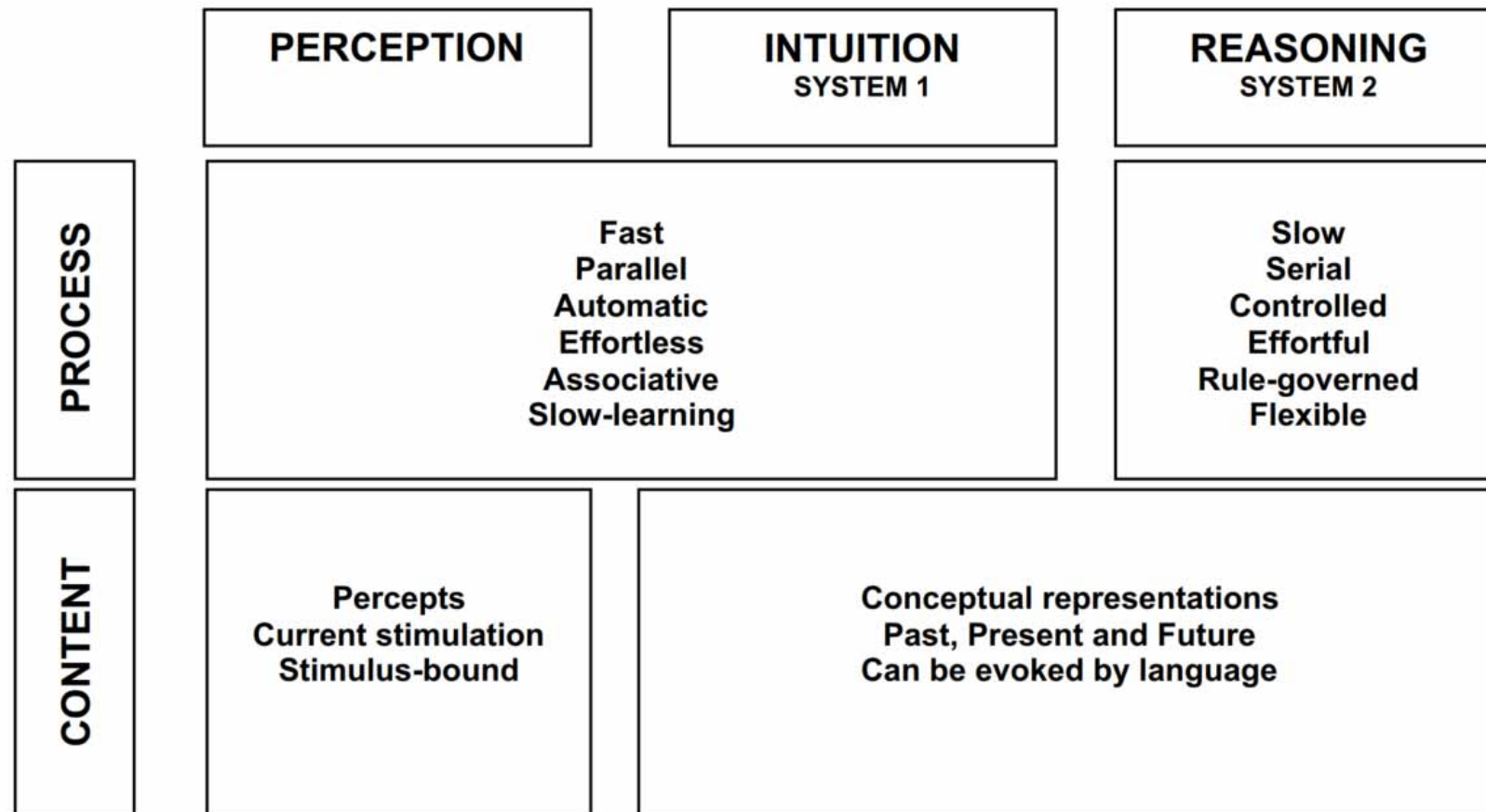
**\*) where the agents can be human**

Holzinger, A. 2016. Interactive Machine Learning (iML). Informatik Spektrum, 39, (1), 64-68, doi:10.1007/s00287-015-0941-6.



Image Source: 10 Ways Technology is Changing Healthcare <http://newhealthypost.com> Posted online on April 22, 2018  
Image is used according UrhG §42 lit. f Abs 1 as "Belegfunktion" for discussion with students





This was presented on December, 8, 2002 as Nobel Prize Lecture by Daniel Kahneman from Princeton University, and has later been published as:

Daniel Kahneman 2003. Maps of bounded rationality: Psychology for behavioural economics. American economic review, 93, (5), 1449-1475, doi:10.1257/000282803322655392.

- **Deductive Reasoning** = Hypothesis > Observations > Logical Conclusions
  - DANGER: Hypothesis must be correct! DR defines whether the truth of a conclusion can be determined for that rule, based on the truth of premises:  $A=B$ ,  $B=C$ , conclusion:  $A=C$
- **Inductive reasoning** = makes broad generalizations from specific observations
  - DANGER: allows a conclusion to be false if the premises are true
  - generate hypotheses and use DR for answering specific questions
- **Abductive reasoning** = inference = to get the best explanation from an incomplete set of preconditions.
  - Given a true conclusion and a rule, it attempts to select some possible premises that, if true also, may support the conclusion ...
  - Example: "When it rains, the grass gets wet. The grass is wet. Therefore, it might have rained." This kind of reasoning can be used to develop a hypothesis, which in turn can be tested by additional reasoning or data.

Randy Goebel, Ajay Chander, Katharina Holzinger, Freddy Lecue, Zeynep Akata, Simone Stumpf, Peter Kieseberg & Andreas Holzinger 2018.

Explainable AI: the new 42? Springer Lecture Notes in Computer Science LNCS 11015. pp. 295-303, doi:10.1007/978-3-319-99740-7\_21.

- := information provided by direct observation (empirical evidence) in contrast to information provided by inference
  - Empirical evidence = information acquired by observation or by experimentation in order to verify the truth (fit to reality) or falsify (non-fit to reality).
  - Empirical inference = drawing conclusions from empirical data (observations, measurements)
  - Causal inference = drawing a conclusion about a causal connection based on the conditions of the occurrence of an effect.
    - Causal inference is an example of causal reasoning.

- **Humans can generalize even from few examples ...**
  - They can learn relevant representations
  - Can disentangle the explanatory factors
  - Find the shared underlying explanatory factors, in particular between  $P(x)$  and  $P(Y|X)$ , with a causal link between  $Y \rightarrow X$

Yoshua Bengio, Aaron Courville & Pascal Vincent 2013. Representation learning: A review and new perspectives. *IEEE transactions on pattern analysis and machine intelligence*, 35, (8), 1798-1828, doi:10.1109/TPAMI.2013.50.



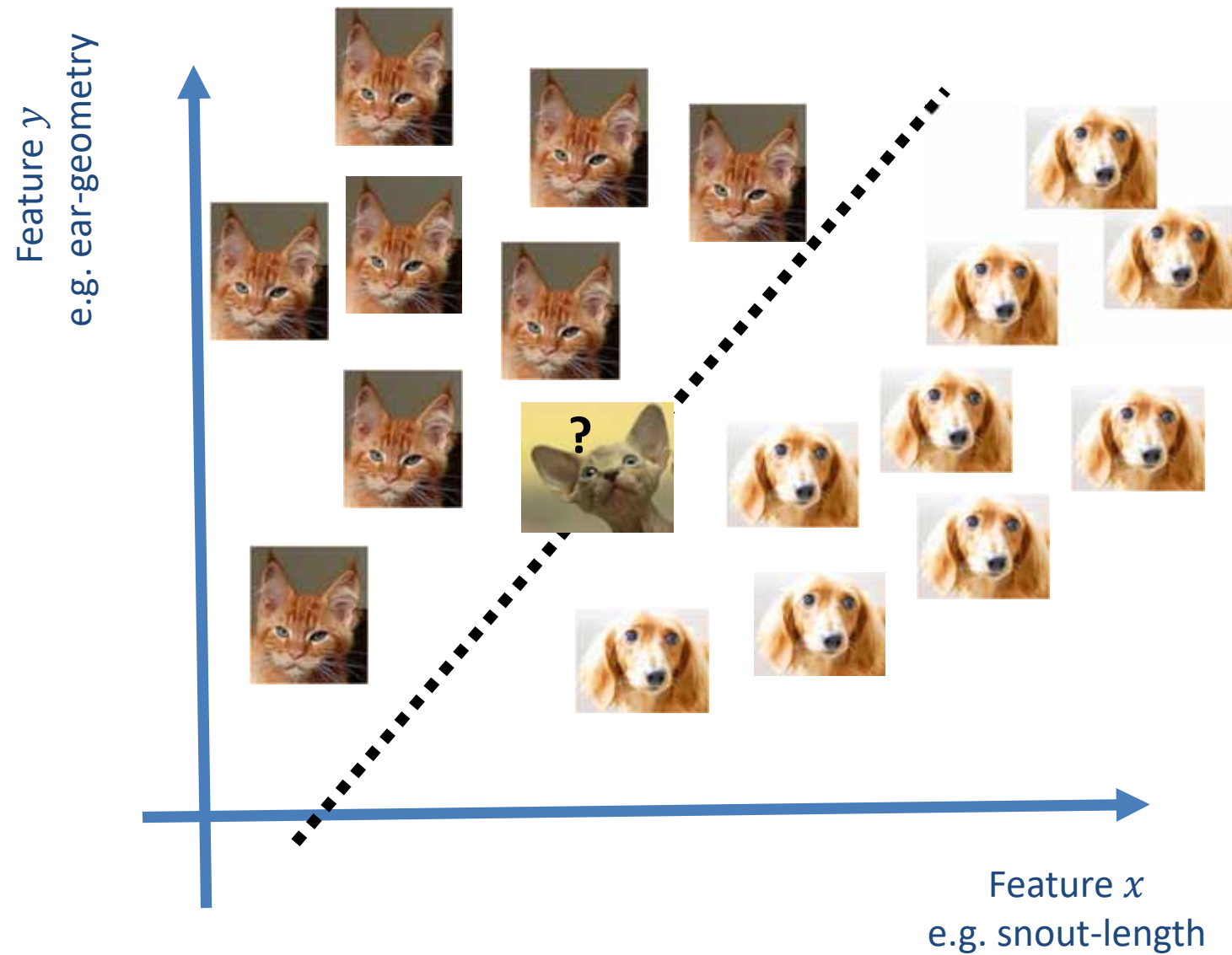
# Even Children can make inferences from little, noisy, incomplete data ...

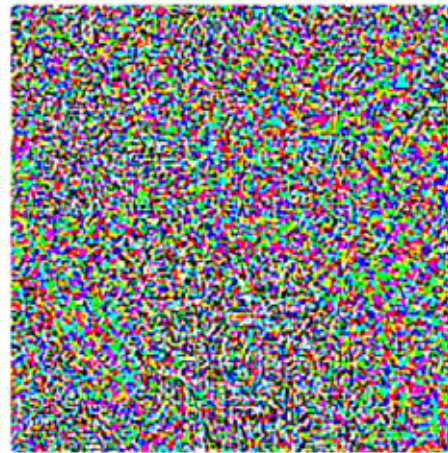


This image is in the public domain, Source: freedesignfile.com

Image is used according UrhG §42 lit. f Abs 1 as "Belegfunktion" for discussion with students

Brenden M. Lake, Ruslan Salakhutdinov & Joshua B. Tenenbaum 2015. Human-level concept learning through probabilistic program induction. Science, 350, (6266), 1332-1338, doi:[10.1126/science.aab3050](https://doi.org/10.1126/science.aab3050)




 $+ .007 \times$ 

 $=$ 

 $x$ 

“panda”

57.7% confidence

 $\text{sign}(\nabla_x J(\theta, x, y))$ 

“nematode”

8.2% confidence

 $x + \epsilon \text{sign}(\nabla_x J(\theta, x, y))$ 

“gibbon”

99.3 % confidence

Ian Goodfellow, Patrick McDaniel & Nicolas Papernot 2018. Making machine learning robust against adversarial inputs. *Communications of the ACM*, 61, (7), 55-66, doi:10.1145/3134599.

Gamaleldin F. Elsayed, Shreya Shankar, Brian Cheung, Nicolas Papernot, Alex Kurakin, Ian Goodfellow & Jascha Sohl-Dickstein 2018. Adversarial Examples that Fool both Human and Computer Vision. *arXiv:1802.08195*.

Ian Goodfellow, Jonathon Shlens & Christian Szegedy 2014. Explaining and harnessing adversarial examples. *arXiv:1412.6572*.

# Adversarial Examples that Fool both Computer Vision and Time-Limited Humans

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**Shreya Shankar**

Stanford University

**Brian Cheung**

UC Berkeley

**Nicolas Papernot**

Pennsylvania State University

**Alex Kurakin**

Google Brain

**Ian Goodfellow**

Google Brain

**Jascha Sohl-Dickstein**

Google Brain

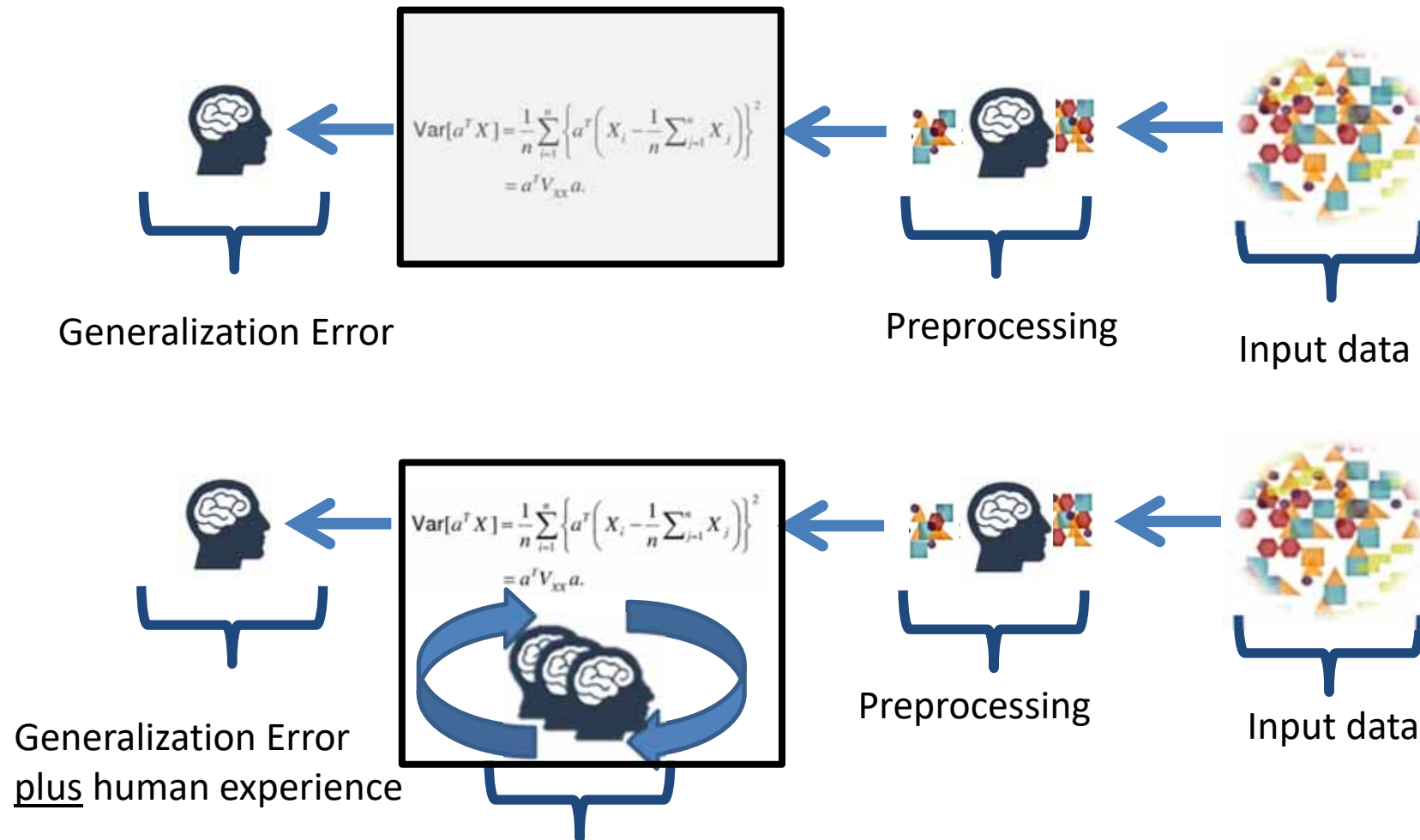
jaschasd@google.com

## Abstract

Machine learning models are vulnerable to **adversarial examples**: small changes to images can cause computer vision models to make mistakes such as identifying a school bus as an ostrich. However, it is still an open question whether humans are prone to similar mistakes. Here, we address this question by leveraging recent techniques that transfer adversarial examples from computer vision models with known parameters and architecture to other models with unknown parameters and architecture, and by matching the initial processing of the human visual system. We find that adversarial examples that strongly transfer across computer vision models influence the classifications made by time-limited human observers.

Gamaleldin F Elsayed, Shreya Shankar, Brian Cheung, Nicolas Papernot, Alex Kurakin, Ian Goodfellow & Jascha Sohl-Dickstein 2018. Adversarial Examples that Fool both Human and Computer Vision. arXiv:1802.08195.

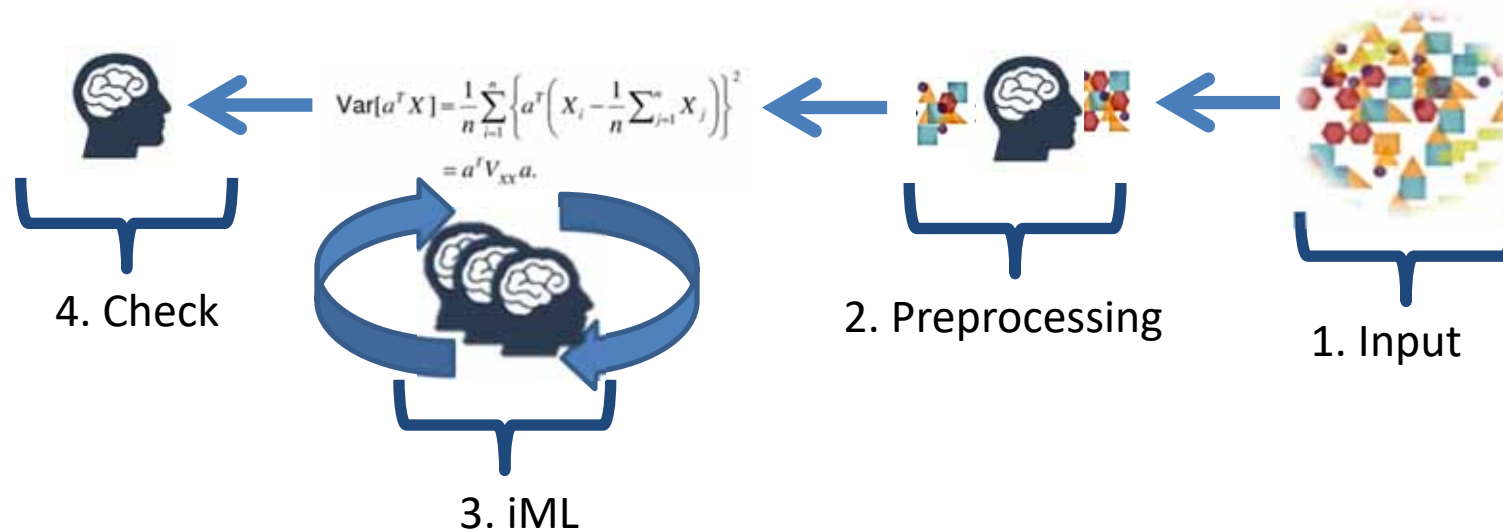




**iML = human inspection – bring in human “intuition” – abstract concept learning and context understanding !**

Andreas Holzinger 2016. Interactive Machine Learning for Health Informatics: When do we need the human-in-the-loop? *Brain Informatics*, 3, (2), 119-131, doi:10.1007/s40708-016-0042-6.

**Interactive Machine Learning:** Human is seen as an agent involved in the actual learning phase, step-by-step influencing measures such as distance, cost functions ...



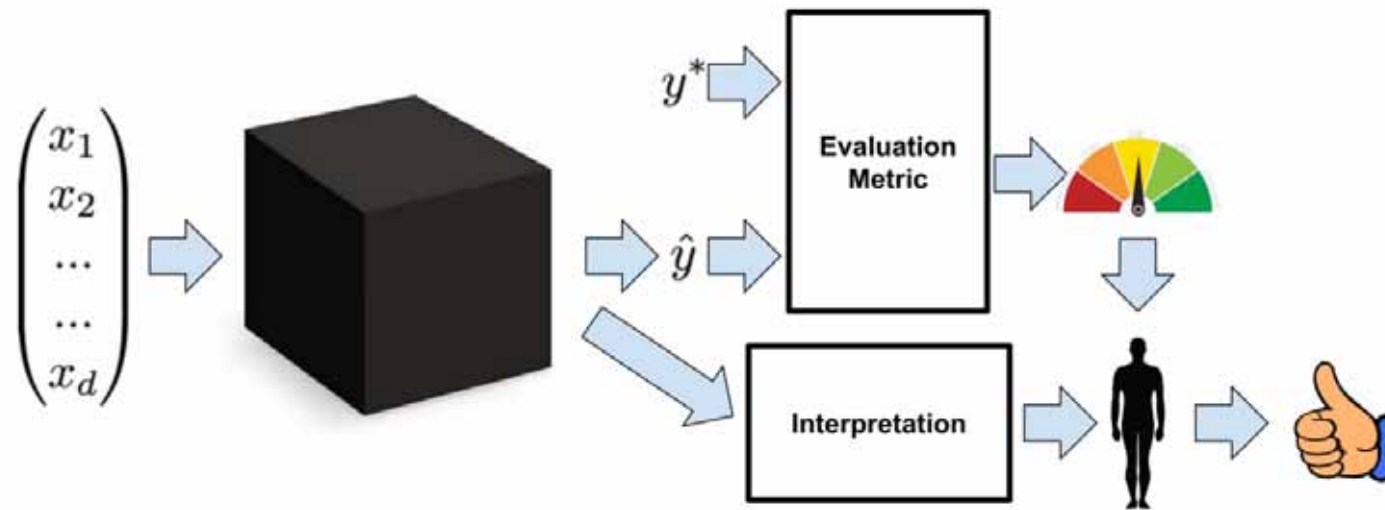
Andreas Holzinger 2016. Interactive Machine Learning for Health Informatics: When do we need the human-in-the-loop? *Brain Informatics*, 3, (2), 119-131, doi:10.1007/s40708-016-0042-6.

# 06

## “explainable AI”

Term coined by Dave Gunning, DARPA, see:

David Gunning 2016. Explainable artificial intelligence (XAI): Technical Report Defense Advanced Research Projects Agency DARPA-BAA-16-53, Arlington, USA, DARPA.



Zachary C. Lipton 2016. The mythos of model interpretability. arXiv:1606.03490.

- Inconsistent Definitions: What is the difference between explainable, interpretable, verifiable, intelligible, transparent, understandable ... ?

Zachary C. Lipton 2018. The mythos of model interpretability. ACM Queue, 16, (3), 31-57, doi:10.1145/3236386.3241340



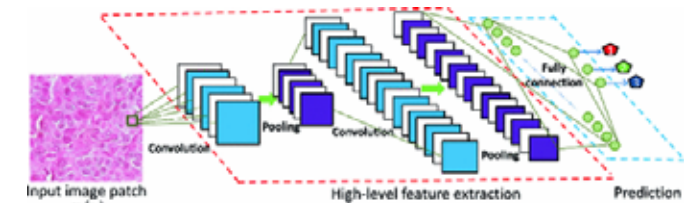
- **Trust** – interpretability as prerequisite for trust (as propagated by Ribeiro et al (2016)); how is trust defined? Confidence?
- **Causality** - inferring causal relationships from pure observational data has been extensively studied (Pearl, 2009), however it relies strongly on prior knowledge
- **Transferability** – humans have a much higher capacity to generalize, and can transfer learned skills to completely new situations; compare this with e.g. susceptibility of CNNs to adversarial data (please remember that we rarely have iid data in real world)
- **Informativeness** - for example, a diagnosis model might provide intuition to a human decision-maker by pointing to similar cases in support of a diagnostic decision
- **Fairness and Ethical decision making** – interpretations for the purpose of assessing whether decisions produced by algorithms conform to ethical standards, avoiding bias and misconceptions ..

Zachary C. Lipton 2016. The mythos of model interpretability. arXiv:1606.03490.

**End-users shall be able to retrace  
the results on demand  
and we engineers need to  
understand our own  
machine learning models!**

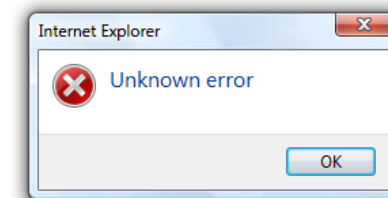
## Verify that algorithms/classifiers work as expected ...

Wrong decisions can be costly and dangerous ...



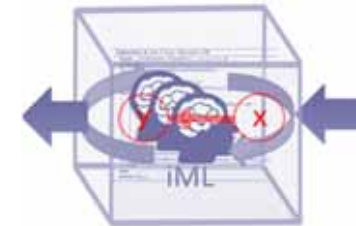
## Understanding the errors ...

Detection of bias, weaknesses, unknowns, ...



## Scientific replicability and causality ...

The “why” is often more important than the prediction ...



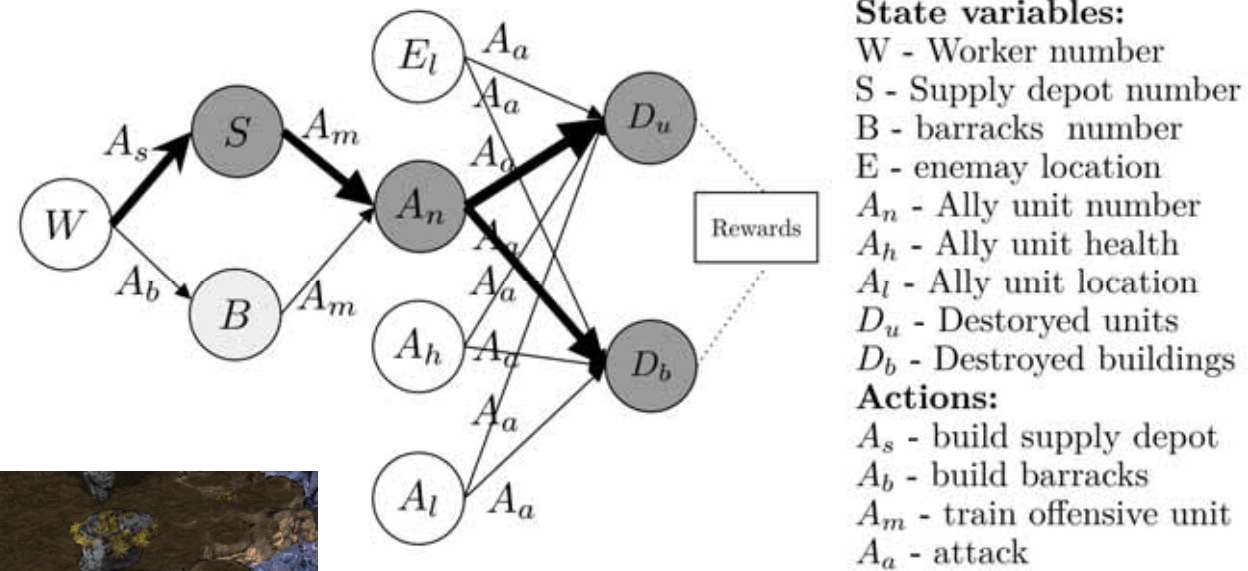
Andreas Holzinger 2018. From Machine Learning to Explainable AI. 2018 World Symposium on Digital Intelligence for Systems and Machines (IEEE DISA). pp. 55-66, doi:10.1109/DISA.2018.8490530.

- **Post-Hoc** (latin) = after- this (event), i.e. such approaches provide an explanation for a specific solution of a “black-box” approach, e.g. LIME, BETA, LRP, ...
- **Ante-hoc** (latin) = before-this (event), i.e. such methods can be (human) interpreted immanently in the system, i.e. they are transparent by nature (glass box), similar to the "interactive machine Learning" (iML) model.
- Note: Many ante-hoc approaches appear to the new student particularly novel, but these have a long tradition and were used since the early beginning of AI and applied in expert systems, e.g. decision trees, linear regression, random forests, ...

Andreas Holzinger, Chris Biemann, Constantinos S. Pattichis & Douglas B. Kell 2017. What do we need to build explainable AI systems for the medical domain? *arXiv:1712.09923*.



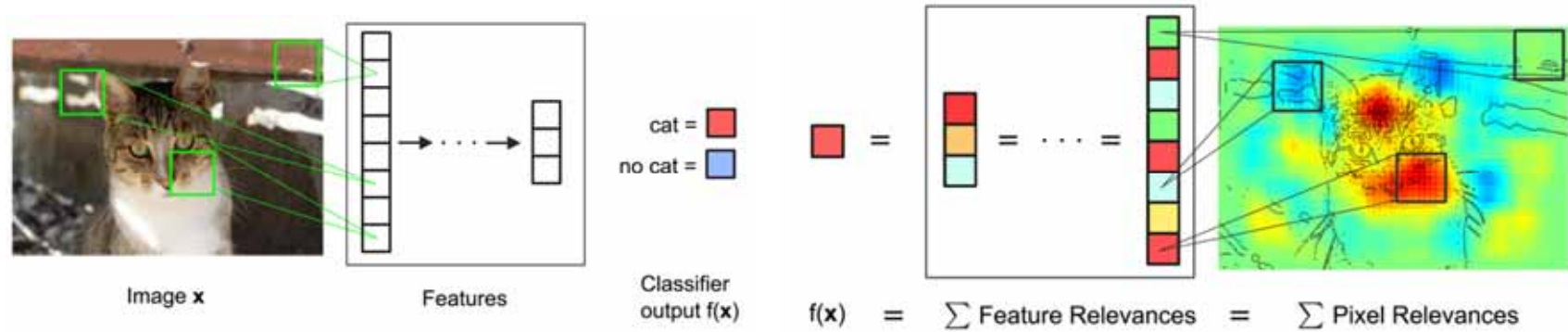
- **Interpretable Models**, the model itself is already interpretable, e.g.
  - Regression
  - Naïve Bayes
  - Random Forests
  - Decision Trees/Graphs
  - ...
- **Interpreting Black-Box Models** (the model is not interpretable and needs a post-hoc interpretability method – like a combustion engine ;- ) e.g.:
  - Decomposition
  - LIME/BETA
  - LRP
  - ...



[https://eecs.wsu.edu/~ala/cdtldms/reports/maf\\_report.htm](https://eecs.wsu.edu/~ala/cdtldms/reports/maf_report.htm)

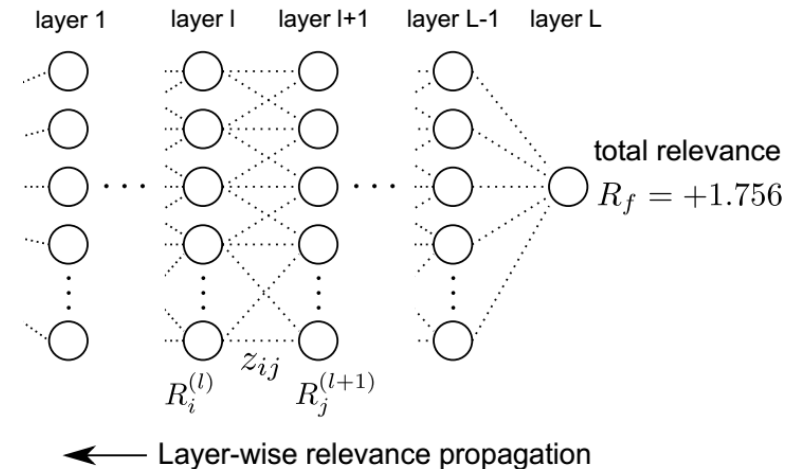
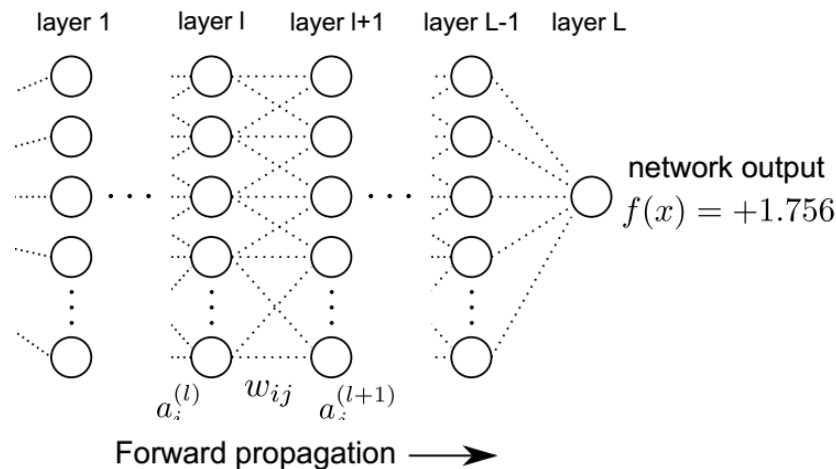
Prashan Madumal, Tim Miller, Liz Sonenberg & Frank Vetere 2019. Explainable Reinforcement Learning Through a Causal Lens. arXiv preprint arXiv:1905.10958.

Sebastian Bach, Alexander Binder, Grégoire Montavon, Frederick Klauschen, Klaus-Robert Müller & Wojciech Samek 2015. On pixel-wise explanations for non-linear classifier decisions by layer-wise relevance propagation. PloS one, 10, (7), e0130140, doi:10.1371/journal.pone.0130140.



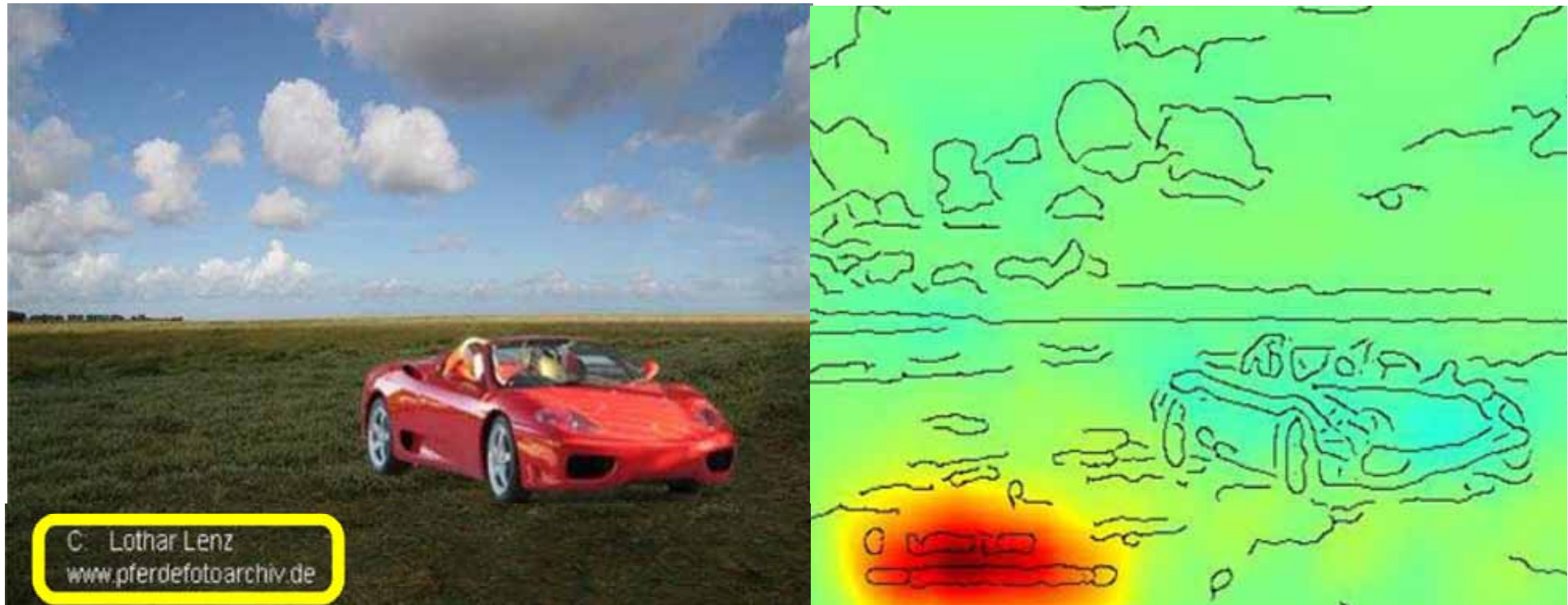
$$a_j^{(l+1)} = \sigma \left( \sum_i a_i^{(l)} w_{ij} + b_j^{(l+1)} \right)$$

$$R_i^{(l)} = \sum_j \frac{z_{ij}}{\sum_{i'} z_{i'j}} R_j^{(l+1)}$$



$$R_i = \left\| \frac{\partial}{\partial x_i} f(\mathbf{x}) \right\| \quad \sum_i R_i = \dots = \sum_j R_j = \sum_k R_k = \dots = f(\mathbf{x})$$

## 98 % A horse on a meadow

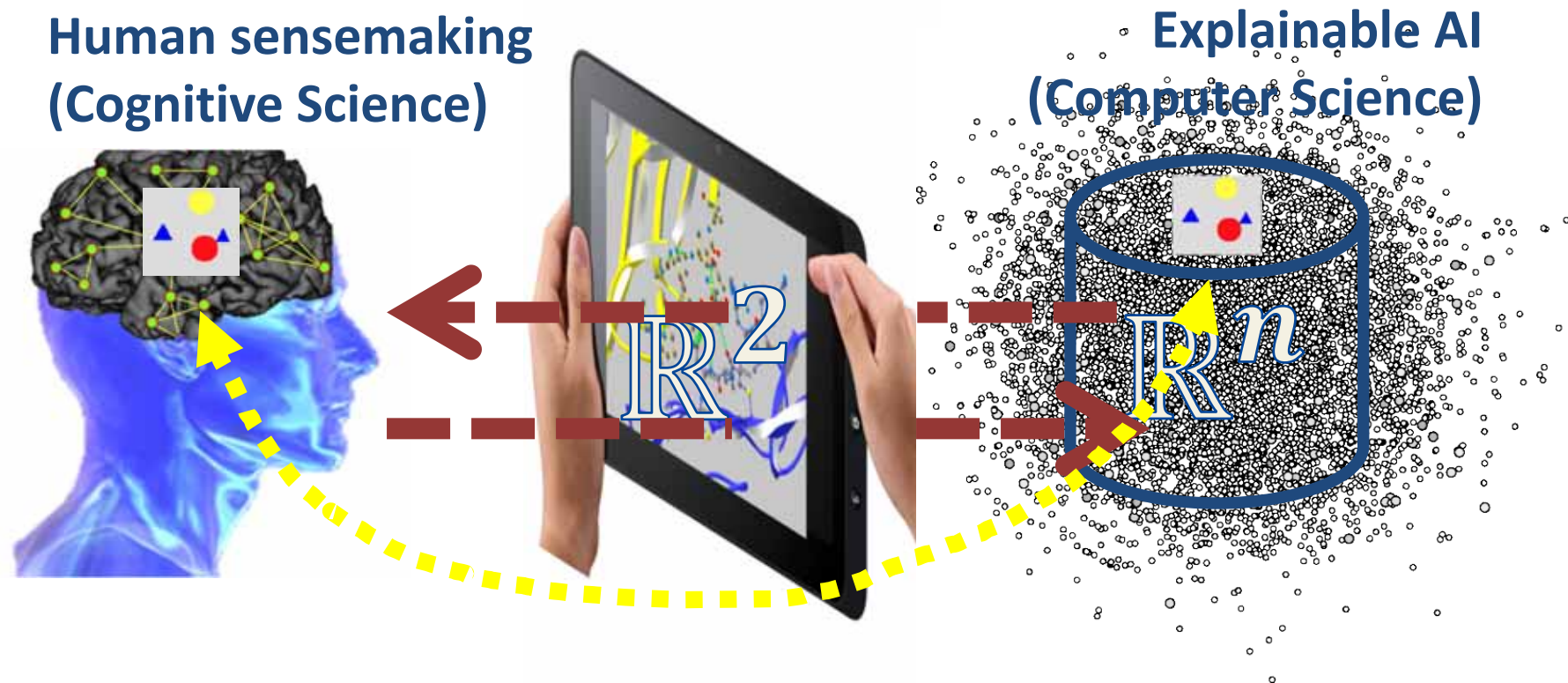


Sebastian Lapuschkin, Stephan Wäldchen, Alexander Binder, Grégoire Montavon, Wojciech Samek & Klaus-Robert Müller 2019. Unmasking Clever Hans predictors and assessing what machines really learn. Nature Communications, 10, (1), doi:10.1038/s41467-019-08987-4.

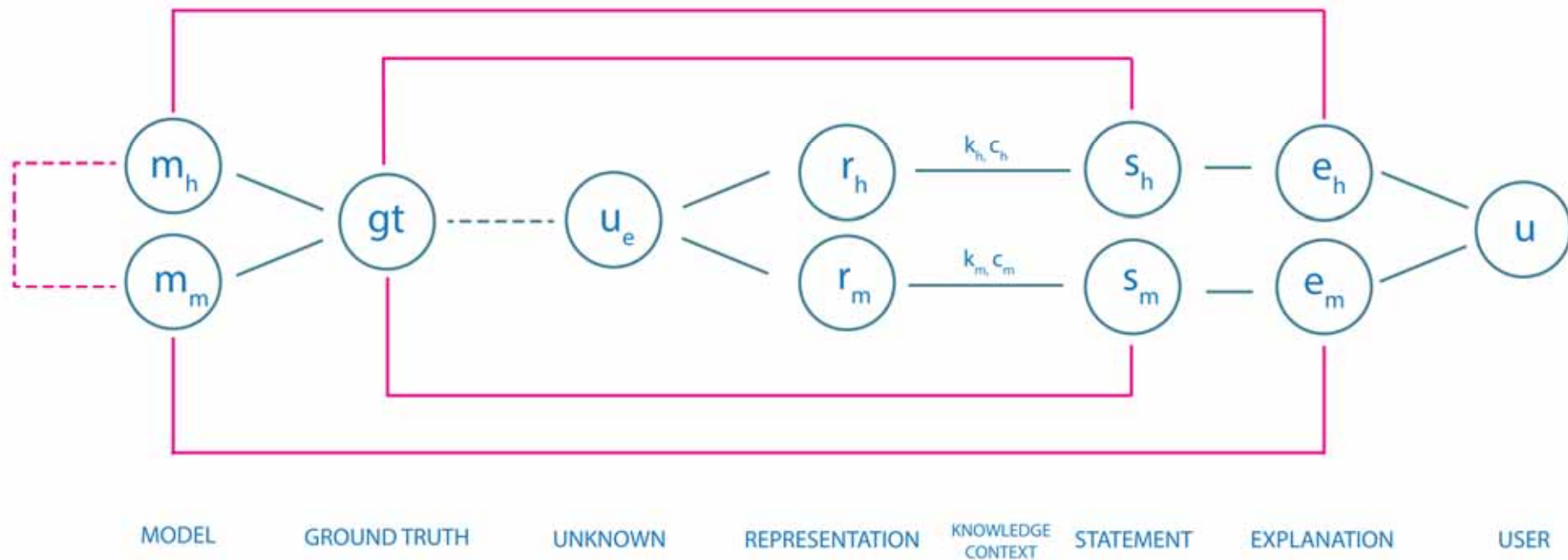


# **A final note on Measuring Causability: Mapping machine explanations with human understanding**

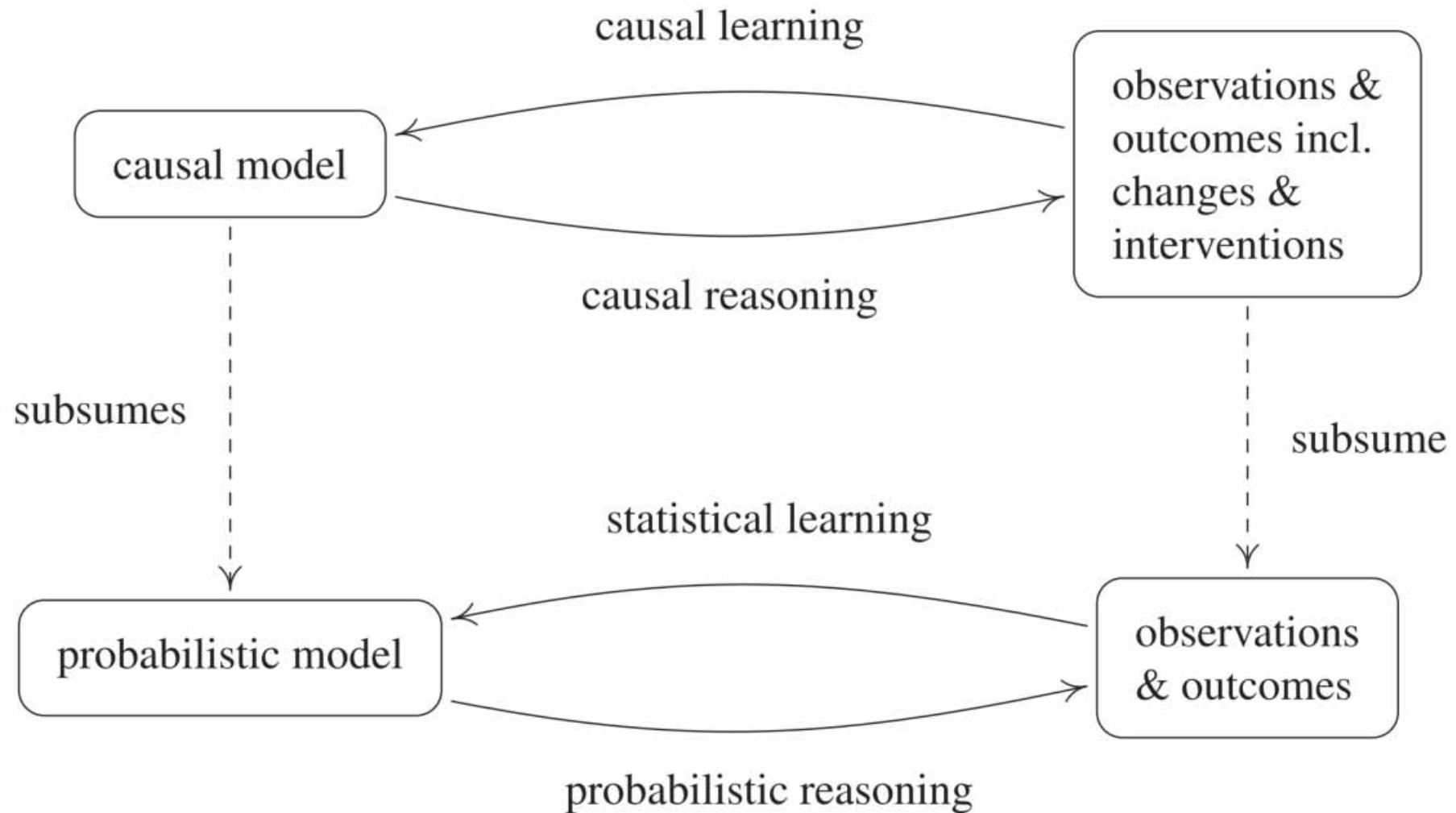
- Causability := a property of a person (Human)
- Explainability := a property of a system (Computer)



Andreas Holzinger et al. 2019. Causability and Explainability of AI in Medicine. Wiley Interdisciplinary Reviews: Data Mining and Knowledge Discovery, doi:10.1002/widm.1312.



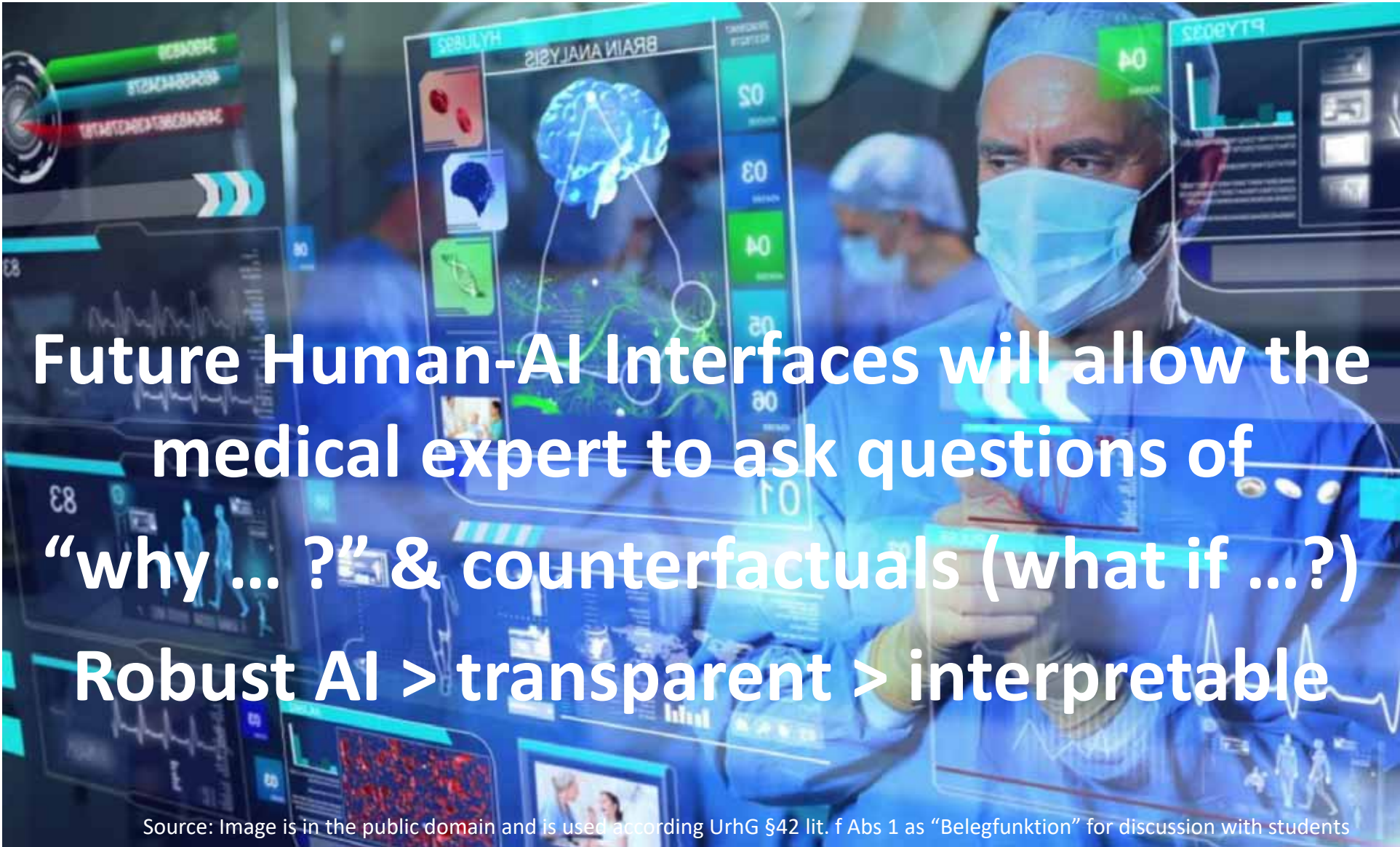
Andreas Holzinger, Andre Carrington & Heimo Müller 2020. Measuring the Quality of Explanations: The System Causability Scale (SCS). Comparing Human and Machine Explanations. KI - Künstliche Intelligenz (German Journal of Artificial intelligence), Special Issue on Interactive Machine Learning, Edited by Kristian Kersting, TU Darmstadt, 34, (2), doi:10.1007/s13218-020-00636-z., <https://link.springer.com/article/10.1007/s13218-020-00636-z>



Jonas Peters, Dominik Janzing & Bernhard Schölkopf 2017. *Elements of causal inference: foundations and learning algorithms*, Cambridge (MA).



# Conclusion and Future Outlook



**Future Human-AI Interfaces will allow the  
medical expert to ask questions of  
“why ... ?” & counterfactuals (what if ...?)  
Robust AI > transparent > interpretable**

Source: Image is in the public domain and is used according UrhG §42 lit. f Abs 1 as “Belegfunktion” for discussion with students

- Current AI does not generalize well,
- can not learn from few examples,
- do not infer causal relationships.

**We need robust AI** to

- reduce costs and limitations

**Fostering acceptance and trust, enabling ethical, legal and socially responsible medical AI**

**Replicability, Retraceability, Explainability & Causability**

- Computers are fast, accurate and stupid,
  - humans are slow, inaccurate and brilliant,
  - **together** they are powerful beyond imagination (attributed to Albert Einstein)
- (Einstein never said that)

<https://www.benshoemate.com/2008/11/30/einstein-never-said-that>

„Das Dumme an Zitaten  
aus dem Internet ist,  
dass man nie weiß,  
ob sie echt sind“

Albert Einstein

